MAKING MODERN LIVING POSSIBLE

Design Guide

VLT® Automation VT Drive FC 322

VLT®
THE REAL DRIVE

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- VLT® Automation VT Drive FC322 High Power Instruction Manual MG.20.Vx.yy provide the neccessary information for getting the HP drive up and running.
- VLT® Automation VT Drive FC322 Design Guide MG.20.Xx.yy entails all technical information about the drive and customer design and applications.
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- Instruction MI.90.Lx.yy: Analog I/O Option MCB109
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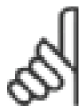
x = Revision number
yy = Language code

Danfoss technical literature is also available online at
www.danfoss.com/BusinessAreas/DrivesSolutions/Documentations/Technical+Documentation.htm.

1.1.3 Symbols

Symbols used in this guide.

	**NB!** Indicates something to be noted by the reader.

	Indicates a general warning.

	Indicates a high-voltage warning.

*	Indicates default setting

1.1.4 Abbreviations

Alternating current	AC
American wire gauge	AWG
Ampere/AMP	A
Automatic Motor Adaptation	AMA
Current limit	I_{LIM}
Degrees Celsius	°C
Direct current	DC
Drive Dependent	D-TYPE
Electro Magnetic Compatibility	EMC
Electronic Thermal Relay	ETR
Drive	FC
Gram	g
Hertz	Hz
Kilohertz	kHz
Local Control Panel	LCP
Meter	m
Millihenry Inductance	mH
Milliampere	mA
Millisecond	ms
Minute	min
Motion Control Tool	MCT
Nanofarad	nF
Newton Meters	Nm
Nominal motor current	$I_{M,N}$
Nominal motor frequency	$f_{M,N}$
Nominal motor power	$P_{M,N}$
Nominal motor voltage	$U_{M,N}$
Parameter	par.
Protective Extra Low Voltage	PELV
Printed Circuit Board	PCB
Rated Inverter Output Current	I_{INV}
Revolutions Per Minute	RPM
Regenerative terminals	Regen
Second	s
Synchronous Motor Speed	n_s
Torque limit	T_{LIM}
Volts	V
$I_{VLT,MAX}$	The maximum output current
$I_{VLT,N}$	The rated output current supplied by the frequency converter

1.1.5 Definitions

Drive:

$I_{VLT,MAX}$

The maximum output current.

$I_{VLT,N}$

The rated output current supplied by the frequency converter.

$U_{VLT, MAX}$

The maximum output voltage.

Input:

Control command You can start and stop the connected motor by means of LCP and the digital inputs. Functions are divided into two groups. Functions in group 1 have higher priority than functions in group 2.	Group 1	Reset, Coasting stop, Reset and Coasting stop, Quick-stop, DC braking, Stop and the "Off" key.
	Group 2	Start, Pulse start, Reversing, Start reversing, Jog and Freeze output

Motor:

f_{JOG}
The motor frequency when the jog function is activated (via digital terminals).

f_M
The motor frequency.

f_{MAX}
The maximum motor frequency.

f_{MIN}
The minimum motor frequency.

$f_{M,N}$
The rated motor frequency (nameplate data).

I_M
The motor current.

$I_{M,N}$
The rated motor current (nameplate data).

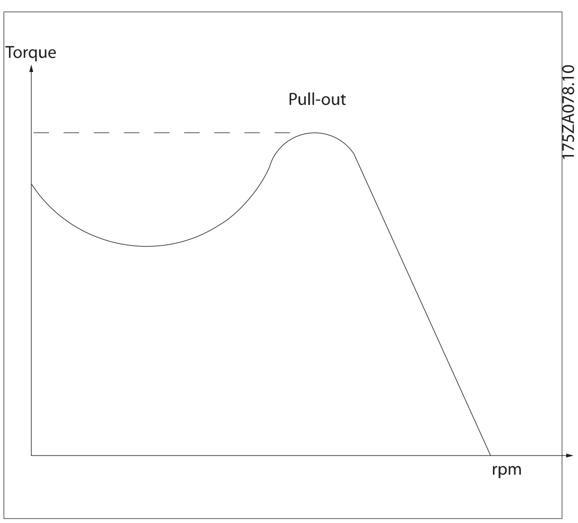
$n_{M,N}$
The rated motor speed (nameplate data).

$P_{M,N}$
The rated motor power (nameplate data).

$T_{M,N}$
The rated torque (motor).

U_M
The instantaneous motor voltage.

$U_{M,N}$
The rated motor voltage (nameplate data).



η_{VLT}
The efficiency of the frequency converter is defined as the ratio between the power output and the power input.

Start-disable command
A stop command belonging to the group 1 control commands - see this group.

Stop command
See Control commands.

References:

Analog Reference
A signal transmitted to the analog inputs 53 or 54, can be voltage or current.

Bus Reference
A signal transmitted to the serial communication port (FC port).

Preset Reference
A defined preset reference to be set from -100% to +100% of the reference range. Selection of eight preset references via the digital terminals.

Pulse Reference
A pulse frequency signal transmitted to the digital inputs (terminal 29 or 33).

Ref_{MAX}
Determines the relationship between the reference input at 100% full scale value (typically 10 V, 20mA) and the resulting reference. The maximum reference value set in par. 3-03.

Ref_{MIN}
Determines the relationship between the reference input at 0% value (typically 0V, 0mA, 4mA) and the resulting reference. The minimum reference value set in par. 3-02.

Miscellaneous:

Analog Inputs
The analog inputs are used for controlling various functions of the frequency converter.
There are two types of analog inputs:
Current input, 0-20 mA and 4-20 mA
Voltage input, 0-10 V DC.

Analog Outputs
The analog outputs can supply a signal of 0-20 mA, 4-20 mA, or a digital signal.

Automatic Motor Adaptation, AMA
AMA algorithm determines the electrical parameters for the connected motor at standstill.

Brake Resistor
The brake resistor is a module capable of absorbing the brake power generated in regenerative braking. This regenerative braking power increases the intermediate circuit voltage and a brake chopper ensures that the power is transmitted to the brake resistor.

CT Characteristics
Constant torque characteristics used for positive displacement pumps and blowers.

Digital Inputs

The digital inputs can be used for controlling various functions of the frequency converter.

Digital Outputs

The drive features two Solid State outputs that can supply a 24 V DC (max. 40 mA) signal.

DSP

Digital Signal Processor.

Relay Outputs:

The frequency converter drive features two programmable Relay Outputs.

ETR

Electronic Thermal Relay is a thermal load calculation based on present load and time. Its purpose is to estimate the motor temperature.

GLCP:

Graphical Local Control Panel (LCP102)

Initialising

If initialising is carried out (par. 14-22), the programmable parameters of the frequency converter return to their default settings.

Intermittent Duty Cycle

An intermittent duty rating refers to a sequence of duty cycles. Each cycle consists of an on-load and an off-load period. The operation can be either periodic duty or none-periodic duty.

LCP

The Local Control Panel (LCP) makes up a complete interface for control and programming of the frequency converter. The control panel is detachable and can be installed up to 3 metres from the frequency converter, i.e. in a front panel by means of the installation kit option.

The Local Control Panel is available in two versions:

- Numerical LCP101 (NLCP)
- Graphical LCP102 (GLCP)

lsb

Least significant bit.

MCM

Short for Mille Circular Mil, an American measuring unit for cable cross-section. 1 MCM ≡ 0.5067 mm^2.

msb

Most significant bit.

NLCP

Numerical Local Control Panel LCP101

On-line/Off-line Parameters

Changes to on-line parameters are activated immediately after the data value is changed. Changes to off-line parameters are not activated until you enter [OK] on the LCP.

PID Controller

The PID controller maintains the desired speed, pressure, temperature, etc. by adjusting the output frequency to match the varying load.

RCD

Residual Current Device.

1

Set-up

You can save parameter settings in four Set-ups. Change between the four parameter Set-ups and edit one Set-up, while another Set-up is active.

SFAVM
Switching pattern called S tator F lux oriented A synchronous V ector M odulation (par. 14-00).

Slip Compensation
The frequency converter compensates for the motor slip by giving the frequency a supplement that follows the measured motor load keeping the motor speed almost constant..

Smart Logic Control (SLC)
The SLC is a sequence of user defined actions executed when the associated user defined events are evaluated as true by the SLC.

Thermistor:
A temperature-dependent resistor placed where the temperature is to be monitored (frequency converter or motor).

Trip
A state entered in fault situations, e.g. if the frequency converter is subject to an over-temperature or when the frequency converter is protecting the motor, process or mechanism. Restart is prevented until the cause of the fault has disappeared and the trip state is cancelled by activating reset or, in some cases, by being programmed to reset automatically. Trip may not be used for personal safety.

Trip Locked
A state entered in fault situations when the frequency converter is protecting itself and requiring physical intervention, e.g. if the frequency converter is subject to a short circuit on the output. A locked trip can only be cancelled by cutting off mains, removing the cause of the fault, and reconnecting the frequency converter. Restart is prevented until the trip state is cancelled by activating reset or, in some cases, by being programmed to reset automatically. Trip locked may not be used for personal safety.

VT Characteristics
Variable torque characteristics used for pumps and fans.

VVC^{plus}
If compared with standard voltage/frequency ratio control, Voltage Vector Control (VVC^{plus}) improves the dynamics and the stability, both when the speed reference is changed and in relation to the load torque.

60° AVM
Switching pattern called 60°A synchronous V ector M odulation (par. 14-00).

1.1.6 Power Factor

The power factor is the relation between I_1 and I_{RMS}.

$$Power\ factor = \frac{\sqrt{3} \times U \times I_1 \times COS\varphi}{\sqrt{3} \times U \times I_{RMS}}$$

The power factor for 3-phase control:

$$= \frac{I_1 \times cos\varphi 1}{I_{RMS}} = \frac{I_1}{I_{RMS}}\ since\ cos\varphi 1 = 1$$

The power factor indicates to which extent the frequency converter imposes a load on the mains supply.
The lower the power factor, the higher the I_{RMS} for the same kW performance.

$$I_{RMS} = \sqrt{I_1^2 + I_5^2 + I_7^2 + .. + I_n^2}$$

In addition, a high power factor indicates that the different harmonic currents are low.
The frequency converters' built-in DC coils produce a high power factor, which minimizes the imposed load on the mains supply.

2 Introduction to VLT Automation VT Drive

2.1 Safety

2.1.1 Safety Note

The voltage of the frequency converter is dangerous whenever connected to mains. Incorrect installation of the motor, frequency converter or fieldbus may cause damage to the equipment, serious personal injury or death. Consequently, the instructions in this manual, as well as national and local rules and safety regulations, must be complied with.

Safety Regulations

1. The frequency converter must be disconnected from mains if repair work is to be carried out. Check that the mains supply has been disconnected and that the necessary time has passed before removing motor and mains plugs.
2. The [STOP/RESET] key on the control panel of the frequency converter does not disconnect the equipment from mains and is thus not to be used as a safety switch.
3. Correct protective earthing of the equipment must be established, the user must be protected against supply voltage, and the motor must be protected against overload in accordance with applicable national and local regulations.
4. The earth leakage currents are higher than 3.5 mA.
5. Protection against motor overload is set by par. 1-90 *Motor Thermal Protection*. If this function is desired, set par. 1-90 to data value [ETR trip] (default value) or data value [ETR warning]. Note: The function is initialised at 1.16 x rated motor current and rated motor frequency. For the North American market: The ETR functions provide class 20 motor overload protection in accordance with NEC.
6. Do not remove the plugs for the motor and mains supply while the frequency converter is connected to mains. Check that the mains supply has been disconnected and that the necessary time has passed before removing motor and mains plugs.
7. Please note that the frequency converter has more voltage inputs than L1, L2 and L3, when load sharing (linking of DC intermediate circuit) and external 24 V DC have been installed. Check that all voltage inputs have been disconnected and that the necessary time has passed before commencing repair work.

Installation at High Altitudes

By altitudes above 2 km, please contact Danfoss regarding PELV.

Warning against Unintended Start

1. The motor can be brought to a stop by means of digital commands, bus commands, references or a local stop, while the frequency converter is connected to mains. If personal safety considerations make it necessary to ensure that no unintended start occurs, these stop functions are not sufficient. 2. While parameters are being changed, the motor may start. Consequently, the stop key [STOP/RESET] must always be activated; following which data can be modified. 3. A motor that has been stopped may start if faults occur in the electronics of the frequency converter, or if a temporary overload or a fault in the supply mains or the motor connection ceases.

Warning:
Touching the electrical parts may be fatal - even after the equipment has been disconnected from mains.

Also make sure that other voltage inputs have been disconnected, such as external 24 V DC, load sharing (linkage of DC intermediate circuit), as well as the motor connection for kinetic back up.

Refer to *VLT® Automation VT Drive FC322 Instruction Manual MG.20.UX.YY* for further safety guidelines.

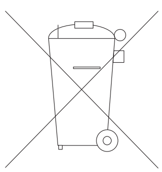
2.1.2 Caution

The frequency converter DC link capacitors remain charged after power has been disconnected. To avoid an electrical shock hazard, disconnect the frequency converter from the mains before carrying out maintenance. Wait at least as follows before doing service on the frequency converter:

Voltage (V)	Min. Waiting Time (Minutes)				
	4	15	20	30	40
200 - 240	0.25 - 3.7 kW	5.5 - 45 kW			
380 - 480	0.37 - 7.5 kW	11 - 90 kW	110 - 250 kW	315 - 1000 kW	
525-600	0.75 kW - 7.5 kW	11 - 90 kW			315 - 1200 kW
525-690		11 - 90 kW	45 - 400 kW	450 - 1200 kW	

Be aware that there may be high voltage on the DC link even when the LEDs are turned off.

2.1.3 Disposal Instruction



Equipment containing electrical components may not be disposed of together with domestic waste.
It must be separately collected with electrical and electronic waste according to local and currently valid legislation.

2.2 Software Version

2.2.1 Software Version and Approvals

VLT Automation VT Drive FC322
Software version: 1.7x

This manual can be used with all VLT Automation VT Drive FC322 frequency converters with software version 1.7x.
The software version number can be found in parameter 15-43.

2.3 CE labelling

2.3.1 CE Conformity and Labelling

What is CE Conformity and Labelling?

The purpose of CE labelling is to avoid technical trade obstacles within EFTA and the EU. The EU has introduced the CE label as a simple way of showing whether a product complies with the relevant EU directives. The CE label says nothing about the specifications or quality of the product. Frequency converters are regulated by three EU directives:

The machinery directive (98/37/EEC)

All machines with critical moving parts are covered by the machinery directive of January 1, 1995. Since a frequency converter is largely electrical, it does not fall under the machinery directive. However, if a frequency converter is supplied for use in a machine, we provide information on safety aspects relating to the frequency converter. We do this by means of a manufacturer's declaration.

The low-voltage directive (73/23/EEC)

Frequency converters must be CE labelled in accordance with the low-voltage directive of January 1, 1997. The directive applies to all electrical equipment and appliances used in the 50 - 1000 V AC and the 75 - 1500 V DC voltage ranges. Danfoss CE-labels in accordance with the directive and issues a declaration of conformity upon request.

The EMC directive (89/336/EEC)

EMC is short for electromagnetic compatibility. The presence of electromagnetic compatibility means that the mutual interference between different components/appliances does not affect the way the appliances work.

The EMC directive came into effect January 1, 1996. Danfoss CE-labels in accordance with the directive and issues a declaration of conformity upon request. To carry out EMC-correct installation, see the instructions in this Design Guide. In addition, we specify which standards our products comply with. We offer the filters presented in the specifications and provide other types of assistance to ensure the optimum EMC result.

The frequency converter is most often used by professionals of the trade as a complex component forming part of a larger appliance, system or installation. It must be noted that the responsibility for the final EMC properties of the appliance, system or installation rests with the installer.

2.3.2 What Is Covered

The EU "*Guidelines on the Application of Council Directive 89/336/EEC*" outline three typical situations of using a frequency converter. See below for EMC coverage and CE labelling.

1. The frequency converter is sold directly to the end-consumer. The frequency converter is for example sold to a DIY market. The end-consumer is a layman. He installs the frequency converter himself for use with a hobby machine, a kitchen appliance, etc. For such applications, the frequency converter must be CE labelled in accordance with the EMC directive.
2. The frequency converter is sold for installation in a plant. The plant is built up by professionals of the trade. It could be a production plant or a heating/ventilation plant designed and installed by professionals of the trade. Neither the frequency converter nor the finished plant has to be CE labelled under the EMC directive. However, the unit must comply with the basic EMC requirements of the directive. This is ensured by using components, appliances, and systems that are CE labelled under the EMC directive.
3. The frequency converter is sold as part of a complete system. The system is being marketed as complete and could e.g. be an air-conditioning system. The complete system must be CE labelled in accordance with the EMC directive. The manufacturer can ensure CE labelling under the EMC directive either by using CE labelled components or by testing the EMC of the system. If he chooses to use only CE labelled components, he does not have to test the entire system.

2.3.3 Danfoss Frequency Converter and CE Labelling

CE labelling is a positive feature when used for its original purpose, i.e. to facilitate trade within the EU and EFTA.

However, CE labelling may cover many different specifications. Thus, you have to check what a given CE label specifically covers.

The covered specifications can be very different and a CE label may therefore give the installer a false feeling of security when using a frequency converter as a component in a system or an appliance.

Danfoss CE labels the frequency converters in accordance with the low-voltage directive. This means that if the frequency converter is installed correctly, we guarantee compliance with the low-voltage directive. Danfoss issues a declaration of conformity that confirms our CE labelling in accordance with the low-voltage directive.

The CE label also applies to the EMC directive provided that the instructions for EMC-correct installation and filtering are followed. On this basis, a declaration of conformity in accordance with the EMC directive is issued.

The Design Guide offers detailed instructions for installation to ensure EMC-correct installation. Furthermore, Danfoss specifies which our different products comply with.

Danfoss gladly provides other types of assistance that can help you obtain the best EMC result.

2.3.4 Compliance with EMC Directive 89/336/EEC

As mentioned, the frequency converter is mostly used by professionals of the trade as a complex component forming part of a larger appliance, system, or installation. It must be noted that the responsibility for the final EMC properties of the appliance, system or installation rests with the installer. As an aid to the installer, Danfoss has prepared EMC installation guidelines for the Power Drive system. The standards and test levels stated for Power Drive systems are complied with, provided that the EMC-correct instructions for installation are followed, see the section *EMC Immunity*.

The frequency converter has been designed to meet the IEC/EN 60068-2-3 standard, EN 50178 pkt. 9.4.2.2 at 50°C.

A frequency converter contains a large number of mechanical and electronic components. All are to some extent vulnerable to environmental effects.

> **!** The frequency converter should not be installed in environments with airborne liquids, particles, or gases capable of affecting and damaging the electronic components. Failure to take the necessary protective measures increases the risk of stoppages, thus reducing the life of the frequency converter.

<u>Liquids</u> can be carried through the air and condense in the frequency converter and may cause corrosion of components and metal parts. Steam, oil, and salt water may cause corrosion of components and metal parts. In such environments, use equipment with enclosure rating IP 54/55. As an extra protection, coated printed circuit boards can be ordered as an option.

Airborne <u>Particles</u> such as dust may cause mechanical, electrical, or thermal failure in the frequency converter. A typical indicator of excessive levels of airborne particles is dust particles around the frequency converter fan. In very dusty environments, use equipment with enclosure rating IP 54/55 or a cabinet for IP 00/IP 20/TYPE 1 equipment.

In environments with high temperatures and humidity, <u>corrosive gases</u> such as sulphur, nitrogen, and chlorine compounds will cause chemical processes on the frequency converter components.

Such chemical reactions will rapidly affect and damage the electronic components. In such environments, mount the equipment in a cabinet with fresh air ventilation, keeping aggressive gases away from the frequency converter.
An extra protection in such areas is a coating of the printed circuit boards, which can be ordered as an option.

NB!
Mounting frequency converters in aggressive environments increases the risk of stoppages and considerably reduces the life of the converter.

Before installing the frequency converter, check the ambient air for liquids, particles, and gases. This is done by observing existing installations in this environment. Typical indicators of harmful airborne liquids are water or oil on metal parts, or corrosion of metal parts.

Excessive dust particle levels are often found on installation cabinets and existing electrical installations. One indicator of aggressive airborne gases is blackening of copper rails and cable ends on existing installations.

NB!
D and E enclosures have a stainless steel back-channel option to provide additional protection in aggressive environments. Proper ventilation is still required for the internal components of the drive. Contact Danfoss for additional information.

2.4 Vibration and shock

The frequency converter has been tested according to the procedure based on the shown standards:

The frequency converter complies with requirements that exist for units mounted on the walls and floors of production premises, as well as in panels bolted to walls or floors.

IEC/EN 60068-2-6:	Vibration (sinusoidal) - 1970
IEC/EN 60068-2-64:	Vibration, broad-band random

2.5 Advantages

2.7.1 Why use a Frequency Converter for Controlling Fans and Pumps?

A frequency converter takes advantage of the fact that centrifugal fans and pumps follow the laws of proportionality for such fans and pumps. For further information see the text *The Laws of Proportionality*.

2.7.2 The Clear Advantage - Energy Savings

The very clear advantage of using a frequency converter for controlling the speed of fans or pumps lies in the electricity savings.
When comparing with alternative control systems and technologies, a frequency converter is the optimum energy control system for controlling fan and pump systems.

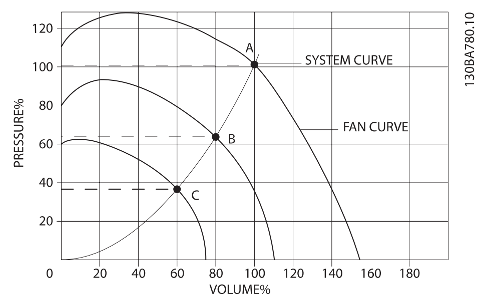


Illustration 2.1: The graph is showing fan curves (A, B and C) for reduced fan volumes.

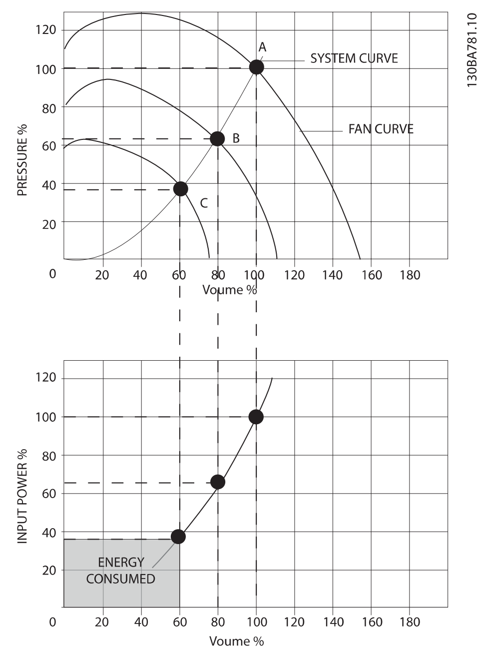


Illustration 2.2: When using a frequency converter to reduce fan capacity to 60% - more than 50% energy savings may be obtained in typical applications.

2.7.3 Example of Energy Savings

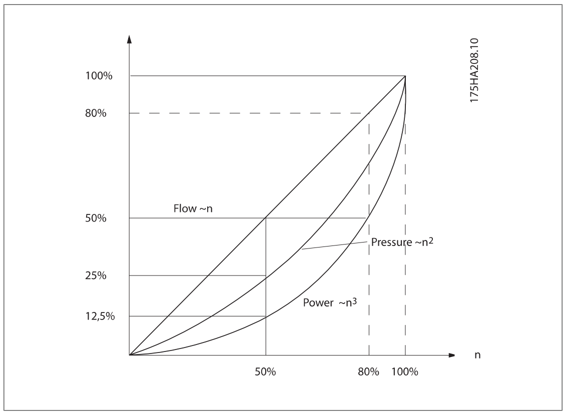
As can be seen from the figure (the laws of proportionality), the flow is controlled by changing the RPM. By reducing the speed only 20% from the rated speed, the flow is also reduced by 20%. This is because the flow is directly proportional to the RPM. The consumption of electricity, however, is reduced by 50%.

If the system in question only needs to be able to supply a flow that corresponds to 100% a few days in a year, while the average is below 80% of the rated flow for the remainder of the year, the amount of energy saved is even more than 50%.

The laws of proportionality

The figure below describes the dependence of flow, pressure and power consumption on RPM.

Q = Flow	P = Power
Q_1 = Rated flow	P_1 = Rated power
Q_2 = Reduced flow	P_2 = Reduced power
H = Pressure	n = Speed regulation
H_1 = Rated pressure	n_1 = Rated speed
H_2 = Reduced pressure	n_2 = Reduced speed



$$Flow\ :\ \frac{Q_1}{Q_2} = \frac{n_1}{n_2}$$

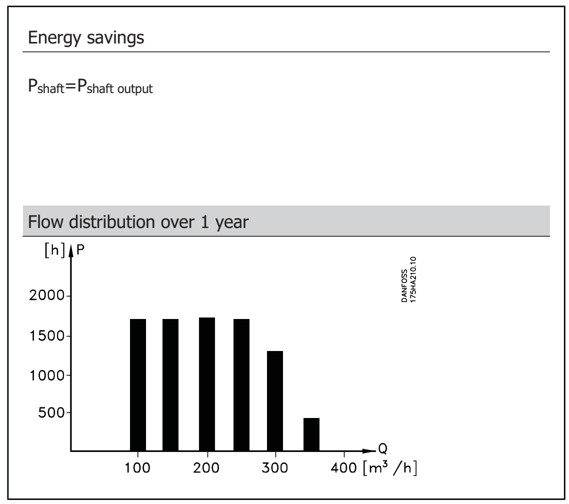
$$Pressure\ :\ \frac{H_1}{H_2} = \left(\frac{n_1}{n_2}\right)^2$$

$$Power\ :\ \frac{P_1}{P_2} = \left(\frac{n_1}{n_2}\right)^3$$

2.7.4 Example with Varying Flow over 1 Year

The example below is calculated on the basis of pump characteristics obtained from a pump datasheet.

The result obtained shows energy savings in excess of 50% at the given flow distribution over a year. The pay back period depends on the price per kwh and price of frequency converter. In this example it is less than a year when compared with valves and constant speed.



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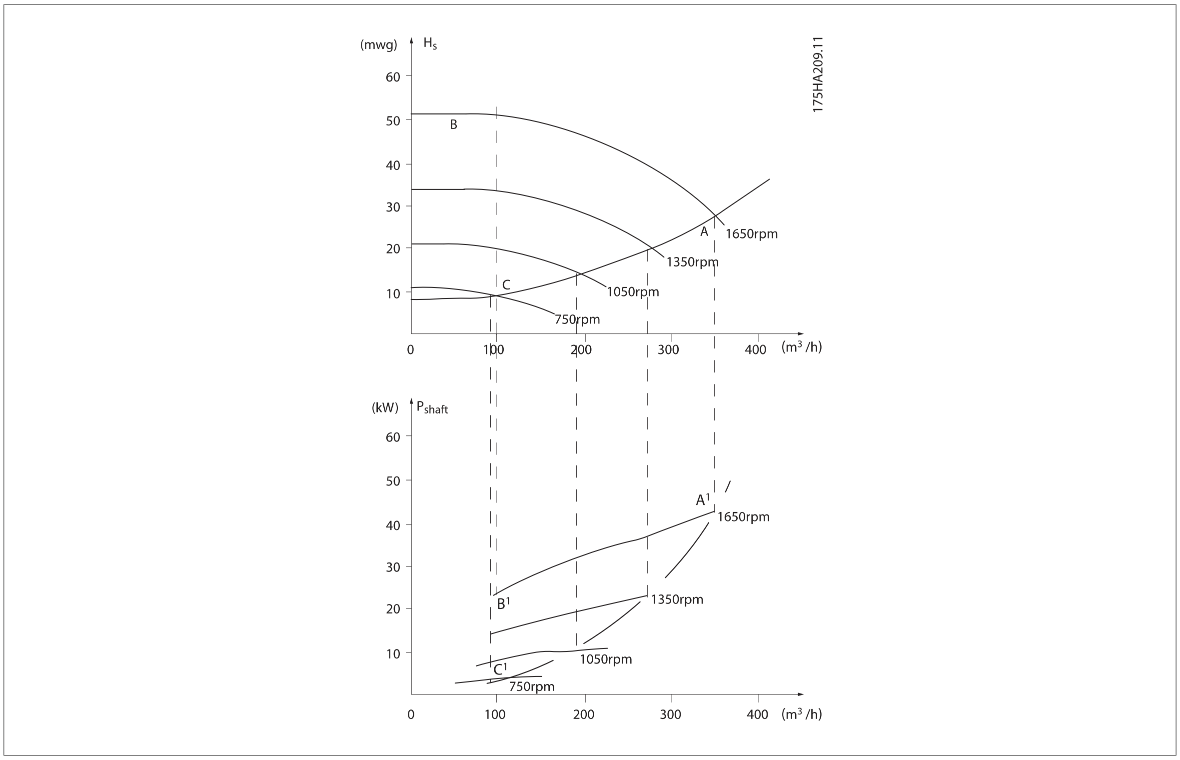


m³/h	Distribution		Valve regulation		Frequency converter control	
	%	Hours	Power	Consumption	Power	Consumption
			A_1 - B_1	kWh	A_1 - C_1	kWh
350	5	438	42,5	18.615	42,5	18.615
300	15	1314	38,5	50.589	29,0	38.106
250	20	1752	35,0	61.320	18,5	32.412
200	20	1752	31,5	55.188	11,5	20.148
150	20	1752	28,0	49.056	6,5	11.388
100	20	1752	23,0	40.296	3,5	6.132
Σ	100	8760		275.064		26.801

2.7.5 Better Control

If a frequency converter is used for controlling the flow or pressure of a system, improved control is obtained.
A frequency converter can vary the speed of the fan or pump, thereby obtaining variable control of flow and pressure.
Furthermore, a frequency converter can quickly adapt the speed of the fan or pump to new flow or pressure conditions in the system.
Simple control of process (Flow, Level or Pressure) utilizing the built in PID control.

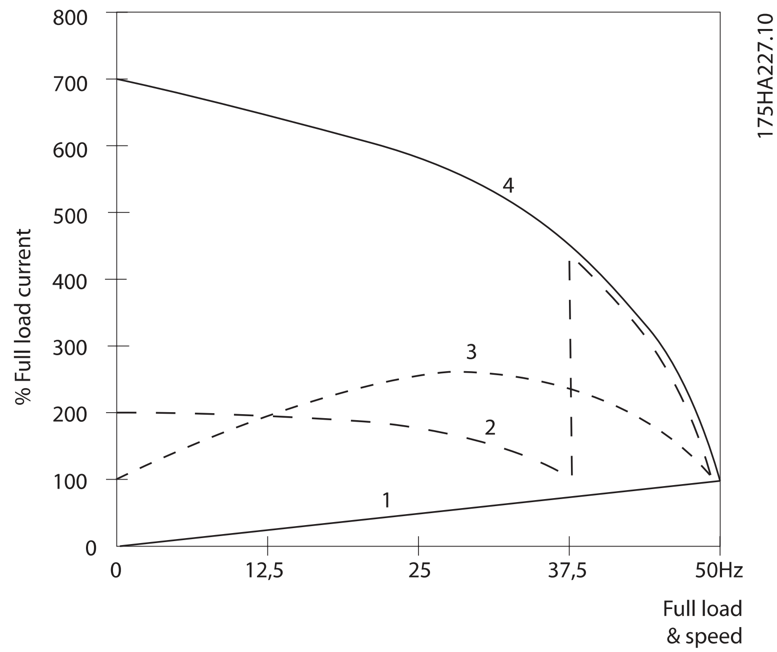
2.7.6 Cos φ Compensation

Generally speaking, a frequency converter with a cos φ of 1 provides power factor correction for the cos φ of the motor, which means that there is no need to make allowance for the cos φ of the motor when sizing the power factor correction unit.

2.7.7 Star/delta Starter or Soft-starter not required

When larger motors are started, it is necessary in many countries to use equipment that limits the start-up current. In more traditional systems, a star/delta starter or soft-starter is widely used. Such motor starters are not required if a frequency converter is used.

As illustrated in the figure below, a frequency converter does not consume more than rated current.



1 = VLT Automation VT Drive	
2 = Star/delta starter	
3 = Soft-starter	
4 = Start directly on mains	

2

2.6 Control Structures

2.8.1 Control Principle

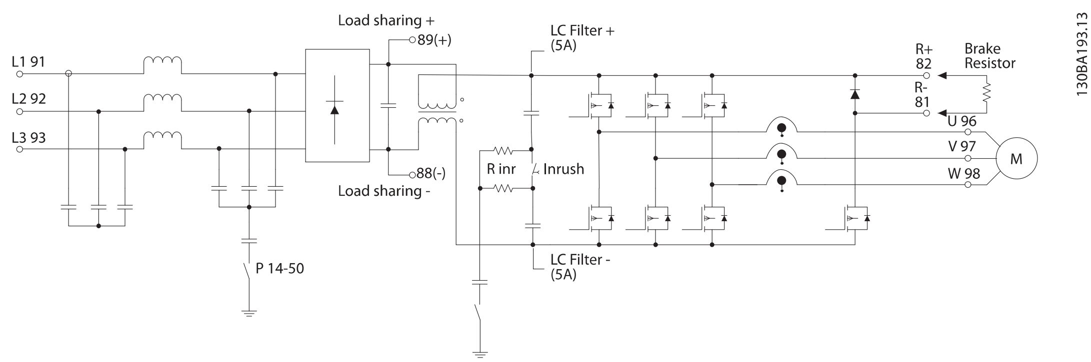


Illustration 2.3: Control structures.

The frequency converter is a high performance unit for demanding applications. It can handle various kinds of motor control principles such as U/f special motor mode and VVC plus and can handle normal squirrel cage asynchronous motors.
Short circuit behavior on this FC depends on the 3 current transducers in the motor phases.

In *par. 1-00 Configuration Mode* it can be selected if open or closed loop is to be used

2.8.2 Control Structure Open Loop

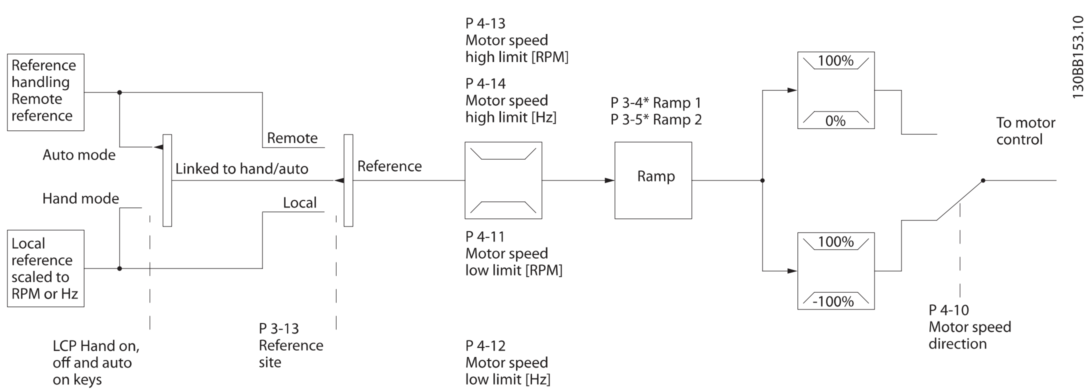


Illustration 2.4: Open Loop structure.

In the configuration shown in the illustration above, *par. 1-00 Configuration Mode* is set to Open loop [0]. The resulting reference from the reference handling system or the local reference is received and fed through the ramp limitation and speed limitation before being sent to the motor control.
The output from the motor control is then limited by the maximum frequency limit.

2.8.3 Local (Hand On) and Remote (Auto On) Control

The frequency converter can be operated manually via the local control panel (LCP) or remotely via analog/digital inputs or serial bus.
If allowed in par. 0-40 *[Hand on] Key on LCP*, par. 0-41 *[Off] Key on LCP*, par. 0-42 *[Auto on] Key on LCP*, and par. 0-43 *[Reset] Key on LCP*, it is possible to start and stop the frequency converter byLCP using the [Hand ON] and [Off] keys. Alarms can be reset via the [RESET] key. After pressing the [Hand On] key, the frequency converter goes into Hand Mode and follows (as default) the Local reference set by using the LCP arrow keys up [▲] and down [▼].

After pressing the [Auto On] key, the frequency converter goes into Auto mode and follows (as default) the Remote reference. In this mode, it is possible to control the frequency converter via the digital inputs and various serial interfaces (RS-485, USB, or an optional fieldbus). See more about starting, stopping, changing ramps and parameter set-ups etc. in par. group 5-1* (digital inputs) or par. group 8-5* (serial communication).

130BP046.10

Hand Off Auto LCP Keys	Reference Site par. 3-13 *Reference Site*	Active Reference
Hand	Linked to Hand / Auto	Local
Hand -> Off	Linked to Hand / Auto	Local
Auto	Linked to Hand / Auto	Remote
Auto -> Off	Linked to Hand / Auto	Remote
All keys	Local	Local
All keys	Remote	Remote

The table shows under which conditions either the Local Reference or the Remote Reference is active. One of them is always active, but both can not be active at the same time.

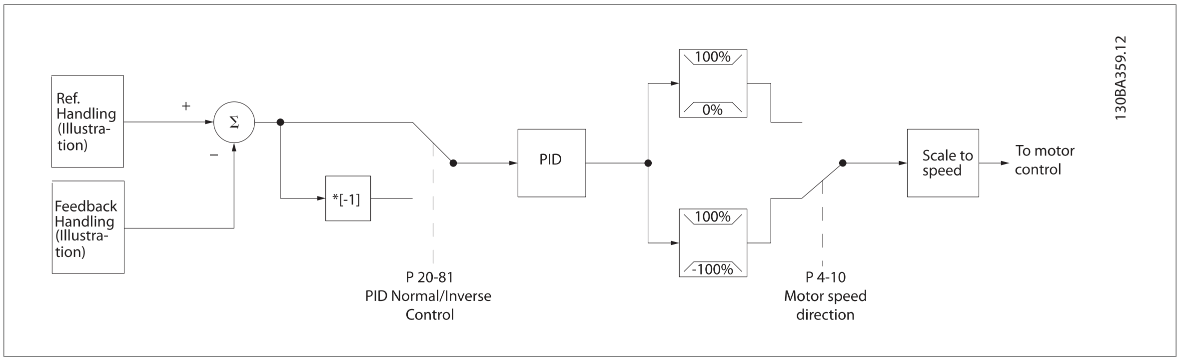
NB!
Local Reference will be restored at power-down.

par. 1-00 *Configuration Mode* determines what kind of application control principle (i.e. Open Loop or Closed loop) is used when the Remote reference is active (see table above for the conditions).

2.8.4 Control Structure Closed Loop

The closed loop controller allows the drive to become an integral part of the controlled system. The drive receives a feedback signal from a sensor in the system. It then compares this feedback to a set-point reference value and determines the error, if any, between these two signals. It then adjusts the speed of the motor to correct this error.

For example, consider a pump application where the speed of a pump is to be controlled so that the static pressure in a pipe is constant. The desired static pressure value is supplied to the drive as the set-point reference. A static pressure sensor measures the actual static pressure in the pipe and supplies this to the drive as a feedback signal. If the feedback signal is greater than the set-point reference, the drive will slow down to reduce the pressure. In a similar way, if the pipe pressure is lower than the set-point reference, the drive will automatically speed up to increase the pressure provided by the pump.

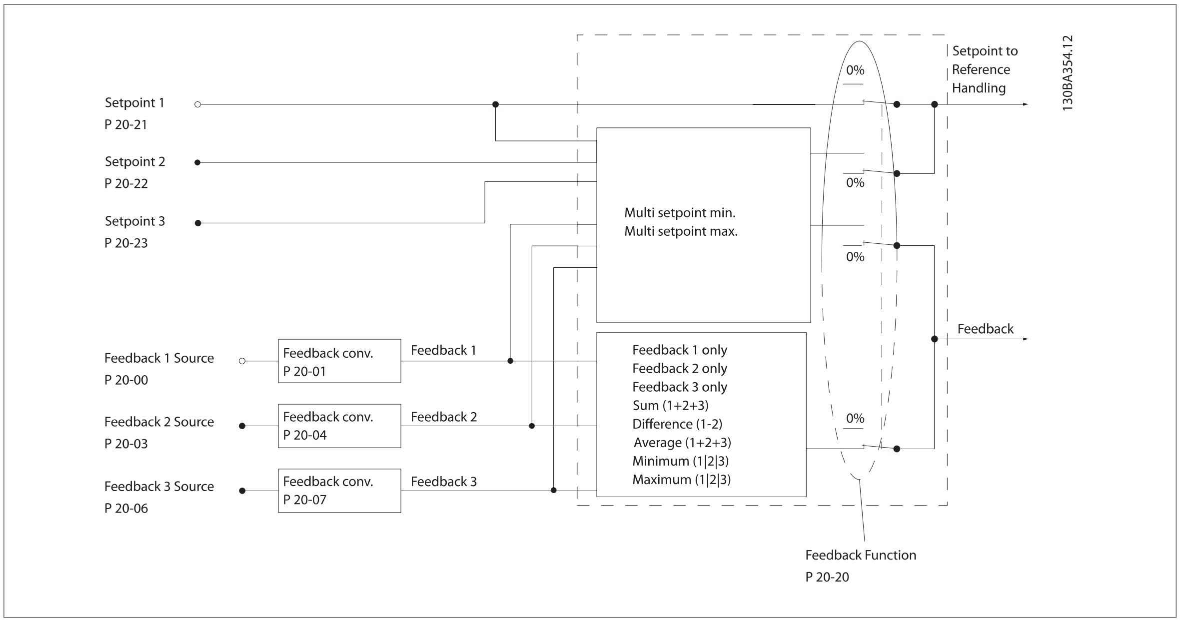


NB!
While the default values for the drive's Closed Loop controller will often provide satisfactory performance, the control of the system can often be optimized by adjusting some of the Closed Loop controller's parameters. It is also possible to autotune the PI constants.

The figure is a block diagram of the drive's Closed Loop controller. The details of the Reference Handling block and Feedback Handling block are described in their respective sections below.

2.8.5 Feedback Handling

A block diagram of how the drive processes the feedback signal is shown below.



Feedback handling can be configured to work with applications requiring advanced control, such as multiple setpoints and multiple feedbacks. Three types of control are common.

Single Zone, Single Setpoint

Single Zone Single Setpoint is a basic configuration. Setpoint 1 is added to any other reference (if any, see Reference Handling) and the feedback signal is selected using par. 20-20.

Multi Zone, Single Setpoint

Multi Zone Single Setpoint uses two or three feedback sensors but only one setpoint. The feedbacks can be added, subtracted (only feedback 1 and 2) or averaged. In addition, the maximum or minimum value may be used. Setpoint 1 is used exclusively in this configuration.

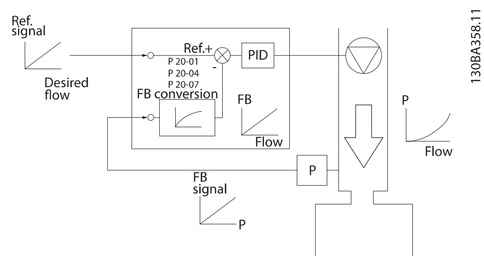
If *Multi Setpoint Min* [13] is selected, the setpoint/feedback pair with the largest difference controls the speed of the drive. *Multi Setpoint Maximum* [14] attempts to keep all zones at or below their respective setpoints, while *Multi Setpoint Min* [13] attempts to keep all zones at or above their respective setpoints.

Example:

A two zone two setpoint application Zone 1 setpoint is 15 bar and the feedback is 5.5 bar. Zone 2 setpoint is 4.4 bar and the feedback is 4.6 bar. If *Multi Setpoint Max* [14] is selected, Zone 1's setpoint and feedback are sent to the PID controller, since this has the smaller difference (feedback is higher than setpoint, resulting in a negative difference). If *Multi Setpoint Min* [13] is selected, Zone 2's setpoint and feedback is sent to the PID controller, since this has the larger difference (feedback is lower than setpoint, resulting in a positive difference).

2.8.6 Feedback Conversion

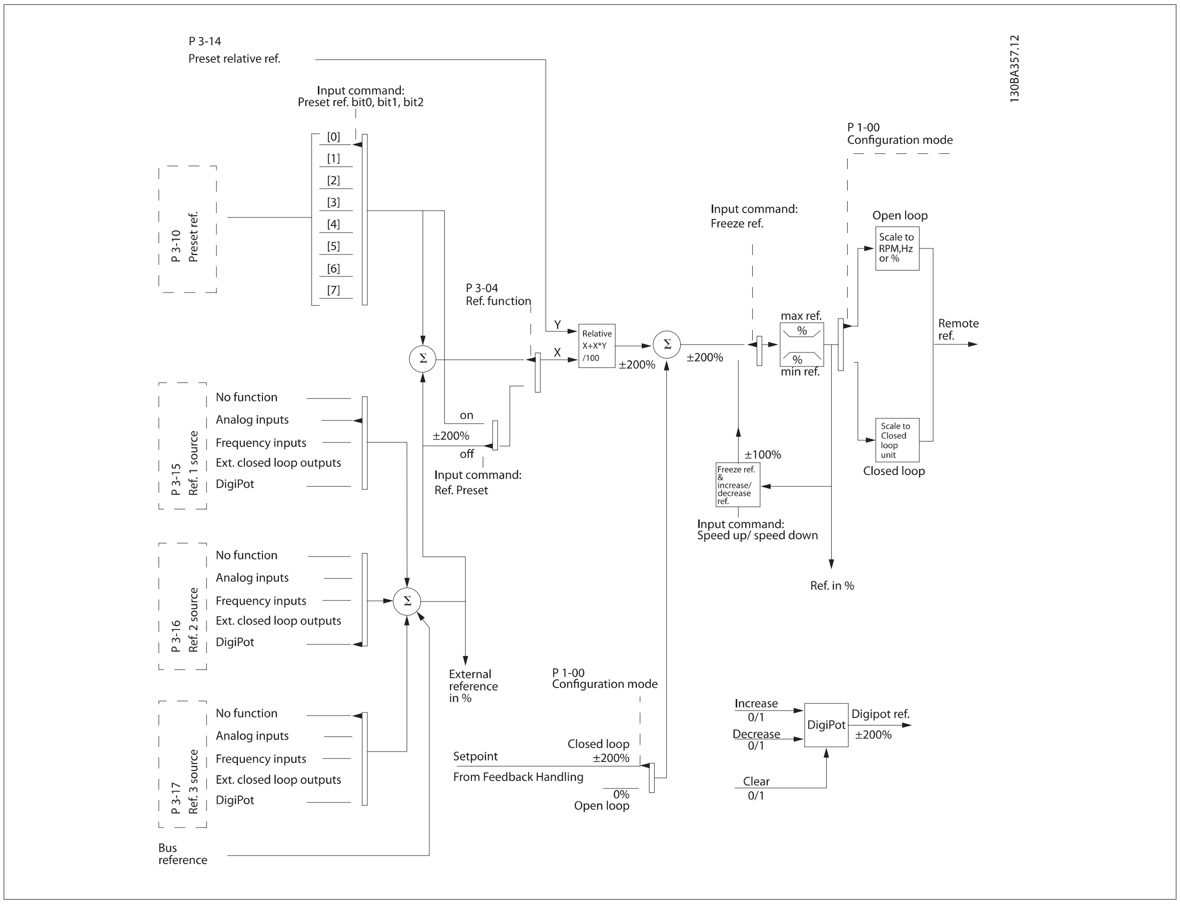
In some applications it may be useful to convert the feedback signal. One example of this is using a pressure signal to provide flow feedback. Since the square root of pressure is proportional to flow, the square root of the pressure signal yields a value proportional to the flow. This is shown below.



2.8.7 Reference Handling

Details for Open Loop and Closed Loop operation.

A block diagram of how the drive produces the Remote Reference is shown below:.


P 3-14
Preset relative ref.
Input command:
Preset ref. bit0, bit1, bit2
[0]
[1]
[2]
[3]
[4]
[5]
[6]
[7]
P 3-10
Preset ref.
P 3-04
Ref. function
Y
X
Relative
X+X*Y
/100
±200%
±200%
P 1-00
Configuration mode
Input command:
Freeze ref.
Open loop
Scale to
RPM,Hz
or %
max ref.
%
%
min ref.
Remote
ref.
on
±200%
off
Input command:
Ref. Preset
±100%
Freeze ref.
&
increase/
decrease
ref.
Scale to
Closed
loop
unit
Closed loop
Input command:
Speed up/ speed down
Ref. in %
P 3-15
Ref. 1 source
No function
Analog inputs
Frequency inputs
Ext. closed loop outputs
DigiPot
P 3-16
Ref. 2 source
No function
Analog inputs
Frequency inputs
Ext. closed loop outputs
DigiPot
External
reference
in %
P 1-00
Configuration mode
P 3-17
Ref. 3 source
No function
Analog inputs
Frequency inputs
Ext. closed loop outputs
DigiPot
Setpoint
From Feedback Handling
Closed loop
±200%
0%
Open loop
Increase
0/1
Decrease
0/1
DigiPot
Digipot ref.
±200%
Clear
0/1
Bus
reference
130BA357.12

The Remote Reference is comprised of:

- Preset references.
- External references (analog inputs, pulse frequency inputs, digital potentiometer inputs and serial communication bus references).
- The Preset relative reference.
- Feedback controlled setpoint.

Up to 8 preset references can be programmed in the drive. The active preset reference can be selected using digital inputs or the serial communications bus. The reference can also be supplied externally, most commonly from an analog input. This external source is selected by one of the 3 Reference Source parameters (par. 3-15 *Reference 1 Source*, par. 3-16 *Reference 2 Source* and par. 3-17 *Reference 3 Source*). Digipot is a digital potentiometer. This is also commonly called a Speed Up/Speed Down Control or a Floating Point Control. To set it up, one digital input is programmed to increase the reference while another digital input is programmed to decrease the reference. A third digital input can be used to reset the Digipot reference. All reference resources and the bus reference are added to produce the total External Reference. The External Reference, the Preset Reference or the sum of the two can be selected to be the active reference. Finally, this reference can by be scaled using par. 3-14 *Preset Relative Reference*.

The scaled reference is calculated as follows:

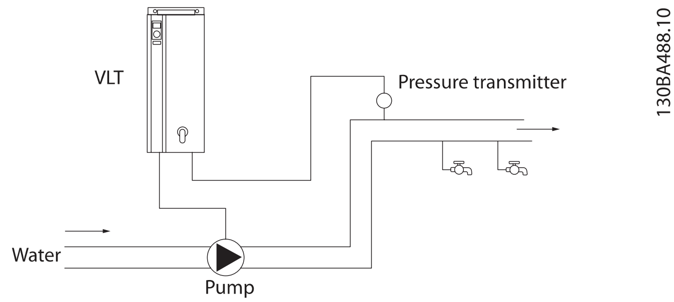
$$Reference = X + X \times \left(\frac{Y}{100}\right)$$

Where X is the external reference, the preset reference or the sum of these and Y is par. 3-14 *Preset Relative Reference* in [%].

NB!
If Y, par. 3-14 *Preset Relative Reference* is set to 0%, the reference will not be affected by the scaling

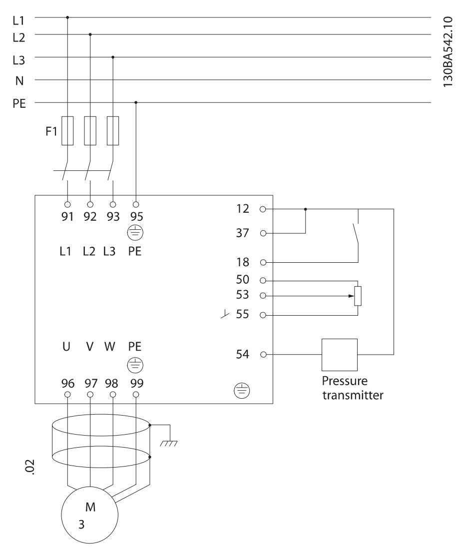
2.8.8 Example of Closed Loop PID Control

The following is an example of a Closed Loop Control for a booster pump application:



In a water distribution system, the pressure is to be maintained at a constant value. The desired pressure (setpoint) is set between 0 and 10 Bar using a 0-10 volt potentiometer or can be set by a parameter. The pressure sensor has a range of 0 to 10 Bar and uses a two-wire transmitter to provide a 4-20 mA signal. The output frequency range of the drive is 10 to 50 Hz.

1. Start/Stop via switch connected between terminals 12 (+24 V) and 18.
2. Pressure reference via a potentiometer (0-10 Bar, 0-10 V) connected to terminals 50 (+10 V), 53 (input) and 55 (common).
3. Pressure feedback via transmitter (0-10 Bar, 4-20 mA) connected to terminal 54. Switch S202 behind the Local Control Panel set to ON (current input).



2.8.9 Programming Order

Function	Par. no.	Setting
1) Make sure the motor runs properly. Do the following:		
Set the drive to control the motor based on drive output frequency.	0-02	*Hz* [1]
Set the motor parameters using nameplate data.	1-2*	As specified by motor name plate
Run Automatic Motor Adaptation.	1-29	*Enable complete AMA* [1] and then run the AMA function.
2) Check that the motor is running in the right direction.		
Press the "Hand On" LCP key and the ^ key to make the motor turn slowly. Check that the motor runs in the correct direction.		If the motor runs in the wrong direction, remove power temporarily and reverse two of the motor phases.
3) Make sure the frequency converter limits are set to safe values		
Check that the ramp settings are within capabilities of the drive and allowed application operating specifications.	3-41 3-42	60 sec. 60 sec. Depends on motor/load size! Also active in Hand mode.
Prohibit the motor from reversing (if necessary)	4-10	*Clockwise* [0]
Set acceptable limits for the motor speed.	4-12 4-14 4-19	10 Hz, *Motor min speed* 50 Hz, *Motor max speed* 50 Hz, *Drive max output frequency*
Switch from open loop to closed loop.	1-00	*Closed Loop* [3]
4) Configure the feedback to the PID controller.		
Set up Analog Input 54 as a feedback input.	20-00	*Analog input 54* [2] (default)
Select the appropriate reference/feedback unit.	20-12	*Bar* [71]
5) Configure the setpoint reference for the PID controller.		
Set acceptable limits for the setpoint reference.	3-02 3-03	0 Bar 10 Bar
Set up Analog Input 53 as Reference 1 Source.	3-15	*Analog input 53* [1] (default)
6) Scale the analog inputs used for setpoint reference and feedback.		
Scale Analog Input 53 for the pressure range of the potentiometer (0 - 10 Bar, 0 - 10 V).	6-10 6-11 6-14 6-15	0 V 10 V (default) 0 Bar 10 Bar
Scale Analog Input 54 for pressure sensor (0 - 10 Bar, 4 - 20 mA)	6-22 6-23 6-24 6-25	4 mA 20 mA (default) 0 Bar 10 Bar
7) Tune the PID controller parameters.		
Adjust the drive's Closed Loop Controller, if needed.	20-93 20-94	See Optimization of the PID Controller, below.
8) Finished!		
Save the parameter setting to the LCP for safe keeping	0-50	*All to LCP* [1]

2.8.10 Tuning the Drive Closed Loop Controller

Once the drive's Closed Loop Controller has been set up, the performance of the controller should be tested. In many cases, its performance may be acceptable using the default values of PID Proportional Gain (par. 20-93) and PID Integral Time (par. 20-94). However, in some cases it may be helpful to optimize these parameter values to provide faster system response while still controlling speed overshoot.

2.8.11 Manual PID Adjustment

1. Start the motor
2. Set par. 20-93 (PID Proportional Gain) to 0.3 and increase it until the feedback signal begins to oscillate. If necessary, start and stop the drive or make step changes in the set-point reference to attempt to cause oscillation. Next reduce the PID Proportional Gain until the feedback signal stabilizes. Then reduce the proportional gain by 40-60%.
3. Set par. 20-94 (PID Integral Time) to 20 sec. and reduce it until the feedback signal begins to oscillate. If necessary, start and stop the drive or make step changes in the set-point reference to attempt to cause oscillation. Next, increase the PID Integral Time until the feedback signal stabilizes. Then increase of the Integral Time by 15-50%.
4. Par. 20-95 (PID Differential Time) should only be used for very fast-acting systems. The typical value is 25% of the PID Integral Time (par. 20-94). The differential function should only be used when the setting of the proportional gain and the integral time has been fully optimized. Make sure that oscillations of the feedback signal are sufficiently dampened by the low-pass filter for the feedback signal (par 6 16, 6 26, 5 54 or 5 59, as required).

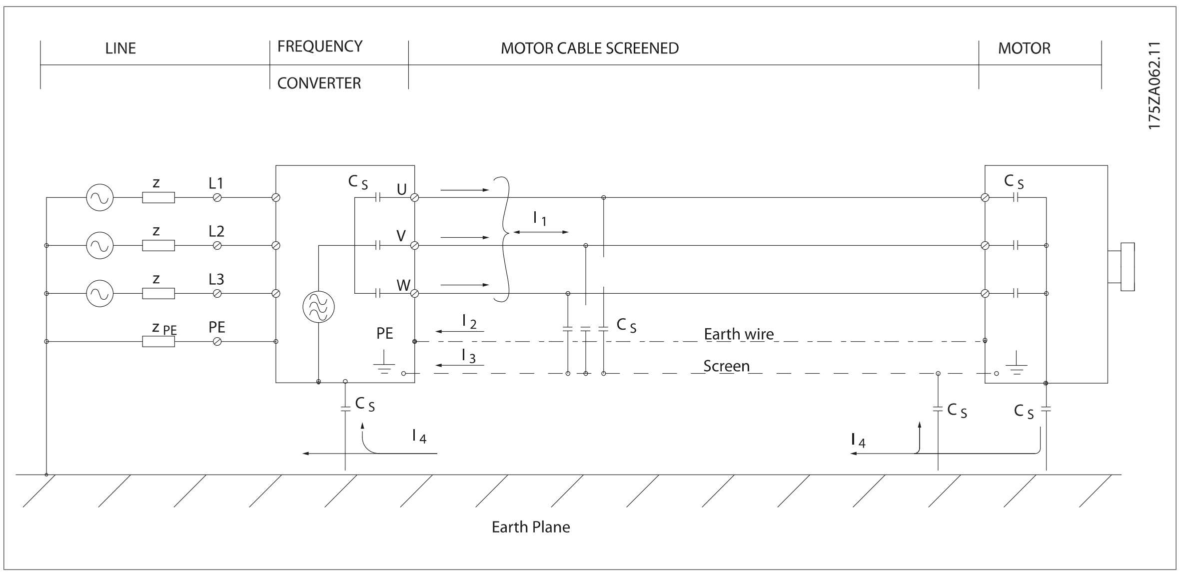
2

2.7 General aspects of EMC

2.9.1 General Aspects of EMC Emissions

Electrical interference is usually conducted at frequences in the range 150 kHz to 30 MHz. Airborne interference from the drive system in the range 30 MHz to 1 GHz is generated from the inverter, motor cable, and the motor.
As shown in the illustration below, capacitive currents in the motor cable coupled with a high dV/dt from the motor voltage generate leakage currents. The use of a screened motor cable increases the leakage current (see illustration below) because screened cables have higher capacitance to earth than unscreened cables. If the leakage current is not filtered, it will cause greater interference on the mains in the radio frequency range below approx. 5 MHz. Since the leakage current (I_1) is carried back to the unit through the screen (I_3), there will in principle only be a small electro-magnetic field (I_4) from the screened motor cable according to the below figure.

The screen reduces the radiated interference but increases the low-frequency interference on the mains. The motor cable screen must be connected to the frequency converter enclosure as well as on the motor enclosure. This is best done by using integrated screen clamps so as to avoid twisted screen ends (pigtails). These increase the screen impedance at higher frequencies, which reduces the screen effect and increases the leakage current (I_4).
If a screened cable is used for Fieldbus, relay, control cable, signal interface and brake, the screen must be mounted on the enclosure at both ends. In some situations, however, it will be necessary to break the screen to avoid current loops.



If the screen is to be placed on a mounting plate for the frequency converter, the mounting plate must be made of metal, because the screen currents have to be conveyed back to the unit. Moreover, ensure good electrical contact from the mounting plate through the mounting screws to the frequency converter chassis.

NB!
When unscreened cables are used, some emission requirements are not complied with, although the immunity requirements are observed.

In order to reduce the interference level from the entire system (unit + installation), make motor and brake cables as short as possible. Avoid placing cables with a sensitive signal level alongside motor and brake cables. Radio interference higher than 50 MHz (airborne) is especially generated by the control electronics.

2.9.2 Emission Requirements

According to the EMC product standard for adjustable speed frequency converters EN/IEC61800-3:2004 the EMC requirements depend on the intended use of the frequency converter. Four categories are defined in the EMC product standard. The definitions of the four categories together with the requirements for mains supply voltage conducted emissions are given in the table below:

Category	Definition	Conducted emission requirement according to the limits given in EN55011
C1	frequency converters installed in the first environment (home and office) with a supply voltage less than 1000 V.	Class B
C2	frequency converters installed in the first environment (home and office) with a supply voltage less than 1000 V, which are neither plug-in nor movable and are intended to be installed and commissioned by a professional.	Class A Group 1
C3	frequency converters installed in the second environment (industrial) with a supply voltage lower than 1000 V.	Class A Group 2
C4	frequency converters installed in the second environment with a supply voltage above 1000 V and rated current above 400 A or intended for use in complex systems.	No limit line. An EMC plan should be made.

When the generic emission standards are used the frequency converters are required to comply with the following limits:

Environment	Generic standard	Conducted emission requirement according to the limits given in EN55011
First environment (home and office)	EN/IEC61000-6-3 Emission standard for residential, commercial and light industrial environments.	Class B
Second environment (industrial environment)	EN/IEC61000-6-4 Emission standard for industrial environments.	Class A Group 1

2.9.3 EMC Test Results (Emission)

The following test results have been obtained using a system with a frequency converter (with options if relevant), a screened control cable, a control box with potentiometer, as well as a motor and motor screened cable.

RFI filter type	**Phase type**	**Conducted emission.** Maximum shielded cable length.			**Radiated emission**	
		Industrial environment		Housing, trades and light industries	Industrial environment	Housing, trades and light industries
Setup:	**S / T**	EN 55011 Class A2	EN 55011 Class A1	EN 55011 Class B	EN 55011 Class A1	EN 55011 Class B
H1		meter	meter	meter		
1.1-22 kW 220-240 V	**S2**	150	150	50	Yes	No
0.25-45 kW 200-240 V	**T2**	150	150	50	Yes	No
7.5-37 kW 380-480 V	**S4**	150	150	50	Yes	No
0.37-90 kW 380-480 V	**T4**	150	150	50	Yes	No
H2						
1.1-22 kW 220-240 V	**S2**	25	No	No	No	No
0.25-3.7 kW 200-240 V	**T2**	5	No	No	No	No
5.5-45 kW 200-240 V	**T2**	25	No	No	No	No
0.37-7.5 kW 380-480 V	**T4**	5	No	No	No	No
7.5-37 kW 380-480 V	**S4**	25	No	No	No	No
11-90 kW 380-480 V	**T4**	25	No	No	No	No
110-1000 kW 380-480 V	**T4**	50	No	No	No	No
0.75-90 kW 525-600 V	**T6**	150	No	No	No	No
11-90 kW 525-690 V	**T7**	Yes	No	No	No	No
45-1200 kW 525-690 V	**T7**	150	No	No	No	No
H3						
0.25-45 kW 200-240 V	**T2**	75	50	10	Yes	No
0.37-90 kW 380-480 V	**T4**	75	50	10	Yes	No
H4						
110-1000 kW 380-480 V	**T4**	150	150	No	Yes	No
11-90 kW 525-690 V	**T7**	No	Yes	No	Yes	No
45-400 kW 525-690 V	**T7**	150	30	No	No	No
Hx						
0.75-90 kW 525-600 V	**T6**	-	-	-	-	-

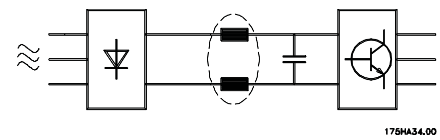
Table 2.1: EMC Test Results (Emission)

2.9.4 General Aspects of Harmonics Emission

A frequency converter takes up a non-sinusoidal current from mains, which increases the input current I_{RMS}. A non-sinusoidal current is transformed by means of a Fourier analysis and split up into sine-wave currents with different frequencies, i.e. different harmonic currents I_N with 50 Hz as the basic frequency:

Harmonic currents	I_1	I_5	I_7
Hz	50 Hz	250 Hz	350 Hz

The harmonics do not affect the power consumption directly but increase the heat losses in the installation (transformer, cables). Consequently, in plants with a high percentage of rectifier load, maintain harmonic currents at a low level to avoid overload of the transformer and high temperature in the cables.



NB!
Some of the harmonic currents might disturb communication equipment connected to the same transformer or cause resonance in connection with power-factor correction batteries.

NB!
To ensure low harmonic currents, the frequency converter is equipped with intermediate circuit coils as standard. This normally reduces the input current I_{RMS} by 40%.

The voltage distortion on the mains supply voltage depends on the size of the harmonic currents multiplied by the mains impedance for the frequency in question. The total voltage distortion THD is calculated on the basis of the individual voltage harmonics using this formula:

$$THD\,\% = \sqrt{U_5^2 + U_7^2 + ... + U_N^2}$$

(U_N% of U)

2.9.5 Harmonics Emission Requirements

Equipment connected to the public supply network:

Options:	Definition:
1	IEC/EN 61000-3-2 Class A for 3-phase balanced equipment (for professional equipment only up to 1 kW total power).
2	IEC/EN 61000-3-12 Equipment 16A-75A and professional equipment as from 1 kW up to 16A phase current.

2.9.6 Harmonics Test Results (Emission)

Power sizes up to PK75 in T2 and T4 complies with IEC/EN 61000-3-2 Class A. Power sizes from P1K1 and up to P18K in T2 and up to P90K in T4 complies with IEC/EN 61000-3-12. Power sizes P110 - P450 in T4 also complies with IEC/EN 61000-3-12 even though not required because currents are above 75 A.
Table 4, R_{sce} >= 120, THD <= 48% and PWHD >=46% provided that the short-circuit power of the supply S_{sc} is greater than or equal to:

$$S_{SC} = \sqrt{3} \times R_{SCE} \times U_{mains} \times I_{equ} = \sqrt{3} \times 120 \times 400 \times I_{equ}$$

at the interface point between the user’s supply and the public system.

It is the responsibility of the installer or user of the equipment to ensure, by consultation with the distribution network operator if necessary, that the equipment is connected only to a supply with a short-circuit power S_{sc} greater than or equal to specified above.
Other power sizes can be connected to the public supply network by consultation with the distribution network operator.

2.8 Immunity Requirements

The immunity requirements for frequency converters depend on the environment where they are installed. The requirements for the industrial environment are higher than the requirements for the home and office environment. All Danfoss frequency converters comply with the requirements for the industrial environment and consequently comply also with the lower requirements for home and office environment with a large safety margin.

In order to document immunity against electrical interference from electrical phenomena, the following immunity tests have been made on a system consisting of a frequency converter (with options if relevant), a screened control cable and a control box with potentiometer, motor cable and motor.
The tests were performed in accordance with the following basic standards:

- **EN 61000-4-2 (IEC 61000-4-2):** Electrostatic discharges (ESD): Simulation of electrostatic discharges from human beings.
- **EN 61000-4-3 (IEC 61000-4-3):** Incoming electromagnetic field radiation, amplitude modulated simulation of the effects of radar and radio communication equipment as well as mobile communications equipment.
- **EN 61000-4-4 (IEC 61000-4-4):** Burst transients: Simulation of interference brought about by switching a contactor, relay or similar devices.
- **EN 61000-4-5 (IEC 61000-4-5):** Surge transients: Simulation of transients brought about e.g. by lightning that strikes near installations.
- **EN 61000-4-6 (IEC 61000-4-6):** RF Common mode: Simulation of the effect from radio-transmission equipment joined by connection cables.

See following EMC immunity form.

Voltage range: 200-240 V, 380-480 V

Basic standard	Burst IEC 61000-4-4	Surge IEC 61000-4-5	ESD IEC 61000-4-2	Radiated electromagnetic field IEC 61000-4-3	RF common mode voltage IEC 61000-4-6
Acceptance criterion	B	B	B	A	A
Line	4 kV CM	2 kV/2 Ω DM 4 kV/12 Ω CM	—	—	10 V_{RMS}
Motor	4 kV CM	4 kV/2 Ω[1)]	—	—	10 V_{RMS}
Brake	4 kV CM	4 kV/2 Ω[1)]	—	—	10 V_{RMS}
Load sharing	4 kV CM	4 kV/2 Ω[1)]	—	—	10 V_{RMS}
Control wires	2 kV CM	2 kV/2 Ω[1)]	—	—	10 V_{RMS}
Standard bus	2 kV CM	2 kV/2 Ω[1)]	—	—	10 V_{RMS}
Relay wires	2 kV CM	2 kV/2 Ω[1)]	—	—	10 V_{RMS}
Application and Fieldbus options	2 kV CM	2 kV/2 Ω[1)]	—	—	10 V_{RMS}
LCP cable	2 kV CM	2 kV/2 Ω[1)]	—	—	10 V_{RMS}
External 24 V DC	2 kV CM	0.5 kV/2 Ω DM 1 kV/12 Ω CM	—	—	10 V_{RMS}
Enclosure	—	—	8 kV AD 6 kV CD	10 V/m	—

AD: Air Discharge
CD: Contact Discharge
CM: Common mode
DM: Differential mode
1. Injection on cable shield.

Table 2.2: Immunity

2.9 Galvanic isolation (PELV)

2.11.1 PELV - Protective Extra Low Voltage

PELV offers protection by way of extra low voltage. Protection against electric shock is ensured when the electrical supply is of the PELV type and the installation is made as described in local/national regulations on PELV supplies.

All control terminals and relay terminals 01-03/04-06 comply with PELV (Protective Extra Low Voltage) (Does not apply to grounded Delta leg above 400 V).

Galvanic (ensured) isolation is obtained by fulfilling requirements for higher isolation and by providing the relevant creapage/clearance distances. These requirements are described in the EN 61800-5-1 standard.

The components that make up the electrical isolation, as described below, also comply with the requirements for higher isolation and the relevant test as described in EN 61800-5-1.
The PELV galvanic isolation can be shown in six locations (see illustration):

In order to maintain PELV all connections made to the control terminals must be PELV, e.g. thermistor must be reinforced/double insulated.

1. Power supply (SMPS) incl. signal isolation of U_{DC}, indicating the intermediate current voltage.
2. Gate drive that runs the IGBTs (trigger transformers/opto-couplers).
3. Current transducers.
4. Opto-coupler, brake module.
5. Internal inrush, RFI, and temperature measurement circuits.
6. Custom relays.

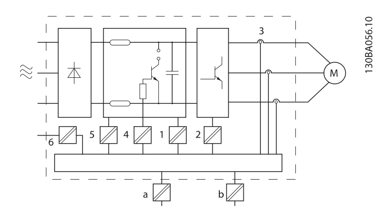


Illustration 2.5: Galvanic isolation

The functional galvanic isolation (a and b on drawing) is for the 24 V back-up option and for the RS 485 standard bus interface.

Installation at high altitude:
380 - 500 V, enclosure A, B and C: At altitudes above 2 km, please contact Danfoss regarding PELV.
380 - 500 V, enclosure D, E and F: At altitudes above 3 km, please contact Danfoss regarding PELV.
525 - 690 V: At altitudes above 2 km, please contact Danfoss regarding PELV.

2.10 Earth leakage current

Warning:

Touching the electrical ts may be fatal - even after the equipment has been disconnected from mains.

Also make sure that other voltage inputs have been disconnected, such as load sharing (linkage of DC intermediate circuit), as well as the motor connection for kinetic back-up.

Before touching any electrical parts, wait at least the amount of time indicated in the *Safety Precautions* section.

Shorter time is allowed only if indicated on the nameplate for the specific unit.

Leakage Current

The earth leakage current from the frequency converter exceeds 3.5 mA. To ensure that the earth cable has a good mechanical connection to the earth connection (terminal 95), the cable cross section must be at least 10 mm^2 or 2 rated earth wires terminated seately.

Residual Current Device

This product can cause a d.c. current in the protective conductor. Where a residual current device (RCD) is used for protection in case of direct or indirect contact, only an RCD of Type B is allowed on the supply side of this product. Otherwise, another protective measure shall be applied, such as separation from the environment by double or reinforced insulation, or isolation from the supply system by a transformer. See also RCD Application Note MN.90.GX.02.

Protective earthing of the frequency converter and the use of RCD's must always follow national and local regulations.

2.11 Control with Brake Function

2.13.1 Selection of Brake Resistor

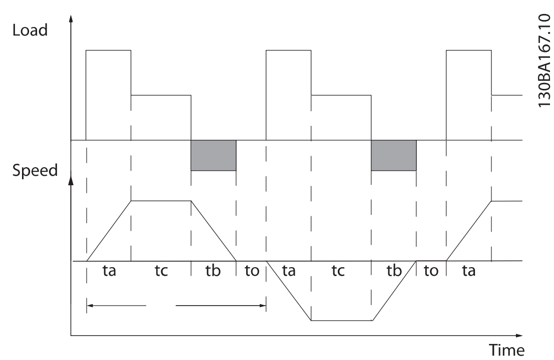
In certain applications, for instance centrifuges, it is desirable to bring the motor to a stop more rapidly than can be achieved through controlling via ramp down or by free-wheeling. In such applications, dynamic braking with a braking resistor may be utilized. Using a braking resistor ensures that the energy is absorbed in the resistor and not in the frequency converter.

If the amount of kinetic energy transferred to the resistor in each braking period is not known, the average power can be calculated on the basis of the cycle time and braking time also called intermitted duty cycle. The resistor intermittent duty cycle is an indication of the duty cycle at which the resistor is active. The below figure shows a typical braking cycle.

The intermittent duty cycle for the resistor is calculated as follows:

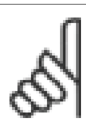
Duty Cycle = t_b/T

T = cycle time in seconds
t_b is the braking time in seconds (as part of the total cycle time)



Danfoss offers brake resistors with duty cycle of 5%, 10% and 40% suitable for use with the Automation VT Drive FC322 series. If a 10% duty cycle resistor is applied, this is able of absorbing braking power upto 10% of the cycle time with the remaining 90% being used to dissipate heat from the resistor.

For further selection advice, please contact Danfoss.



NB!
If a short circuit in the brake transistor occurs, power dissipation in the brake resistor is only prevented by using a mains switch or contactor to disconnect the mains for the frequency converter. (The contactor can be controlled by the frequency converter).

2.13.2 Control with Brake Function

The brake is protected against short-circuiting of the brake resistor, and the brake transistor is monitored to ensure that short-circuiting of the transistor is detected. A relay/digital output can be used for protecting the brake resistor against overloading in connection with a fault in the frequency converter. In addition, the brake makes it possible to read out the momentary power and the mean power for the latest 120 seconds. The brake can also monitor the power energizing and make sure it does not exceed a limit selected in par. 2-12 *Brake Power Limit (kW)*. In par. 2-13 *Brake Power Monitoring*, select the function to carry out when the power transmitted to the brake resistor exceeds the limit set in par. 2-12 *Brake Power Limit (kW)*.

NB!
Monitoring the brake power is not a safety function; a thermal switch is required for that purpose. The brake resistor circuit is not earth leakage protected.

Over voltage control (OVC) (exclusive brake resistor) can be selected as an alternative brake function in par. 2-17 *Over-voltage Control*. This function is active for all units. The function ensures that a trip can be avoided if the DC link voltage increases. This is done by increasing the output frequency to limit the voltage from the DC link. It is a very useful function, e.g. if the ramp-down time is too short since tripping of the frequency converter is avoided. In this situation the ramp-down time is extended.

2.12 Mechanical Brake Control

2.14.1 Brake Resistor Cabling

EMC (twisted cables/shielding)
To reduce the electrical noise from the wires between the brake resistor and the frequency converter, the wires must be twisted.

For enhanced EMC performance a metal screen can be used.

2.13 Extreme Running Conditions

Short Circuit (Motor Phase – Phase)
The frequency converter is protected against short circuits by means of current measurement in each of the three motor phases or in the DC link. A short circuit between two output phases will cause an overcurrent in the inverter. The inverter will be turned off individually when the short circuit current exceeds the permitted value (Alarm 16 Trip Lock.
To protect the drive against a short circuit at the load sharing and brake outputs please see the design guidelines.

Switching on the Output
Switching on the output between the motor and the frequency converter is fully permitted. You cannot damage the frequency converter in any way by switching on the output. However, fault messages may appear.

Motor-generated Overvoltage
The voltage in the intermediate circuit is increased when the motor acts as a generator.

This occurs in following cases:

1. The load drives the motor, ie. the load generates energy.
2. During deceleration ("ramp-down") if the moment of inertia is high, the friction is low and the ramp-down time is too short for the energy to be dissipated as a loss in the frequency converter, the motor and the installation.
3. In-correct slip compensation setting may cause higher DC link voltage.

The control unit may attempt to correct the ramp if possible (par. 2-17 *Over-voltage Control*.
The inverter turns off to protect the transistors and the intermediate circuit capacitors when a certain voltage level is reached.
See par. 2-10 and par. 2-17 to select the method used for controlling the intermediate circuit voltage level.

High Temperature
High ambient temperature may overheat the frequency converter.

Mains Drop-out

During a mains drop-out, the frequency converter keeps running until the intermediate circuit voltage drops below the minimum stop level, which is typically 15% below the frequency converter's lowest rated supply voltage.

The mains voltage before the drop-out and the motor load determines how long it takes for the inverter to coast.

Static Overload in VVC^{plus} mode

When the frequency converter is overloaded (the torque limit in par. 4-16/4-17 is reached), the controls reduces the output frequency to reduce the load. If the overload is excessive, a current may occur that makes the frequency converter cut out after approx. 5-10 s.

Operation within the torque limit is limited in time (0-60 s) in par. 14-25.

2.15.1 Motor Thermal Protection

This is the way Danfoss is protecting the motor from being overheated. It is an electronic feature that simulates a bimetal relay based on internal measurements. The characteristic is shown in the following figure:

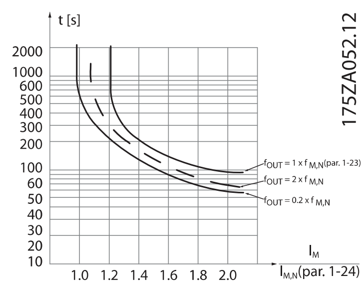


Illustration 2.6: The X-axis is showing the ratio between I_{motor} and I_{motor} nominal. The Y- axis is showing the time in seconds before the ETR cuts off and trips the drive. The curves are showing the characteristic nominal speed at twice the nominal speed and at 0,2x the nominal speed.

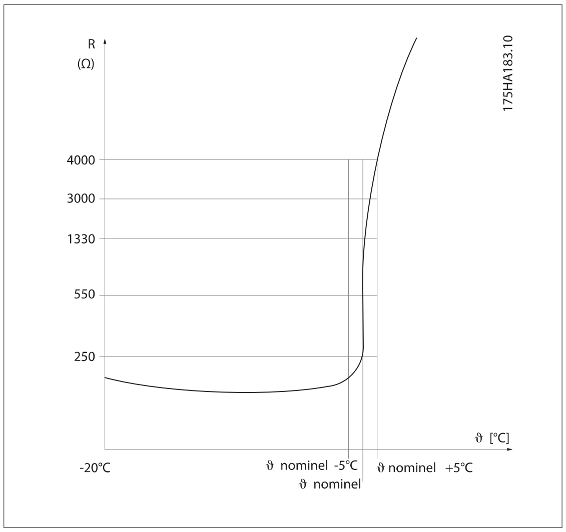
It is clear that at lower speed the ETR cuts of at lower heat due to less cooling of the motor. In that way the motor are protected from being over heated even at low speed. The ETR feature is calculating the motor temperature based on actual current and speed. The calculated temperature is visible as a read out parameter in par. 16-18 *Motor Thermal* in the frequency converter.

The thermistor cut-out value is > 3 kΩ.

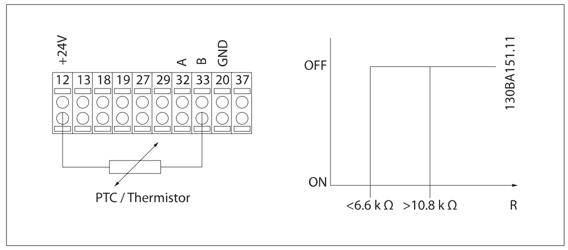
Integrate a thermistor (PTC sensor) in the motor for winding protection.

Motor protection can be implemented using a range of techniques: PTC sensor in motor windings; mechanical thermal switch (Klixon type); or Electronic Thermal Relay (ETR).

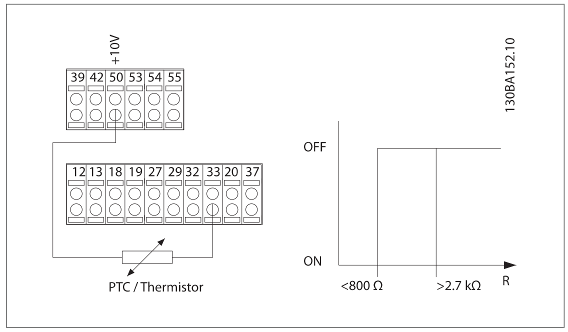
2


R
(Ω)
4000
3000
1330
550
250
-20°C
ϑ nominel -5°C
ϑ nominel
ϑ nominel +5°C
ϑ [°C]
175HA183.10

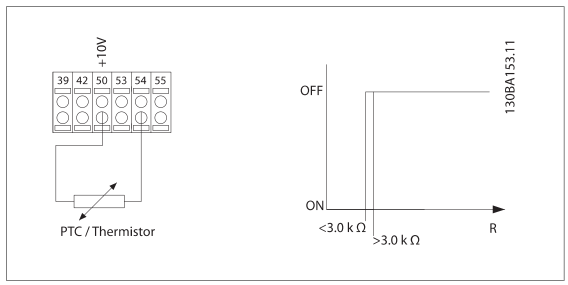
Using a digital input and 24 V as power supply:
Example: The frequency converter trips when the motor temperature is too high.
Parameter set-up:
Set par. 1-90 *Motor Thermal Protection* to *Thermistor Trip* [2]
Set par. 1-93 *Thermistor Source* to *Digital Input 33* [6]



Using a digital input and 10 V as power supply:
Example: The frequency converter trips when the motor temperature is too high.
Parameter set-up:
Set par. 1-90 *Motor Thermal Protection* to *Thermistor Trip* [2]
Set par. 1-93 *Thermistor Source* to *Digital Input 33* [6]



Using an analog input and 10 V as power supply:
Example: The frequency converter trips when the motor temperature is too high.
Parameter set-up:
Set par. 1-90 *Motor Thermal Protection* to *Thermistor Trip* [2]
Set par. 1-93 *Thermistor Source* to *Analog Input 54* [2]
Do not select a reference source.



Input	**Supply Voltage**	**Threshold**
Digital/analog	Volt	Cut-out Values
Digital	24 V	< 6.6 kΩ - > 10.8 kΩ
Digital	10 V	< 800Ω - > 2.7 kΩ
Analog	10 V	< 3.0 kΩ - > 3.0 kΩ

NB!
Check that the chosen supply voltage follows the specification of the used thermistor element.

Summary

With the Torque limit feature the motor is protected for being overloaded independent of the speed. With the ETR the motor is protected for being over heated and there is no need for any further motor protection. That means when the motor is heated up the ETR timer controls for how long time the motor can be running at the high temperature before it is stopped in order to prevent over heating. If the motor is overloaded without reaching the temperature where the ETR shuts of the motor, the torque limit is protecting the motor and application for being overloaded.

NB!

ETR is activated in par. and is controlled in par. 4-16 *Torque Limit Motor Mode*. The time before the torque limit warning trips the frequency converter is set in par. 14-25 *Trip Delay at Torque Limit*.

2.15.2 Safe Stop Operation (Optional)

The FC322 can perform the Safety Function "Uncontrolled Stopping by removal of power" (as defined by draft IEC 61800-5-2) or Stop Category 0 (as defined in EN 60204-1).
It is designed and approved suitable for the requirements of Safety Category 3 in EN 954-1. This functionality is called Safe Stop.
Prior to integration and use of FC322 Safe Stop in an installation, a thorough risk analysis on the installation must be carried out in order to determine whether the FC322 Safe Stop functionality and safety category are appropriate and sufficient.
The Safe Stop function is activated by removing the voltage at Terminal 37 of the Safe Inverter. By connecting the Safe Inverter to external safety devices providing a safe relay, an installation for a safe Stop Category 1 can be obtained. The Safe Stop function of FC322 can be used for asynchronous and synchronous motors.

Safe Stop activation (i.e. removal of 24 V DC voltage supply to terminal 37) does not provide electrical safety.

NB!
The Safe Stop function of FC322 can be used for asynchronous and synchronous motors. It may happen that two faults occur in the frequency converter's power semiconductor. When using synchronous motors this may cause a residual rotation. The rotation can be calculated to Angle=360/(Number of Poles). The application using synchronous motors must take this into consideration and ensure that this is not a safety critical issue. This situation is not relevant for asynchronous motors.

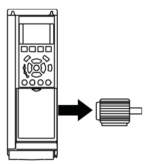
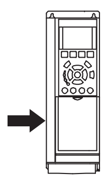
NB!
In order to use the Safe Stop functionality in conformance with the requirements of EN-954-1 Category 3, a number of conditions must be fulfilled by the installation of Safe Stop. Please see section *Safe Stop Installation* for further information.

NB!
The frequency converter does not provide a safety-related protection against unintended or malicious voltage supply to terminal 37 and subsequent reset. Provide this protection via the interrupt device, at the application level, or organisational level.
For more information - see section *Safe Stop Installation*.

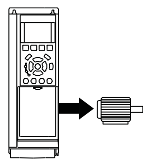
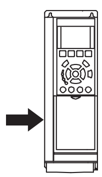
3 VLT Automation VT Drive Selection

3.1 General Specifications

3.1.1 Mains Supply 1 x 200 - 240 VAC

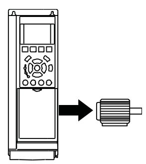
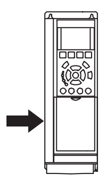
Mains Supply 1 x 200 - 240 VAC - Normal overload 110% for 1 minute										
Frequency converter Typical Shaft Output [kW]		P1K1 1.1	P1K5 1.5	P2K2 2.2	P3K0 3.0	P3K7 3.7	P5K5 5.5	P7K5 7.5	P15K0 15	P22K0 22
Typical Shaft Output [HP] at 240 V		1.5	2.0	2.9	4.0	4.9	7.5	10	20	30
IP 20 / Chassis		A3	-	-	-	-	-	-	-	-
IP 21 / NEMA 1		-	B1	B1	B1	B1	B1	B2	C1	C2
IP 55 / NEMA 12		A5	B1	B1	B1	B1	B1	B2	C1	C2
IP 66		A5	B1	B1	B1	B1	B1	B2	C1	C2
Output current										
	Continuous (3 x 200-240 V) [A]	6.6	7.5	10.6	12.5	16.7	24.2	30.8	59.4	88
	Intermittent (3 x 200-240 V) [A]	7.3	8.3	11.7	13.8	18.4	26.6	33.4	65.3	96.8
	Continuous kVA (208 V AC) [kVA]						5.00	6.40	12.27	18.30
	Max. cable size:									
	(mains, motor, brake) [[mm²/ AWG] 2)]	0.2-4 / 4-10					10/7	35/2	50/1/0	95/4/0
Max. input current										
	Continuous (1 x 200-240 V) [A]	12.5	15	20.5	24	32	46	59	111	172
	Intermittent (1 x 200-240 V) [A]	13.8	16.5	22.6	26.4	35.2	50.6	64.9	122.1	189.2
	Max. pre-fuses1)[A]	20	30	40	40	60	80	100	150	200
	Environment									
	Estimated power loss at rated max. load [W] 4)	44	30	44	60	74	110	150	300	440
	Weight enclosure IP 20 [kg]	4.9	-	-	-	-	-	-	-	-
	Weight enclosure IP 21 [kg]	-	23	23	23	23	23	27	45	65
	Weight enclosure IP 55 [kg]	-	23	23	23	23	23	27	45	65
	Weight enclosure IP 66 [kg]	-	23	23	23	23	23	27	45	65
	Efficiency 3)	0.968	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98

3.1.2 Mains Supply 3 x 200 - 240 VAC

Normal overload 110% for 1 minute										
IP 20 / NEMA Chassis		A2	A2	A2	A2	A2	A2	A2	A3	A3
IP 21 / NEMA 1		A2	A2	A2	A2	A2	A2	A2	A3	A3
IP 55 / NEMA 12		A5	A5	A5	A5	A5	A5	A5	A5	A5
IP 66		A5	A5	A5	A5	A5	A5	A5	A5	A5
Mains supply 200 - 240 VAC										
Frequency converter		PK25	PK37	PK55	PK75	P1K1	P1K5	P2K2	P3K0	P3K7
Typical Shaft Output [kW]		0.25	0.37	0.55	0.75	1.1	1.5	2.2	3	3.7
Typical Shaft Output [HP] at 208 V		0.25	0.37	0.55	0.75	1.5	2.0	2.9	4.0	4.9
Output current										
	Continuous (3 x 200-240 V) [A]	1.8	2.4	3.5	4.6	6.6	7.5	10.6	12.5	16.7
	Intermittent (3 x 200-240 V) [A]	1.98	2.64	3.85	5.06	7.26	8.3	11.7	13.8	18.4
	Continuous kVA (208 V AC) [kVA]	0.65	0.86	1.26	1.66	2.38	2.70	3.82	4.50	6.00
	Max. cable size: (mains, motor, brake) [mm^2 /AWG] 2)	0.2 - 4 mm^2 / 4 - 10 AWG								
Max. input current										
	Continuous (3 x 200-240 V) [A]	1.6	2.2	3.2	4.1	5.9	6.8	9.5	11.3	15.0
	Intermittent (3 x 200-240 V) [A]	1.7	2.42	3.52	4.51	6.5	7.5	10.5	12.4	16.5
	Max. pre-fuses1) [A]	10	10	10	10	20	20	20	32	32
	Environment									
	Estimated power loss at rated max. load [W] 4)	21	29	42	54	63	82	116	155	185
	Weight enclosure IP20 [kg]	4.9	4.9	4.9	4.9	4.9	4.9	4.9	6.6	6.6
	Weight enclosure IP21 [kg]	5.5	5.5	5.5	5.5	5.5	5.5	5.5	7.5	7.5
	Weight enclosure IP55 [kg]	13.5	13.5	13.5	13.5	13.5	13.5	13.5	13.5	13.5
	Weight enclosure IP 66 [kg]	13.5	13.5	13.5	13.5	13.5	13.5	13.5	13.5	13.5
	Efficiency 3)	0.94	0.94	0.95	0.95	0.96	0.96	0.96	0.96	0.96

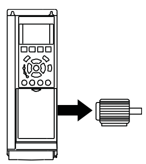
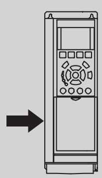
3

Mains supply 3 x 200 - 240 VAC - Normal overload 110% for 1 minute

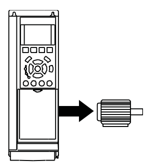
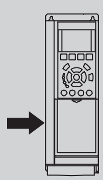
IP 20 / NEMA Chassis (B3+4 and C3+4 may be converted to IP21 using a conversion kit (Please contact Danfoss)		B3	B3	B3	B4	B4	C3	C3	C4	C4
IP 21 / NEMA 1		B1	B1	B1	B2	C1	C1	C1	C2	C2
IP 55 / NEMA 12		B1	B1	B1	B2	C1	C1	C1	C2	C2
IP 66		B1	B1	B1	B2	C1	C1	C1	C2	C2
Frequency converter		P5K5	P7K5	P11K	P15K	P18K	P22K	P30K	P37K	P45K
Typical Shaft Output [kW]		5.5	7.5	11	15	18.5	22	30	37	45
Typical Shaft Output [HP] at 208 V		7.5	10	15	20	25	30	40	50	60
Output current										
	Continuous (3 x 200-240 V) [A]	24.2	30.8	46.2	59.4	74.8	88.0	115	143	170
	Intermittent (3 x 200-240 V) [A]	26.6	33.9	50.8	65.3	82.3	96.8	127	157	187
	Continuous kVA (208 V AC) [kVA]	8.7	11.1	16.6	21.4	26.9	31.7	41.4	51.5	61.2
	Max. cable size:									
	(mains, motor, brake) [mm² /AWG] 2)		10/7		35/2		50/1/0		95/4/0	120/250 MCM
Max. input current										
	Continuous (3 x 200-240 V) [A]	22.0	28.0	42.0	54.0	68.0	80.0	104.0	130.0	154.0
	Intermittent (3 x 200-240 V) [A]	24.2	30.8	46.2	59.4	74.8	88.0	114.0	143.0	169.0
	Max. pre-fuses1) [A]	63	63	63	80	125	125	160	200	250
	Environment:									
	Estimated power loss at rated max. load [W] 4)	269	310	447	602	737	845	1140	1353	1636
	Weight enclosure IP20 [kg]	12	12	12	23.5	23.5	35	35	50	50
	Weight enclosure IP21 [kg]	23	23	23	27	45	45	65	65	65
	Weight enclosure IP55 [kg]	23	23	23	27	45	45	65	65	65
	Weight enclosure IP 66 [kg]	23	23	23	27	45	45	65	65	65
	Efficiency 3)	0.96	0.96	0.96	0.96	0.96	0.97	0.97	0.97	0.97

3

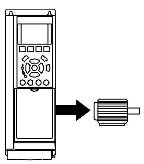
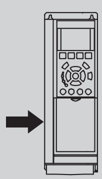
3.1.3 Mains Supply 1 x 380 - 480 VAC

Mains Supply 1x 380 VAC - Normal overload 110% for 1 minute					
Frequency converter		P7K5	P11K	P18K	P37K
Typical Shaft Output [kW]		7.5	11	18.5	37
Typical Shaft Output [HP] at 460 V		10	15	25	50
IP 21 / NEMA 1		B1	B2	C1	C2
IP 55 / NEMA 12		B1	B2	C1	C2
IP 66		B1	B2	C1	C2
Output current					
	Continuous (3 x 380-440 V) [A]	16	24	37.5	73
	Intermittent (3 x 380-440 V) [A]	17.6	26.4	41.2	80.3
	Continuous (3 x 441-480 V) [A]	14.5	21	34	65
	Intermittent (3 x 441-480 V) [A]	15.4	23.1	37.4	71.5
	Continuous kVA (400 V AC) [kVA]	11.0	16.6	26	50.6
	Continuous kVA (460 V AC) [kVA]	11.6	16.7	27.1	51.8
	Max. cable size: (mains, motor, brake) [[mm²/ AWG] 2)	10/7	35/2	50/1/0	120/4/0
Max. input current					
	Continuous (1 x 380-440 V) [A]	33	48	78	151
	Intermittent (1 x 380-440 V) [A]	36	53	85.8	166
	Continuous (1 x 441-480 V) [A]	30	41	72	135
	Intermittent (1 x 441-480 V) [A]	33	46	79.2	148
	Max. pre-fuses1)[A]	63	80	160	250
	Environment				
	Estimated power loss at rated max. load [W] 4)	300	440	740	1480
	Weight enclosure IP 21 [kg]	23	27	45	65
	Weight enclosure IP 55 [kg]	23	27	45	65
	Weight enclosure IP 66 [kg]	23	27	45	65
	Efficiency 3)	0.96	0.96	0.96	0.96

3.1.4 Mains Supply 3 x 380 - 480 VAC

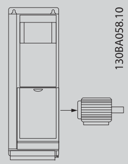
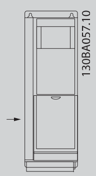
Mains Supply 3 x 380 - 480 VAC - Normal overload 110% for 1 minute										
Frequency converter	PK37	PK55	PK75	P1K1	P1K5	P2K2	P3K0	P4K0	P5K5	P7K5
Typical Shaft Output [kW]	0.37	0.55	0.75	1.1	1.5	2.2	3	4	5.5	7.5
Typical Shaft Output [HP] at 460 V	0.5	0.75	1.0	1.5	2.0	2.9	4.0	5.3	7.5	10
IP 20 / NEMA Chassis	A2	A2	A2	A2	A2	A2	A2	A2	A3	A3
IP 21 / NEMA 1										
IP 55 / NEMA 12	A5	A5	A5	A5	A5	A5	A5	A5	A5	A5
IP 66	A5	A5	A5	A5	A5	A5	A5	A5	AA	A5
Output current 										
Continuous (3 x 380-440 V) [A]	1.3	1.8	2.4	3	4.1	5.6	7.2	10	13	16
Intermittent (3 x 380-440 V) [A]	1.43	1.98	2.64	3.3	4.5	6.2	7.9	11	14.3	17.6
Continuous (3 x 441-480 V) [A]	1.2	1.6	2.1	2.7	3.4	4.8	6.3	8.2	11	14.5
Intermittent (3 x 441-480 V) [A]	1.32	1.76	2.31	3.0	3.7	5.3	6.9	9.0	12.1	15.4
Continuous kVA (400 V AC) [kVA]	0.9	1.3	1.7	2.1	2.8	3.9	5.0	6.9	9.0	11.0
Continuous kVA (460 V AC) [kVA]	0.9	1.3	1.7	2.4	2.7	3.8	5.0	6.5	8.8	11.6
Max. cable size: (mains, motor, brake) [[mm²/ AWG] 2)	4/10									
Max. input current 										
Continuous (3 x 380-440 V) [A]	1.2	1.6	2.2	2.7	3.7	5.0	6.5	9.0	11.7	14.4
Intermittent (3 x 380-440 V) [A]	1.32	1.76	2.42	3.0	4.1	5.5	7.2	9.9	12.9	15.8
Continuous (3 x 441-480 V) [A]	1.0	1.4	1.9	2.7	3.1	4.3	5.7	7.4	9.9	13.0
Intermittent (3 x 441-480 V) [A]	1.1	1.54	2.09	3.0	3.4	4.7	6.3	8.1	10.9	14.3
Max. pre-fuses1)[A]	10	10	10	10	10	20	20	20	30	30
Environment										
Estimated power loss at rated max. load [W] 4)	35	42	46	58	62	88	116	124	187	255
Weight enclosure IP20 [kg]	4.7	4.7	4.8	4.8	4.9	4.9	4.9	4.9	6.6	6.6
Weight enclosure IP 21 [kg]										
Weight enclosure IP 55 [kg]	13.5	13.5	13.5	13.5	13.5	13.5	13.5	13.5	14.2	14.2
Weight enclosure IP 66 [kg]	13.5	13.5	13.5	13.5	13.5	13.5	13.5	13.5	14.2	14.2
Efficiency 3)	0.93	0.95	0.96	0.96	0.97	0.97	0.97	0.97	0.97	0.97

Mains Supply 3 x 380 - 480 VAC - Normal overload 110% for 1 minute

Frequency converter Typical Shaft Output [kW]		P11K 11	P15K 15	P18K 18.5	P22K 22	P30K 30	P37K 37	P45K 45	P55K 55	P75K 75	P90K 90
Typical Shaft Output [HP] at 460 V		15	20	25	30	40	50	60	75	100	125
IP 20 / NEMA Chassis (B3+4 and C3+4 may be converted to IP21 using a conversion kit (Please contact Danfoss)		B3	B3	B3	B4	B4	B4	C3	C3	C4	C4
IP 21 / NEMA 1		B1	B1	B1	B2	B2	C1	C1	C1	C2	C2
IP 55 / NEMA 12		B1	B1	B1	B2	B2	C1	C1	C1	C2	C2
IP 66		B1	B1	B1	B2	B2	C1	C1	C1	C2	C2
Output current											
	Continuous (3 x 380-440 V) [A]	24	32	37.5	44	61	73	90	106	147	177
	Intermittent (3 x 380-440 V) [A]	26.4	35.2	41.3	48.4	67.1	80.3	99	117	162	195
	Continuous (3 x 441-480 V) [A]	21	27	34	40	52	65	80	105	130	160
	Intermittent (3 x 441-480 V) [A]	23.1	29.7	37.4	44	61.6	71.5	88	116	143	176
	Continuous kVA (400 V AC) [kVA]	16.6	22.2	26	30.5	42.3	50.6	62.4	73.4	102	123
	Continuous kVA (460 V AC) [kVA]	16.7	21.5	27.1	31.9	41.4	51.8	63.7	83.7	104	128
	Max. cable size: (mains, motor, brake) [[mm²/ AWG] 2)		10/7		35/2			50/1/0		120/4/0	120/4/0
Max. input current											
	Continuous (3 x 380-440 V) [A]	22	29	34	40	55	66	82	96	133	161
	Intermittent (3 x 380-440 V) [A]	24.2	31.9	37.4	44	60.5	72.6	90.2	106	146	177
	Continuous (3 x 441-480 V) [A]	19	25	31	36	47	59	73	95	118	145
	Intermittent (3 x 441-480 V) [A]	20.9	27.5	34.1	39.6	51.7	64.9	80.3	105	130	160
	Max. pre-fuses1)[A]	63	63	63	63	80	100	125	160	250	250
	Environment										
	Estimated power loss at rated max. load [W] 4)	278	392	465	525	698	739	843	1083	1384	1474
	Weight enclosure IP20 [kg]	12	12	12	23.5	23.5	23.5	35	35	50	50
	Weight enclosure IP 21 [kg]	23	23	23	27	27	45	45	45	65	65
	Weight enclosure IP 55 [kg]	23	23	23	27	27	45	45	45	65	65
	Weight enclosure IP 66 [kg]	23	23	23	27	27	45	45	45	65	65
	Efficiency 3)	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.99

3

Normal overload 110% for 1 minute

Frequency converter / Typical Shaft Output [kW] at 400V	P110 110	P132 132	P160 160	P200 200	P250 250	315	P400 400	P450 450	P500 500	P560 560	P630 630	P710 710	P800 800	P1M0 1000
Typical Shaft Output [HP] at 460V	150	200	250	300	350	450	550	600	650	750	900	1000	1200	1350
IP 00	D3	D3	D4	D4	D4	E2	E2	E2	F1/F3	F1/F3	F1/F3	F1/F3	F2/F4	F2/F4
IP 21 / Nema 1	D1	D1	D2	D2	D2	E1	E1	E1	F1/F3	F1/F3	F1/F3	F1/F3	F2/F4	F2/F4
IP 54 / Nema 12	D1	D1	D2	D2	D2	E1	E1	E1	F1/F3	F1/F3	F1/F3	F1/F3	F2/F4	F2/F4
Output current														
 Continuous (3 x 380-440 V) [A]	212	260	315	395	480	600	745	800	880	990	1120	1260	1460	1720
Intermittent (3 x 380-440 V) [A]	233	286	347	435	528	660	820	880	968	1089	1232	1386	1606	1892
Continuous (3 x 441-480V) [A]	190	240	302	361	443	540	678	730	780	890	1050	1160	1380	1530
Intermittent (3 x 441-480V) [A]	209	264	332	397	487	594	746	803	858	979	1155	1276	1518	1683
Continuous kVA (400 VAC) [kVA]	147	180	218	274	333	416	516	554	610	686	776	873	1012	1192
Continuous kVA (460 VAC) [kVA]	151	191	241	288	353	430	540	582	621	709	837	924	1100	1219
Max. cable size:														
(motor,) [mm²/ AWG[2]]	2x70 2x2/0		2x185 2x300 mcm			4x240 4x500 mcm			8x150 8x300 mcm				12x150 12x300 mcm	
(mains,) [mm²/ AWG[2]]	2x70 2x2/0		2x185 2x300 mcm			4x240 4x500 mcm			8x240 8x500 mcm					
(loadsharing) [mm²/ AWG[2]]	2x70 2x2/0		2x185 2x300 mcm			4x240 4x500 mcm			4x120 4x250 mcm					
(brake) [mm²/ AWG[2]]	2x70 2x2/0		2x185 2x300 mcm			2x185 2x350 mcm			4x185 4x350 mcm				6x185 6x350 mcm	
Max. input current														
 Continuous (3 x 380-440 V) [A]	204	251	304	381	463	590	733	787	857	964	1090	1227	1422	1675
Continuous (3 x 441-480V) [A]	183	231	291	348	427	531	667	718	759	867	1022	1129	1344	1490
Max. pre-fuses[1][A]	300	350	400	500	630	700	900	900	1600	1600	2000	2000	2500	2500
Environment:														
Estimated power loss at 400 VAC at rated max. load [W] [4]	3234	3782	4213	5119	5893	6790	8879	9670	10647	12338	13201	15436	18084	20358
Estimated power loss at 460 VAC at rated max. load [W] [4]	2947	3665	4063	4652	5634	6082	8089	8803	9414	11006	12353	14041	17137	17752
Weight enclosure IP00 [kg]	82	91	112	123	138	221	236	277	-	-	-	-	-	-
Weight enclosure IP 21 [kg]	96	104	125	136	151	263	272	313	1004	1004	1004	1004	1246	1246
Weight enclosure IP 54 [kg]	96	104	125	136	151	263	272	313	1299	1299	1299	1299	1541	1541
Efficiency [3]	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98

[1] For type of fuse see section *Fuses*
[2] American Wire Gauge
[3] Measured using 5 m screened motor cables at rated load and rated frequency
[4] The typical power loss is at normal load conditions and expected to be within +/- 15% (tolerance relates to variety in voltage and cable conditions).
Values are based on a typical motor efficiency (eff2/eff3 border line). Lower efficiency motors will also add to the power loss in the frequency converter and vice versa.
If the switching frequency is raised from nominal the power losses may rise significantly.
LCP and typical control card power consumptions are included. Further options and customer load may add up to 30 Watts to the losses. (Though typically only 4 Watts extra for a fully loaded control card or options for slot A or slot B, each).
Although measurements are made with state of the art equipment, some measurement inaccuracy must be allowed for (+/- 5%).

3.1.5 Mains Supply 3 x 525 - 600 VAC

Normal overload 110% for 1 minute																		
Size:	PK75	P1K1	P1K5	P2K2	P3K0	P4K0	P5K5	P7K5	P11K	P15K	P18K	P22K	P30K	P37K	P45K	P55K	P75K	P90K
Typical Shaft Output [kW]	0.75	1.1	1.5	2.2	3	4	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90
IP 20 / NEMA Chassis	A2	A2	A2	A2	A2	A2	A3	A3	B3	B3	B3	B4	B4	B4	C3	C3	C4	C4
IP 21 / NEMA 1	A2	A2	A2	A2	A2	A2	A3	A3	B1	B1	B1	B2	B2	B2	C1	C1	C2	C2
IP 55 / NEMA 12	A5	A5	A5	A5	A5	A5	A5	A5	B1	B1	B1	B2	B2	B2	C1	C1	C2	C2
IP 66	A5	A5	A5	A5	A5	A5	A5	A5	B1	B1	B1	B2	B2	B2	C1	C1	C2	C2
Output current																		
Continuous (3 x 525-550 V) [A]	1.8	2.6	2.9	4.1	5.2	6.4	9.5	11.5	19	23	28	36	43	54	65	87	105	137
Intermittent (3 x 525-550 V) [A]		2.9	3.2	4.5	5.7	7.0	10.5	12.7	21	25	31	40	47	59	72	96	116	151
Continuous (3 x 525-600 V) [A]	1.7	2.4	2.7	3.9	4.9	6.1	9.0	11.0	18	22	27	34	41	52	62	83	100	131
Intermittent (3 x 525-600 V) [A]		2.6	3.0	4.3	5.4	6.7	9.9	12.1	20	24	30	37	45	57	68	91	110	144
Continuous kVA (525 V AC) [kVA]	1.7	2.5	2.8	3.9	5.0	6.1	9.0	11.0	18.1	21.9	26.7	34.3	41	51.4	61.9	82.9	100	130.5
Continuous kVA (575 V AC) [kVA]	1.7	2.4	2.7	3.9	4.9	6.1	9.0	11.0	17.9	21.9	26.9	33.9	40.8	51.8	61.7	82.7	99.6	130.5
Max. cable size (mains, motor, brake) [AWG] 2) [mm²]	24 - 10 AWG 0.2 - 4								6 16			2 35			1 50		3/0 95 5)	
Max. input current																		
Continuous (3 x 525-600 V) [A]	1.7	2.4	2.7	4.1	5.2	5.8	8.6	10.4	17.2	20.9	25.4	32.7	39	49	59	78.9	95.3	124.3
Intermittent (3 x 525-600 V) [A]		2.7	3.0	4.5	5.7	6.4	9.5	11.5	19	23	28	36	43	54	65	87	105	137
Max. pre-fuses1) [A]	10	10	10	20	20	20	32	32	40	40	50	60	80	100	150	160	225	250
Environment:																		
Estimated power loss at rated max. load [W] 4)	35	50	65	92	122	145	195	261	225	285	329	460	560	740	860	890	1020	1130
Weight [kg]:																		
Enclosure IP20	6.5	6.5	6.5	6.5	6.5	6.5	6.6	6.6	12	12	12	23.5	23.5	23.5	35	35	50	50
Efficiency 4)	0.97	0.97	0.97	0.97	0.97	0.97	0.97	0.97	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98

Table 3.1: 5) Motor and mains cable: 300MCM/150mm²

3

3.1.6 Mains Supply 3 x 525 - 690 VAC

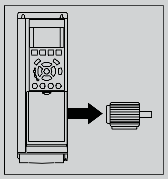
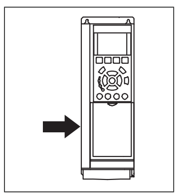
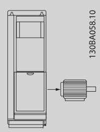
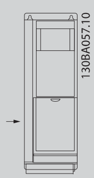
		Normal overload 110% for 1 minute									
Size:		P11K	P15K	P18K	P22K	P30K	P37K	P45K	P55K	P75K	P90K
Typical Shaft Output [kW]		11	15	18.5	22	30	37	45	55	75	90
Typical Shaft Output [HP] at 575 V		10	16.4	20.1	24	33	40	50	60	75	100
IP 21 / NEMA 1		B2	B2	B2	B2	B2	C2	C2	C2	C2	C2
IP 55 / NEMA 12		B2	B2	B2	B2	B2	C2	C2	C2	C2	C2
Output current											
	Continuous (3 x 525-550 V) [A]	14	19	23	28	36	43	54	65	87	105
	Intermittent (3 x 525-550 V) [A]	15.4	20.9	25.3	30.8	39.6	47.3	59.4	71.5	95.7	115.5
	Continuous (3 x 551-690 V) [A]	13	18	22	27	34	41	52	62	83	100
	Intermittent (3 x 551-690 V) [A]	14.3	19.8	24.2	29.7	37.4	45.1	57.2	68.2	91.3	110
	Continuous kVA (550 V AC) [kVA]	13.3	18.1	21.9	26.7	34.3	41	51.4	61.9	82.9	100
	Continuous kVA (575 V AC) [kVA]	12.9	17.9	21.9	26.9	33.8	40.8	51.8	61.7	82.7	99.6
	Continuous kVA (690 V AC) [kVA]	15.5	21.5	26.3	32.3	40.6	49	62.1	74.1	99.2	119.5
	Max. cable size (mains, motor, brake) [mm²]/[AWG] [2]			35 1/0					95 4/0		
Max. input current											
	Continuous (3 x 525-690 V) [A]	15	19.5	24	29	36	49	59	71	87	99
	Intermittent (3 x 525-690 V) [A]	16.5	21.5	26.4	31.9	39.6	53.9	64.9	78.1	95.7	108.9
	Max. pre-fuses[1] [A]	60	60	60	60	60	150	150	150	150	150
	Environment:										
	Estimated power loss at rated max. load [W] [4]	201	285	335	375	430	592	720	880	1200	1440
	Weight:										
	IP21 [kg]	27	27	27	27	27	65	65	65	65	65
	IP55 [kg]	27	27	27	27	27	65	65	65	65	65
	Efficiency [4]	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98

Table 3.2: [5] Motor and mains cable: 300MCM/150mm²

3.1.7 Mains Supply 3 x 525 - 690 VAC

Normal overload 110% for 1 minute																					
Frequency converter		P45K	P55K	P75K	P90K	P110	P132	P160	P200	P250	P315	P400	P450	P500	P560	P630	P710	P800	P900	P1M0	P1M2
Typical Shaft Output [kW]		45	55	75	90	110	132	160	200	250	315	400	450	500	560	630	710	800	900	1000	1200
Typical Shaft Output [HP] at 575 V		50	60	75	100	125	150	200	250	300	350	400	450	500	600	650	750	950	1050	1150	1350
IP 00		D3	D3	D3	D3	D3	D3	D3	D4	D4	D4	D4	E2	E2	E2	E2	-	-	-	-	-
IP 21 / Nema 1		D1	D1	D1	D1	D1	D1	D1	D2	D2	D2	D2	E1	E1	E1	E1	F1/ F3 6)	F1/ F3 6)	F1/ F3 6)	F2/ F4 6)	F2/ F4 6)
IP 54 / Nema 12		D1	D1	D1	D1	D1	D1	D1	D2	D2	D2	D2	E1	E1	E1	E1	F1/ F3 6)	F1/ F3 6)	F1/ F3 6)	F1/ F3 6)	F1/ F3 6)
Output current																					
	Continuous (3 x 550 V) [A]	56	76	90	113	137	162	201	253	303	360	418	470	523	596	630	763	889	988	1108	1317
	Intermittent (3 x 550 V) [A]	62	84	99	124	151	178	221	278	333	396	460	517	575	656	693	839	978	1087	1219	1449
	Continuous (3 x 690V) [A]	54	73	86	108	131	155	192	242	290	344	400	450	500	570	630	730	850	945	1060	1260
	Intermittent (3 x 690 V) [A]	59	80	95	119	144	171	211	266	319	378	440	495	550	627	693	803	935	1040	1166	1386
	Continuous kVA (550 VAC) [kVA]	53	72	86	108	131	154	191	241	289	343	398	448	498	568	600	727	847	941	1056	1255
	Continuous kVA (575 VAC) [kVA]	54	73	86	108	130	154	191	241	289	343	398	448	498	568	627	727	847	941	1056	1255
	Continuous kVA (690 VACr) [kVA]	65	87	103	129	157	185	229	289	347	411	478	538	598	681	753	872	1016	1129	1267	1506
	Max. cable size:																				
	(Mains) [mm2/ AWG] 2)	2x70 2x2/0							2x185 2x300 mcm				4x240 4x500 mcm				8x240 8x500 mcm			8x240 8x500 mcm	
	(Motor) [mm2/ AWG] 2)	2x70 2x2/0							2x185 2x300 mcm				4x240 4x500 mcm				8x150 8x300 mcm			12x150 12x300 mcm	
	(Brake) [mm2/ AWG] 2)	2x70 2x2/0							2x185 2x300 mcm				2x185 2x350 mcm				4x185 4x350 mcm			6x185 6x350 mcm	
Max. input current																					
	Continuous (3 x 550 V) [A]	60	77	89	110	130	158	198	245	299	355	408	453	504	574	607	743	866	962	1079	1282
	Continuous (3 x 575 V) [A]	58	74	85	106	124	151	189	224	286	339	390	434	482	549	607	711	828	920	1032	1227
	Continuous (3 x 690 V) [A]	58	77	87	109	128	155	197	240	296	352	400	434	482	549	607	711	828	920	1032	1227
	Max. mains pre-fuses1)[A]	125	160	200	200	250	315	350	350	400	500	550	700	700	900	900	2000	2000	2000	2000	2000
	Environment:																				
	Estimated power loss at 690 VAC at rated max. load [W] 4)	1458	1717	1913	2262	2662	3430	3612	4292	5156	5821	6149	6440	7249	8727	9673	11315	12903	14533	16375	19207
	Estimated power loss at 575 VAC at rated max. load [W] 4)	1398	1645	1827	2157	2533	2963	3430	4051	4867	5493	5852	6132	6903	8343	9244	10771	12272	13835	15592	18281
	Weight enclosure IP00 [kg]	82	82	82	82	82	82	91	112	123	138	151	221	221	236	277	-	-	-	-	-
	Weight enclosure IP 21 [kg] 6)	96	96	96	96	96	96	104	125	136	151	165	263	263	272	313	1004	1004	1004	1246	1246
	Weight enclosure IP 54 [kg] 6)	96	96	96	96	96	96	104	125	136	151	165	263	263	272	313	1004	1004	1004	1246	1246
	Efficiency 3)	0.97	0.97	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98	0.98

1) For type of fuse see section *Fuses*

2) American Wire Gauge

3) Measured using 5 m screened motor cables at rated load and rated frequency

4) The typical power loss is at normal load conditions and expected to be within +/- 15% (tolerance relates to variety in voltage and cable conditions). Values are based on a typical motor efficiency (eff2/eff3 border line). Lower efficiency motors will also add to the power loss in the frequency converter and vice versa.
If the switching frequency is raised from nominal the power losses may rise significantly. LCP and typical control card power consumptions are included. Further options and customer load may add up to 30 [W] to the losses. (Though typically only 4 [W] extra for a fully loaded control card, or options for slot A or slot B, each).
Although measurements are made with state of the art equipment, some measurement inaccuracy must be allowed for (+/- 5%).

6) Adding the F-enclosure option cabinet (resulting in the F3 and F4 enclosure sizes) adds 295 kg to the estimated weight.

Protection and Features:

- Electronic thermal motor protection against overload.
- Temperature monitoring of the heatsink ensures that the frequency converter trips if the temperature reaches 95 °C ± 5°C. An overload temperature cannot be reset until the temperature of the heatsink is below 70 °C ± 5°C (Guideline - these temperatures may vary for different power sizes, enclosures etc.). VLT Automation VT Drive Drive has an auto derating function to avoid it's heatsink reaching 95 °C.
- The frequency converter is protected against short-circuits on motor terminals U, V, W.
- If a mains phase is missing, the frequency converter trips or issues a warning (depending on the load).
- Monitoring of the intermediate circuit voltage ensures that the frequency converter trips if the intermediate circuit voltage is too low or too high.
- The frequency converter is protected against earth faults on motor terminals U, V, W.

Mains supply (L1, L2, L3):

Supply voltage	200-240 V ±10%
Supply voltage	380-480 V ±10%
Supply voltage	525-600 V ±10%
Supply voltage	525-690 V ±10%

Mains voltage low / mains drop-out:

During low mains voltage or a mains drop-out, the FC continues until the intermediate circuit voltage drops below the minimum stop level, which corresponds typically to 15% below the FC's lowest rated supply voltage. Power-up and full torque cannot be expected at mains voltage lower than 10% below the FC's lowest rated supply voltage.

Supply frequency	50/60 Hz +4/-6%

The frequency converter power supply is tested in accordance with IEC61000-4-28, 50 Hz +4/-6%.

Max. imbalance temporary between mains phases	3.0 % of rated supply voltage
True Power Factor (λ)	≥ 0.9 nominal at rated load
Displacement Power Factor (cosφ) near unity	(> 0.98)
Switching on input supply L1, L2, L3 (power-ups) ≤ enclosure type A	maximum 2 times/min.
Switching on input supply L1, L2, L3 (power-ups) ≥ enclosure type B, C	maximum 1 time/min.
Switching on input supply L1, L2, L3 (power-ups) ≥ enclosure type D, E, F	maximum 1 time/2 min.
Environment according to EN60664-1	overvoltage category III/pollution degree 2

The unit is suitable for use on a circuit capable of delivering not more than 100.000 RMS symmetrical Amperes, 240/480 V maximum.

Motor output (U, V, W):

Output voltage	0 - 100% of supply voltage
Output frequency	0 - 1000 Hz*
Switching on output	Unlimited
Ramp times	1 - 3600 sec.

** Dependent on power size.*

Torque characteristics:

Starting torque (Constant torque)	maximum 110% for 1 min.*
Starting torque	maximum 135% up to 0.5 sec.*
Overload torque (Constant torque)	maximum 110% for 1 min.*

**Percentage relates to VLT Automation VT Drive's nominal torque.*

Cable lengths and cross sections:

Max. motor cable length, screened/armoured	VLT Automation VT Drive: 150 m
Max. motor cable length, unscreened/unarmoured	VLT Automation VT Drive: 300 m
Max. cross section to motor, mains, load sharing and brake *	
Maximum cross section to control terminals, rigid wire	1.5 mm^2/16 AWG (2 x 0.75 mm^2)
Maximum cross section to control terminals, flexible cable	1 mm^2/18 AWG
Maximum cross section to control terminals, cable with enclosed core	0.5 mm^2/20 AWG
Minimum cross section to control terminals	0.25 mm^2

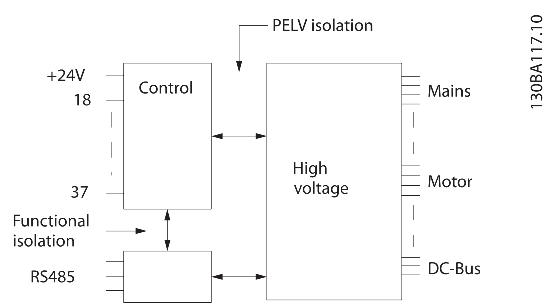
** See Mains Supply tables for more information!*

Control card, RS-485 serial communication:	
Terminal number	68 (P,TX+, RX+), 69 (N,TX-, RX-)
Terminal number 61	Common for terminals 68 and 69

The RS-485 serial communication circuit is functionally separated from other central circuits and galvanically isolated from the supply voltage (PELV).

Analog inputs:	
Number of analog inputs	2
Terminal number	53, 54
Modes	Voltage or current
Mode select	Switch S201 and switch S202
Voltage mode	Switch S201/switch S202 = OFF (U)
Voltage level	: 0 to + 10 V (scaleable)
Input resistance, R_i	approx. 10 kΩ
Max. voltage	± 20 V
Current mode	Switch S201/switch S202 = ON (I)
Current level	0/4 to 20 mA (scaleable)
Input resistance, R_i	approx. 200 Ω
Max. current	30 mA
Resolution for analog inputs	10 bit (+ sign)
Accuracy of analog inputs	Max. error 0.5% of full scale
Bandwidth	: 200 Hz

The analog inputs are galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.



Analog output:	
Number of programmable analog outputs	1
Terminal number	42
Current range at analog output	0/4 - 20 mA
Max. resistor load to common at analog output	500 Ω
Accuracy on analog output	Max. error: 0.8 % of full scale
Resolution on analog output	8 bit

The analog output is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

Digital inputs:	
Programmable digital inputs	4 (6)
Terminal number	18, 19, 27 1), 29 1), 32, 33,
Logic	PNP or NPN
Voltage level	0 - 24 V DC
Voltage level, logic'0' PNP	< 5 V DC
Voltage level, logic'1' PNP	> 10 V DC
Voltage level, logic '0' NPN	> 19 V DC
Voltage level, logic '1' NPN	< 14 V DC
Maximum voltage on input	28 V DC
Input resistance, R_i	approx. 4 k

All digital inputs are galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

1) Terminals 27 and 29 can also be programmed as output.

Digital output:	
Programmable digital/pulse outputs	2
Terminal number	27, 29 [1)]
Voltage level at digital/frequency output	0 - 24 V
Max. output current (sink or source)	40 mA
Max. load at frequency output	1 kΩ
Max. capacitive load at frequency output	10 nF
Minimum output frequency at frequency output	0 Hz
Maximum output frequency at frequency output	32 kHz
Accuracy of frequency output	Max. error: 0.1 % of full scale
Resolution of frequency outputs	12 bit

1) Terminal 27 and 29 can also be programmed as input.

The digital output is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

Pulse inputs:	
Programmable pulse inputs	2
Terminal number pulse	29, 33
Max. frequency at terminal, 29, 33	110 kHz (Push-pull driven)
Max. frequency at terminal, 29, 33	5 kHz (open collector)
Min. frequency at terminal 29, 33	4 Hz
Voltage level	see section on Digital input
Maximum voltage on input	28 V DC
Input resistance, R_i	approx. 4 kΩ
Pulse input accuracy (0.1 - 1 kHz)	Max. error: 0.1% of full scale

Control card, 24 V DC output:	
Terminal number	12, 13
Max. load	: 200 mA

The 24 V DC supply is galvanically isolated from the supply voltage (PELV), but has the same potential as the analog and digital inputs and outputs.

Relay outputs:	
Programmable relay outputs	2
Relay 01 Terminal number	1-3 (break), 1-2 (make)
Max. terminal load (AC-1)[1)] on 1-3 (NC), 1-2 (NO) (Resistive load)	240 V AC, 2 A
Max. terminal load (AC-15)[1)] (Inductive load @ cosφ 0.4)	240 V AC, 0.2 A
Max. terminal load (DC-1)[1)] on 1-2 (NO), 1-3 (NC) (Resistive load)	60 V DC, 1A
Max. terminal load (DC-13)[1)] (Inductive load)	24 V DC, 0.1A
Relay 02 Terminal number	4-6 (break), 4-5 (make)
Max. terminal load (AC-1)[1)] on 4-5 (NO) (Resistive load)[2)3)]	400 V AC, 2 A
Max. terminal load (AC-15)[1)] on 4-5 (NO) (Inductive load @ cosφ 0.4)	240 V AC, 0.2 A
Max. terminal load (DC-1)[1)] on 4-5 (NO) (Resistive load)	80 V DC, 2 A
Max. terminal load (DC-13)[1)] on 4-5 (NO) (Inductive load)	24 V DC, 0.1A
Max. terminal load (AC-1)[1)] on 4-6 (NC) (Resistive load)	240 V AC, 2 A
Max. terminal load (AC-15)[1)] on 4-6 (NC) (Inductive load @ cosφ 0.4)	240 V AC, 0.2A
Max. terminal load (DC-1)[1)] on 4-6 (NC) (Resistive load)	50 V DC, 2 A
Max. terminal load (DC-13)[1)] on 4-6 (NC) (Inductive load)	24 V DC, 0.1 A
Min. terminal load on 1-3 (NC), 1-2 (NO), 4-6 (NC), 4-5 (NO)	24 V DC 10 mA, 24 V AC 20 mA
Environment according to EN 60664-1	overvoltage category III/pollution degree 2

1) IEC 60947 part 4 and 5

The relay contacts are galvanically isolated from the rest of the circuit by reinforced isolation (PELV).

2) Overvoltage Category II

3) UL applications 300 V AC 2A

Control card, 10 V DC output:

Terminal number	50
Output voltage	10.5 V ±0.5 V
Max. load	25 mA

The 10 V DC supply is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

Control characteristics:

Resolution of output frequency at 0 - 1000 Hz	: +/- 0.003 Hz
System response time (terminals 18, 19, 27, 29, 32, 33)	: ≤ 2 ms
Speed control range (open loop)	1:100 of synchronous speed
Speed accuracy (open loop)	30 - 4000 rpm: Maximum error of ±8 rpm

All control characteristics are based on a 4-pole asynchronous motor

Surroundings:

Enclosure type A	IP 20/Chassis, IP 21kit/Type 1, IP55/Type12, IP 66
Enclosure type B1/B2	IP 21/Type 1, IP55/Type12, IP 66
Enclosure type B3/B4	IP20/Chassis
Enclosure type C1/C2	IP 21/Type 1, IP55/Type 12, IP66
Enclosure type C3/C4	IP20/Chassis
Enclosure type D1/D2/E1	IP21/Type 1, IP54/Type12
Enclosure type D3/D4/E2	IP00/Chassis
Enclosure kit available ≤ enclosure type A	IP21/TYPE 1/IP 4X top
Vibration test enclosure A/B/C	1.0 g
Vibration test enclosure D/E/F	0.7 g
Max. relative humidity	5% - 95%(IEC 721-3-3; Class 3K3 (non-condensing) during operation
Aggressive environment (IEC 721-3-3), uncoated	class 3C2
Aggressive environment (IEC 721-3-3), coated	class 3C3
Test method according to IEC 60068-2-43 H2S (10 days)	
Ambient temperature	Max. 50 °C

Derating for high ambient temperature, see section on special conditions

Minimum ambient temperature during full-scale operation	0 °C
Minimum ambient temperature at reduced performance	- 10 °C
Temperature during storage/transport	-25 - +65/70 °C
Maximum altitude above sea level without derating	1000 m
Maximum altitude above sea level with derating	3000 m

Derating for high altitude, see section on special conditions

EMC standards, Emission	EN 61800-3, EN 61000-6-3/4, EN 55011, IEC 61800-3
EMC standards, Immunity	EN 61800-3, EN 61000-6-1/2, EN 61000-4-2, EN 61000-4-3, EN 61000-4-4, EN 61000-4-5, EN 61000-4-6

See section on special conditions

Control card performance:

Scan interval	: 5 ms

Control card, USB serial communication:

USB standard	1.1 (Full speed)
USB plug	USB type B "device" plug

Connection to PC is carried out via a standard host/device USB cable.
The USB connection is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.
The USB connection is <u>not</u> galvanically isolated from protection earth. Use only isolated laptop/PC as connection to the USB connector on VLT Automation VT Drive or an isolated USB cable/converter.

3.2 Efficiency

Efficiency of VLT Automation VT Drive (η_{VLT})

The load on the frequency converter has little effect on its efficiency. In general, the efficiency is the same at the rated motor frequency $f_{M,N}$, even if the motor supplies 100% of the rated shaft torque or only 75%, i.e. in case of part loads.

This also means that the efficiency of the frequency converter does not change even if other U/f characteristics are chosen.
However, the U/f characteristics influence the efficiency of the motor.

The efficiency declines a little when the switching frequency is set to a value of above 5 kHz. The efficiency will also be slightly reduced if the mains voltage is 480 V, or if the motor cable is longer than 30 m.

Efficiency of the motor (η)$_{MOTOR}$

The efficiency of a motor connected to the frequency converter depends on magnetising level. In general, the efficiency is just as good as with mains operation. The efficiency of the motor depends on the type of motor.

In the range of 75-100% of the rated torque, the efficiency of the motor is practically constant, both when it is controlled by the frequency converter and when it runs directly on mains.

In small motors, the influence from the U/f characteristic on efficiency is marginal. However, in motors from 11 kW and up, the advantages are significant.

In general, the switching frequency does not affect the efficiency of small motors. Motors from 11 kW and up have their efficiency improved (1-2%). This is because the sine shape of the motor current is almost perfect at high switching frequency.

Efficiency of the system (η_{SYSTEM}

To calculate the system efficiency, the efficiency of VLT Automation VT Drive (η_{VLT}) is multiplied by the efficiency of the motor (η_{MOTOR}):

η_{SYSTEM}) = $\eta_{VLT} \times \eta_{MOTOR}$

Calculate the efficiency of the system at different loads based on the graph above.

3

3.3 Acoustic Noise

The acoustic noise from the frequency converter comes from three sources:

1. DC intermediate circuit coils.
2. Integral fan.
3. RFI filter choke.

The typical values measured at a distance of 1 m from the unit:

Enclosure	At reduced fan speed (50%) [dBA] ***	Full fan speed [dBA]
A2	51	60
A3	51	60
A5	54	63
B1	61	67
B2	58	70
B3	59.4	70.5
B4	53	62.8
C1	52	62
C2	55	65
C3	56.4	67.3
C4	-	-
D1+D3	74	76
D2+D4	73	74
E1/E2 *	73	74
E1/E2 **	82	83
F1/F2/F3/F4	78	80

* 315 kW, 380-480 VAC and 450/500 kW, 525-690 VAC only!

** Remaining E1+E2 power sizes.

*** For D, E and F sizes, reduced fan speed is at 87%, measured at 200 V.

3.4 Peak Voltage on Motor

When a transistor in the inverter bridge switches, the voltage across the motor increases by a du/dt ratio depending on:

- the motor cable (type, cross-section, length screened or unscreened)
- inductance

The natural induction causes an overshoot U_{PEAK} in the motor voltage before it stabilizes itself at a level depending on the voltage in the intermediate circuit. The rise time and the peak voltage U_{PEAK} affect the service life of the motor. If the peak voltage is too high, especially motors without phase coil insulation are affected. If the motor cable is short (a few metres), the rise time and peak voltage are lower.
If the motor cable is long (100 m), the rise time and peak voltage increases.

In motors without phase insulation paper or other insulation reinforcement suitable for operation with voltage supply (such as a frequency converter), fit a sine-wave filter on the output of the frequency converter.

To obtain approximate values for cable lengths and voltages not mentioned below, use the following rules of thumb:

1.	Rise time increases/decreases proportionally with cable length.
2.	U_{PEAK} = DC link voltage x 1.9 (DC link voltage = Mains voltage x 1.35).
3.	$dU / dt = \frac{0.8 \times U_{PEAK}}{Risetime}$

3

Data are measured according to IEC 60034-17.
Cable lengths are in metres.

FC322, P7K5T2

Cable length [m]	Mains voltage [V]	Rise time [µsec]	Vpeak [kV]	dU/dt [kV/µsec]
5	230	0.13	0.510	3.090
50	230	0.23		2.034
100	230	0.54	0.580	0.865
150	230	0.66	0.560	0.674

FC322, P11KT2

Cable length [m]	Mains voltage [V]	Rise time [µsec]	Vpeak [kV]	dU/dt [kV/µsec]
36	240	0.264	0.624	1.890
136	240	0.536	0.596	0.889
150	240	0.568	0.568	0.800

FC322, P15KT2

Cable length [m]	Mains voltage [V]	Rise time [µsec]	Vpeak [kV]	dU/dt [kV/µsec]
30	240	0.556	0.650	0.935
100	240	0.592	0.594	0.802
150	240	0.708	0.587	0.663

FC322, P18KT2

Cable length [m]	Mains voltage [V]	Rise time [µsec]	Vpeak [kV]	dU/dt [kV/µsec]
36	240	0.244	0.608	1.993
136	240	0.568	0.580	0.816
150	240	0.720	0.574	0.637

FC322, P22KT2

Cable length [m]	Mains voltage [V]	Rise time [µsec]	Vpeak [kV]	dU/dt [kV/µsec]
36	240	0.244	0.608	1.993
136	240	0.568	0.580	0.816
150	240	0.720	0.574	0.637

FC322, P30KT2

Cable length [m]	Mains voltage [V]	Rise time [µsec]	Vpeak [kV]	dU/dt [kV/µsec]
15	240	0.194	0.626	2.581
50	240	0.252	0.574	1.822
150	240	0.488	0.538	0.882

FC322, P37KT2

Cable length [m]	Mains voltage [V]	Rise time [µsec]	Vpeak [kV]	dU/dt [kV/µsec]
30	240	0.300	0.598	1.594
100	240	0.536	0.566	0.844
150	240	0.776	0.546	0.562

FC322, P45KT2

Cable length [m]	Mains voltage [V]	Rise time [µsec]	Vpeak [kV]	dU/dt [kV/µsec]
30	240	0.300	0.598	1.594
100	240	0.536	0.566	0.844
150	240	0.776	0.546	0.562

FC322, P1K5T4

Cable length [m]	Mains voltage [V]	Rise time [µsec]	Vpeak [kV]	dU/dt [kV/µsec]
5	690	0.640	0.690	0.862
50	985	0.470		0.985
150	1045	0.760	1.045	0.947

FC322, P4K0T4

Cable length [m]	Mains voltage [V]	Rise time [µsec]	Vpeak [kV]	dU/dt [kV/µsec]
5	400	0.172	0.890	4.156
50	400	0.310		2.564
150	400	0.370	1.190	1.770

FC322, P7K5T4

Cable length [m]	Mains voltage [V]	Rise time [µsec]	Vpeak [kV]	dU/dt [kV/µsec]
5	500	0.04755	0.739	8.035
50	500	0.207		4.548
150	500	0.6742	1.030	2.828

FC322, P11KT4

Cable length [m]	Mains voltage [V]	Rise time [µsec]	Vpeak [kV]	dU/dt [kV/µsec]
15	480	0.192	1.300	5.416
100	480	0.612	1.300	1.699
150	480	0.512	1.290	2.015

FC322, P15KT4

Cable length [m]	Mains voltage [V]	Rise time [µsec]	Vpeak [kV]	dU/dt [kV/µsec]
36	480	0.396	1.210	2.444
100	480	0.844	1.230	1.165
150	480	0.696	1.160	1.333

FC322, P18KT4

Cable length [m]	Mains voltage [V]	Rise time [μsec]	Vpeak [kV]	dU/dt [kV/μsec]
36	480	0.396	1.210	2.444
100	480	0.844	1.230	1.165
150	480	0.696	1.160	1.333

FC322, P22KT4

Cable length [m]	Mains voltage [V]	Rise time [μsec]	Vpeak [kV]	dU/dt [kV/μsec]
36	480	0.312		2.846
100	480	0.556	1.250	1.798
150	480	0.608	1.230	1.618

FC322, P30KT4

Cable length [m]	Mains voltage [V]	Rise time [μsec]	Vpeak [kV]	dU/dt [kV/μsec]
15	480	0.288		3.083
100	480	0.492	1.230	2.000
150	480	0.468	1.190	2.034

FC322, P37KT4

Cable length [m]	Mains voltage	Rise time [μsec]	Vpeak [kV]	dU/dt [kV/μsec]
5	480	0.368	1.270	2.853
50	480	0.536	1.260	1.978
100	480	0.680	1.240	1.426
150	480	0.712	1.200	1.334

FC322, P45KT4

Cable length [m]	Mains voltage [V]	Rise time [μsec]	Vpeak [kV]	dU/dt [kV/μsec]
5	480	0.368	1.270	2.853
50	480	0.536	1.260	1.978
100	480	0.680	1.240	1.426
150	480	0.712	1.200	1.334

FC322, P55KT4

Cable length [m]	Mains voltage [V]	Rise time [μsec]	Vpeak [kV]	dU/dt [kV/μsec]
15	480	0.256	1.230	3.847
50	480	0.328	1.200	2.957
100	480	0.456	1.200	2.127
150	480	0.960	1.150	1.052

FC322, P75KT4

Cable length [m]	Mains voltage [V]	Rise time [μsec]	Vpeak [kV]	dU/dt [kV/μsec]
5	480	0.371	1.170	2.523

FC322, P90KT4

Cable length [m]	Mains voltage [V]	Rise time [µsec]	Vpeak [kV]	dU/dt [kV/µsec]
5	480	0.371	1.170	2.523

High Power Range:

FC322, P110 - P250, T4

Cable length [m]	Mains voltage [V]	Rise time [µsec]	Vpeak [kV]	dU/dt [kV/µsec]
30	400	0.34	1.040	2.447

FC322, P315 - P1M0, T4

Cable length [m]	Mains voltage [V]	Rise time [µsec]	Vpeak [kV]	dU/dt [kV/µsec]
30	500	0.71	1.165	1.389
30	400	0.61	0.942	1.233

FC322, P110 - P400, T7

Cable length [m]	Mains voltage [V]	Rise time [µsec]	Vpeak [kV]	dU/dt [kV/µsec]
30	690	0.38	1.513	3.304
30	575	0.23	1.313	2.750
30	690 1)	1.72	1.329	0.640

1) With Danfoss dU/dt filter.

FC322, P450 - P1M2, T7

Cable length [m]	Mains voltage [V]	Rise time [µsec]	Vpeak [kV]	dU/dt [kV/µsec]
30	690	0.57	1.611	2.261
30	575	0.25		2.510
30	690 1)	1.13	1.629	1.150

1) With Danfoss dU/dt filter.

3

3.5 Special Conditions

3.5.1 Purpose of Derating

Derating must be taken into account when using the frequency converter at low air pressure (heights), at low speeds, with long motor cables, cables with a large cross section or at high ambient temperature. The required action is described in this section.

3.5.2 Derating for Ambient Temperature

The average temperature ($T_{AMB, AVG}$) measured over 24 hours must be at least 5 °C lower than the maximum allowed ambient temperature ($T_{AMB,MAX}$).

If the frequency converter is operated at high ambient temperatures, the continuous output current should be decreased.

The derating depends on the switching pattern, which can be set to 60 AVM or SFAVM in parameter 14-00.

A enclosures

60 AVM - Pulse Width Modulation

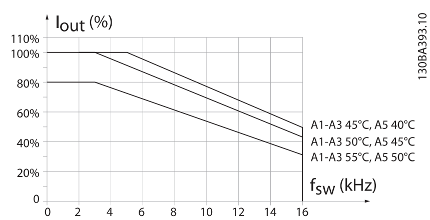


Illustration 3.1: Derating of I_{out} for different $T_{AMB, MAX}$ for enclosure A, using 60 AVM

SFAVM - Stator Frequency Asyncron Vector Modulation

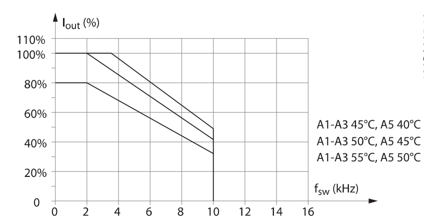


Illustration 3.2: Derating of I_{out} for different $T_{AMB, MAX}$ for enclosure A, using SFAVM

In enclosure A, the length of the motor cable has a relatively high impact on the recommended derating. Therefore, the recommended derating for an application with max. 10 m motor cable is also shown.

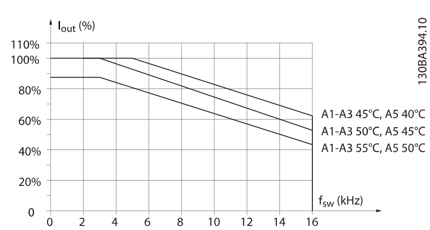


Illustration 3.3: Derating of I_{out} for different $T_{AMB, MAX}$ for enclosure A, using 60 AVM and maximum 10 m motor cable

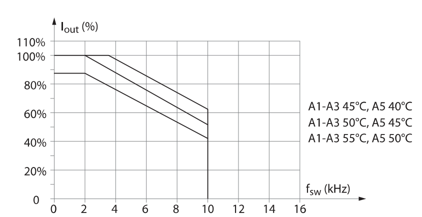


Illustration 3.4: Derating of I_{out} for different $T_{AMB, MAX}$ for enclosure A, using SFAVM and maximum 10 m motor cable

B enclosures

60 AVM - Pulse Width Modulation

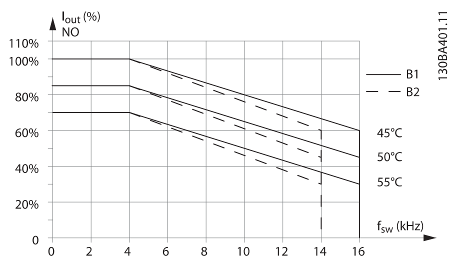


Illustration 3.5: Derating of I_{out} for different $T_{AMB, MAX}$ for enclosure B, using 60 AVM in Normal torque mode (110% over torque)

SFAVM - Stator Frequency Asyncron Vector Modulation

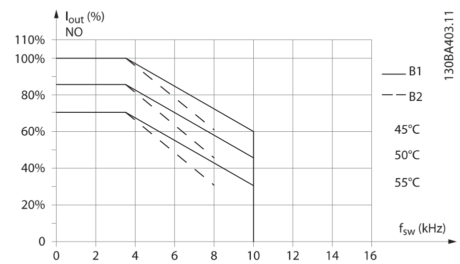


Illustration 3.6: Derating of I_{out} for different $T_{AMB, MAX}$ for enclosure B, using SFAVM in Normal torque mode (110% over torque)

C enclosures

Please note: For 90 kW in IP55 and IP66 the max. ambient temperature is 5° C lower.

60 AVM - Pulse Width Modulation

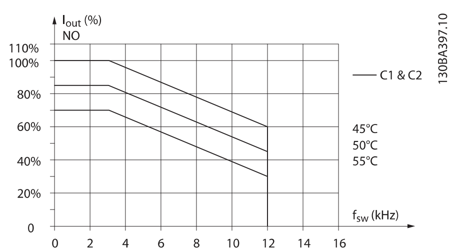


Illustration 3.7: Derating of I_{out} for different $T_{AMB, MAX}$ for enclosure C, using 60 AVM in Normal torque mode (110% over torque)

SFAVM - Stator Frequency Asyncron Vector Modulation

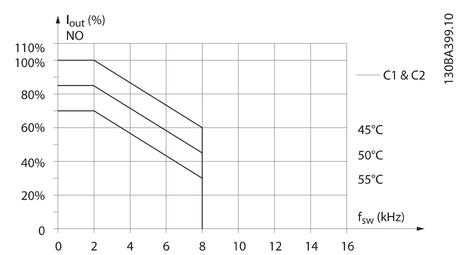


Illustration 3.8: Derating of I_{out} for different $T_{AMB, MAX}$ for enclosure C, using SFAVM in Normal torque mode (110% over torque)

D enclosures

60 AVM - Pulse Width Modulation, 380 - 480 V

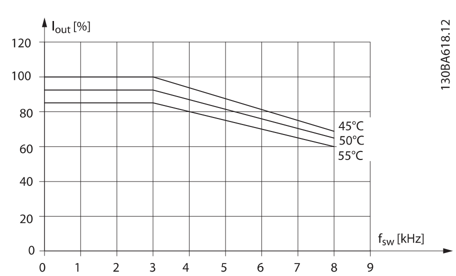


Illustration 3.9: Derating of I_{out} for different $T_{AMB, MAX}$ for enclosure D at 480 V, using 60 AVM in Normal torque mode (110% over torque)

SFAVM - Stator Frequency Asyncron Vector Modulation

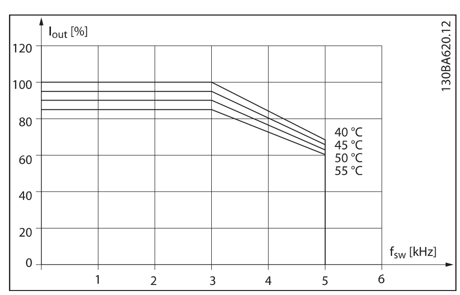


Illustration 3.10: Derating of I_{out} for different $T_{AMB, MAX}$ for enclosure D at 480 V, using SFAVM in Normal torque mode (110% over torque)

3

60 AVM - Pulse Width Modulation, 525 - 690 V (except P400)

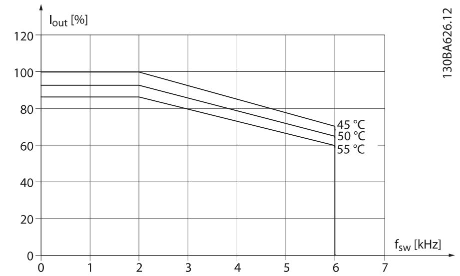


Illustration 3.11: Derating of I_{out} for different $T_{AMB, MAX}$ for enclosure D at 690 V, using 60 AVM in Normal torque mode (110% over torque). Note: *not* valid for P400.

SFAVM - Stator Frequency Asyncron Vector Modulation

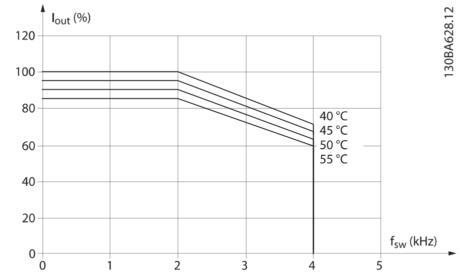


Illustration 3.12: Derating of I_{out} for different $T_{AMB, MAX}$ for enclosure D at 690 V, using SFAVM in Normal torque mode (110% over torque). Note: *not* valid for P400.

60 AVM - Pulse Width Modulation, 525 - 690 V, P400

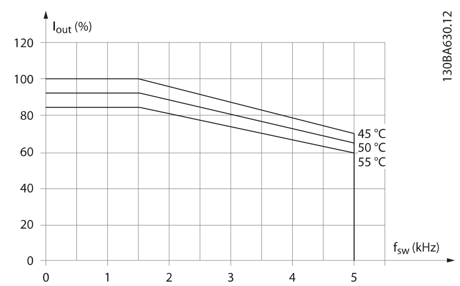


Illustration 3.13: Derating of I_{out} for different $T_{AMB, MAX}$ for enclosure D at 690 V, using 60 AVM in Normal torque mode (110% over torque). Note: P400 *only*.

SFAVM - Stator Frequency Asyncron Vector Modulation

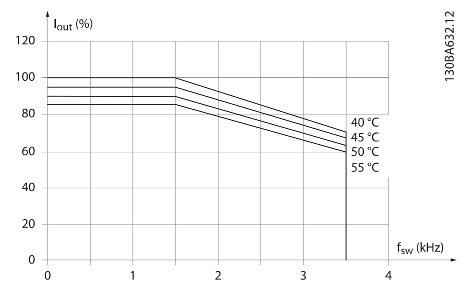


Illustration 3.14: Derating of I_{out} for different $T_{AMB, MAX}$ for enclosure D at 690 V, using SFAVM in Normal torque mode (110% over torque). Note: P400 *only*.

E and F enclosures

60 AVM - Pulse Width Modulation, 380 - 480 V

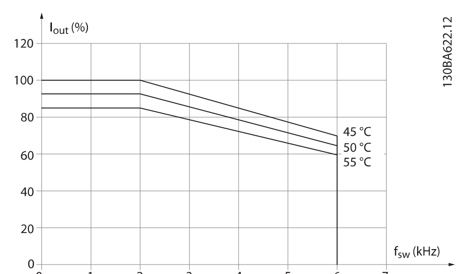


Illustration 3.15: Derating of I_{out} for different $T_{AMB, MAX}$ for enclosure E at 480 V, using 60 AVM in Normal torque mode (110% over torque)

SFAVM - Stator Frequency Asyncron Vector Modulation

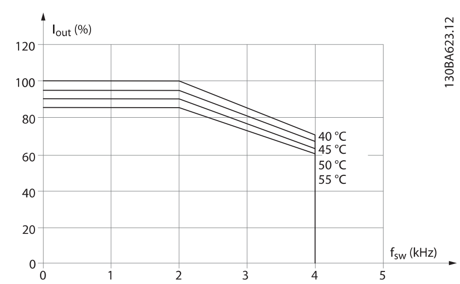


Illustration 3.16: Derating of I_{out} for different $T_{AMB, MAX}$ for enclosure E and F at 480 V, using SFAVM in Normal torque mode (110% over torque)

60 AVM - Pulse Width Modulation, 525 - 690 V

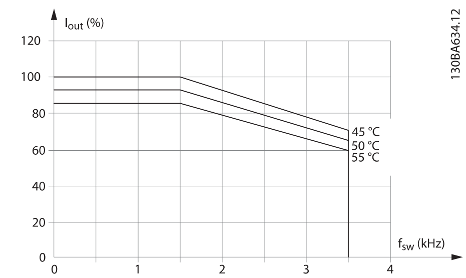


Illustration 3.17: Derating of I_{out} for different $T_{AMB, MAX}$ for enclosure E and F at 690 V, using 60 AVM in Normal torque mode (110% over torque).

SFAVM - Stator Frequency Asyncron Vector Modulation

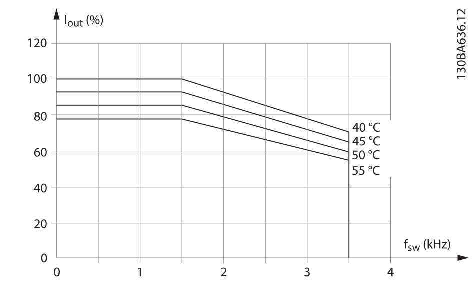


Illustration 3.18: Derating of I_{out} for different $T_{AMB, MAX}$ for enclosure E and F at 690 V, using SFAVM in Normal torque mode (110% over torque).

3.5.3 Derating for Low Air Pressure

The cooling capability of air is decreased at lower air pressure.

Below 1000 m altitude no derating is necessary but above 1000 m the ambient temperature (T_{AMB}) or max. output current (I_{out}) should be derated in accordance with the shown diagram.

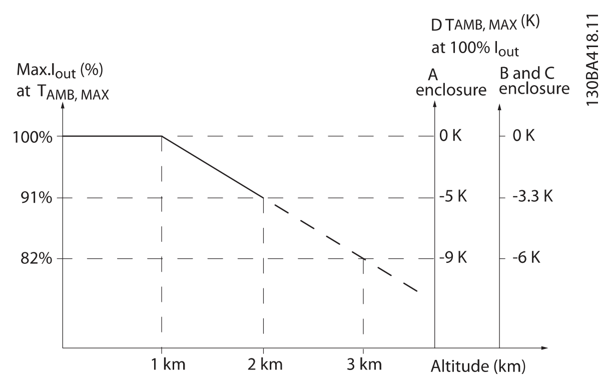
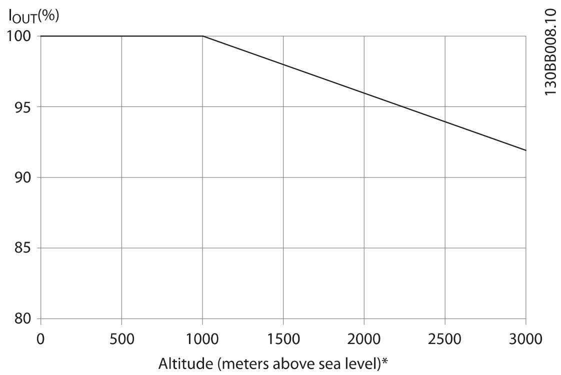
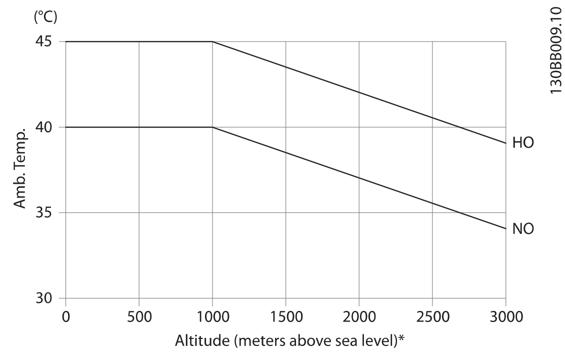


Illustration 3.19: Derating of output current versus altitude at $T_{AMB, MAX}$ for frame sizes A, B and C. At altitudes above 2 km, please contact Danfoss Drives regarding PELV.

An alternative is to lower the ambient temperature at high altitudes and thereby ensure 100% output current at high altitudes. As an example of how to read the graph, the situation at 2 km is elaborated. At a temperature of 45° C ($T_{AMB, MAX}$ - 3.3 K), 91% of the rated output current is available. At a temperature of 41.7° C, 100% of the rated output current is available.





Derating of output current versus altitude at $T_{AMB, MAX}$ for frame sizes D, E and F.

3.5.4 Derating for Running at Low Speed

When a motor is connected to a frequency converter, it is necessary to check that the cooling of the motor is adequate.
The level of heating depends on the load on the motor, as well as the operating speed and time.

Constant torque applications (CT mode)

A problem may occur at low RPM values in constant torque applications. In a constant torque application s a motor may over-heat at low speeds due to less cooling air from the motor integral fan.
Therefore, if the motor is to be run continuously at an RPM value lower than half of the rated value, the motor must be supplied with additional air-cooling (or a motor designed for this type of operation may be used).

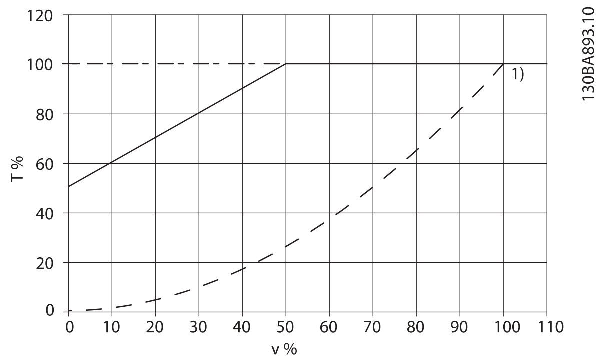
An alternative is to reduce the load level of the motor by choosing a larger motor. However, the design of the frequency converter puts a limit to the motor size.

Variable (Quadratic) torque applications (VT)

In VT applications such as centrifugal pumps and fans, where the torque is proportional to the square of the speed and the power is proportional to the cube of the speed, there is no need for additional cooling or de-rating of the motor.

In the graphs shown below, the typical VT curve is below the maximum torque with de-rating and maximum torque with forced cooling at all speeds.

Maximum Load for a Standard Motor at 40 °C driven by a frequency converter type VLT FCxxx



Legend: – – – –Typical torque at VT load –•–•–Max torque with forced cooling ——Max torque

Note 1) Over-syncronous speed operation will result in the available motor torque decreasing inversely proportional with the increase in speed. This must be considered during the design phase to avoid over-loading of the motor.

3.5.5 Derating for Installing Long Motor Cables or Cables with Larger Cross-Section

NB!
Applicable for drives up to 90 kW only.

The maximum cable length for this frequency converter is 300 m unscreened and 150 m screened cable.

The frequency converter has been designed to work using a motor cable with a rated cross-section. If a cable with a larger cross-section is used, reduce the output current by 5% for every step the cross-section is increased.
(Increased cable cross-section leads to increased capacity to earth, and thus an increased earth leakage current).

3.5.6 Automatic Adaptations to Ensure Performance

The frequency converter constantly checks for critical levels of internal temperature, load current, high voltage on the intermediate circuit and low motor speeds. As a response to a critical level, the frequency converter can adjust the switching frequency and / or change the switching pattern in order to ensure the performance of the frequency converter. The capability to automatically reduce the output current extends the acceptable operating conditions even further.

3.6 Options and Accessories

Danfoss offers a wide range of options and accessories for the frequency converters.

3.6.1 Mounting of Option Modules in Slot B

The power to the frequency converter must be disconnected.

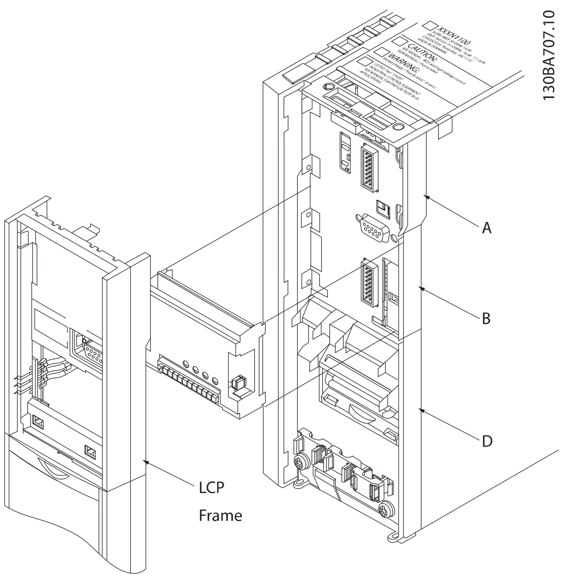
For A2 and A3 enclosures:

- Remove the LCP (Local Control Panel), the terminal cover, and the LCP frame from the frequency converter.
- Fit the MCB10x option card into slot B.

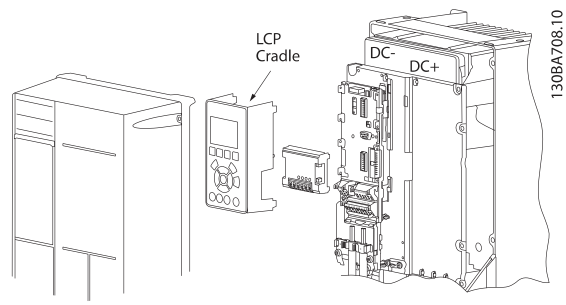
- Connect the control cables and relieve the cable by the enclosed cable strips.
  Remove the knock out in the extended LCP frame delivered in the option set, so that the option will fit under the extended LCP frame.
- Fit the extended LCP frame and terminal cover.
- Fit the LCP or blind cover in the extended LCP frame.
- Connect power to the frequency converter.
- Set up the input/output functions in the corresponding parameters, as mentioned in the section *General Technical Data*.

For B1, B2, C1 and C2 enclosures:

- Remove the LCP and the LCP cradle
- Fit the MCB 10x option card into slot B
- Connect the control cables and relieve the cable by the enclosed cable strips
- Fit the cradle
- Fit the LCP



A2, A3 and B3 enclosures

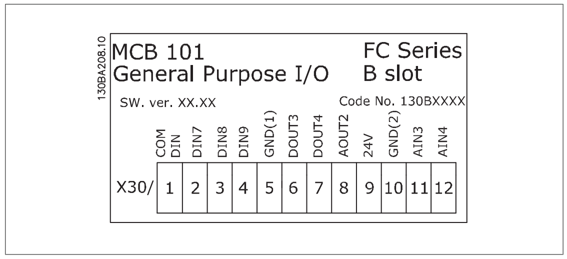


A5, B1, B2, B4, C1, C2, C3 and C4 enclosures

3

3.6.2 General Purpose Input Output Module MCB 101

MCB 101 is used for extension of the number of digital and analog inputs and outputs of the VLT Automation VT Drive.



Contents: MCB 101 must be fitted into slot B in the VLT Automation VT Drive.

- MCB 101 option module
- Extended LCP frame
- Terminal cover

Galvanic Isolation in the MCB 101

Digital/analog inputs are galvanically isolated from other inputs/outputs on the MCB 101 and in the control card of the drive. Digital/analog outputs in the MCB 101 are galvanically isolated from other inputs/outputs on the MCB 101, but not from these on the control card of the drive.

If the digital inputs 7, 8 or 9 are to be switched by use of the internal 24 V power supply (terminal 9) the connection between terminal 1 and 5 which is illustrated in the drawing has to be established.

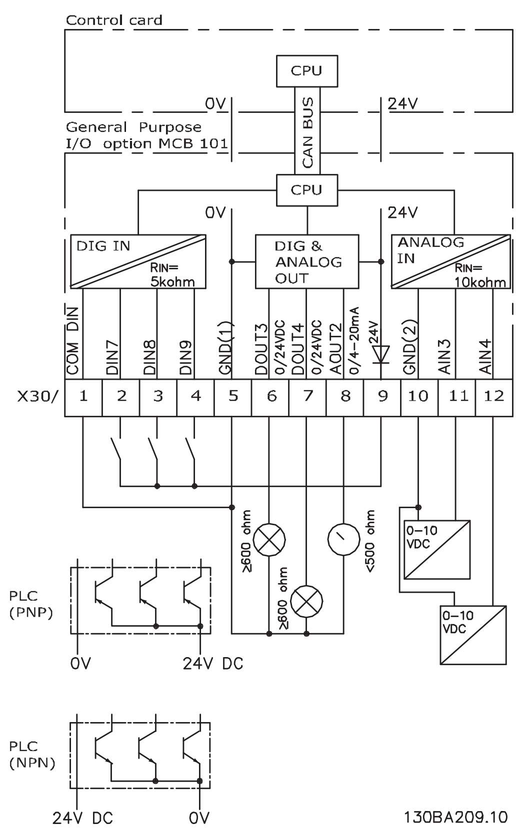


Illustration 3.20: Principle Diagram

3.6.3 Digital inputs - Terminal X30/1-4

Parameters for set-up: 5-16, 5-17 and 5-18

Number of digital inputs	Voltage level	Voltage levels	Tolerance	Max. Input impedance
3	0-24 V DC	PNP type: Common = 0 V Logic "0": Input < 5 V DC Logic "0": Input > 10 V DC NPN type: Common = 24 V Logic "0": Input > 19 V DC Logic "0": Input < 14 V DC	± 28 V continuous ± 37 V in minimum 10 sec.	Approx. 5 k ohm

3.6.4 Analog Voltage inputs - Terminal X30/10-12

Parameters for set-up: 6-3*, 6-4* and 16-76

Number of analog voltage inputs	Standardized input signal	Tolerance	Resolution	Max. Input impedance
2	0-10 V DC	± 20 V continuously	10 bits	Approx. 5 K ohm

3.6.5 Digital Outputs - Terminal X30/5-7

Parameters for set-up: 5-32 and 5-33

Number of digital outputs	Output level	Tolerance	Max.impedance
2	0 or 24 V DC	± 4 V	≥ 600 ohm

3.6.6 Analog Outputs - Terminal X30/5+8

Parameters for set-up: 6-6* and 16-77

Number of analog outputs	Output signal level	Tolerance	Max.impedance
1	0/4 - 20 mA	± 0.1 mA	< 500 ohm

3

3.6.7 Relay Option MCB 105

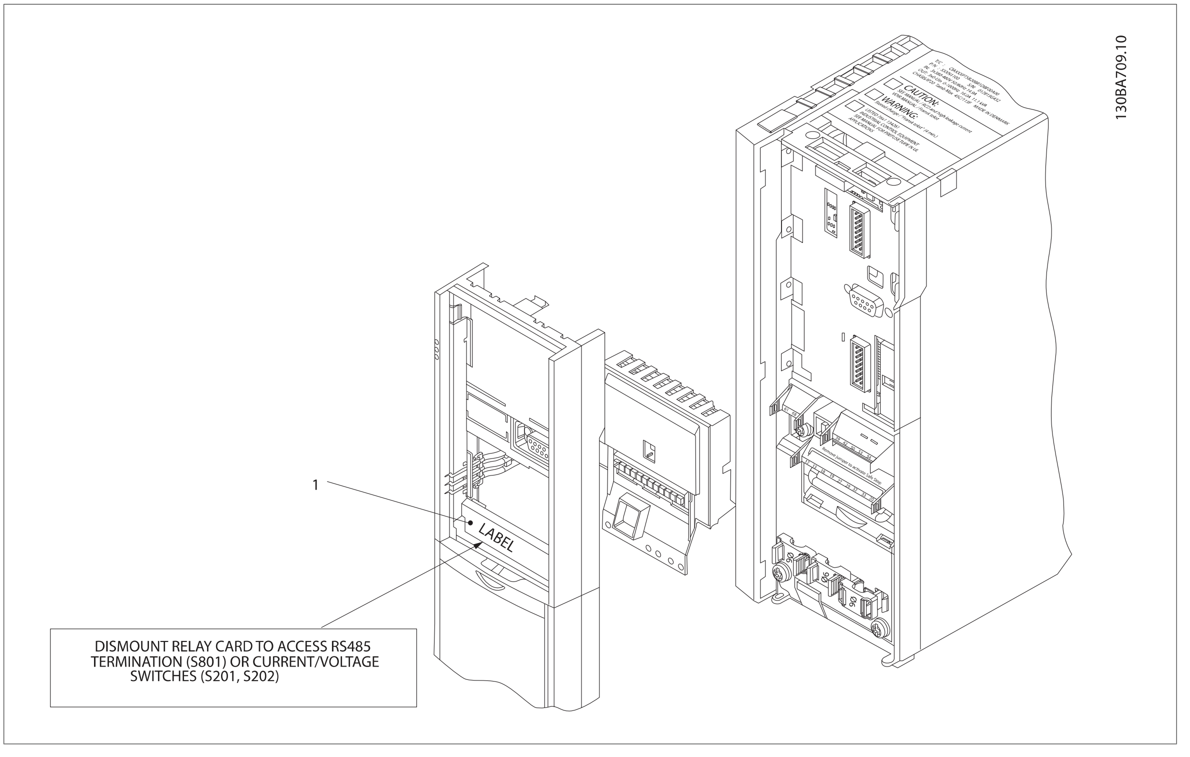
The MCB 105 option includes 3 pieces of SPDT contacts and must be fitted into option slot B.

Electrical Data:	
Max terminal load (AC-1) 1) (Resistive load)	240 V AC 2A
Max terminal load (AC-15) 1) (Inductive load @ cosφ 0.4)	240 V AC 0.2 A
Max terminal load (DC-1) 1) (Resistive load)	24 V DC 1 A
Max terminal load (DC-13) 1) (Inductive load)	24 V DC 0.1 A
Min terminal load (DC)	5 V 10 mA
Max switching rate at rated load/min load	6 min^{-1}/20 sec^{-1}

1) IEC 947 part 4 and 5

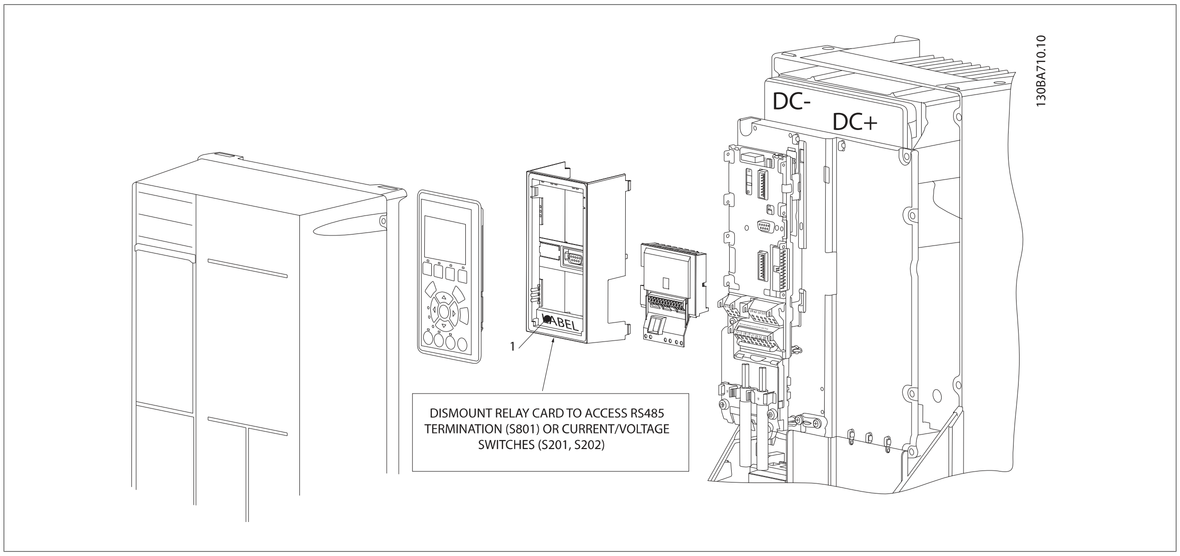
When the relay option kit is ordered separately the kit includes:

- Relay Module MCB 105
- Extended LCP frame and enlarged terminal cover
- Label for covering access to switches S201, S202 and S801
- Cable strips for fastening cables to relay module



A2-A3-B3	A5-B1-B2-B4-C1-C2-C3-C4

1) **IMPORTANT**! The label MUST be placed on the LCP frame as shown (UL approved).

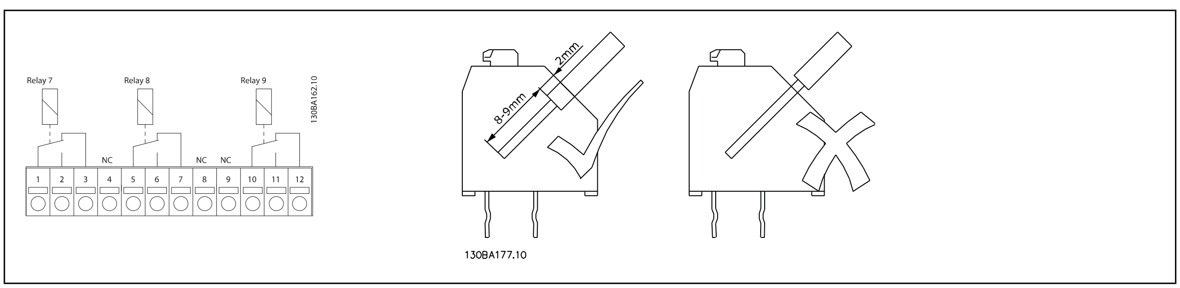


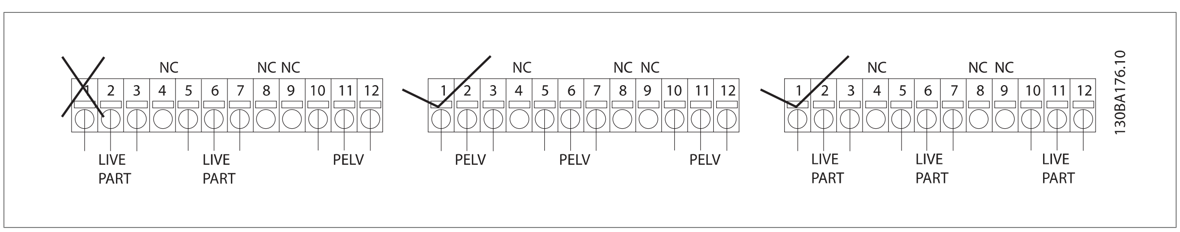
Warning Dual supply

How to add the MCB 105 option:

- See mounting instructions in the beginning of section *Options and Accessories*
- The power to the live part connections on relay terminals must be disconnected.
- Do not mix live parts (high voltage) with control signals (PELV).
- Select the relay functions in par. 5-40 *Function Relay* [6-8], par. 5-41 *On Delay, Relay* [6-8] and par. 5-42 *Off Delay, Relay* [6-8].

NB! (Index [6] is relay 7, index [7] is relay 8, and index [8] is relay 9)





Do not combine low voltage parts and PELV systems.

3

3.6.8 24 V Back-Up Option MCB 107 (Option D)

External 24 V DC Supply

An external 24 V DC supply can be installed for low-voltage supply to the control card and any option card installed. This enables full operation of the LCP (including the parameter setting) and field busses without mains supplied to the power section.

External 24 V DC supply specification:	
Input voltage range	24 V DC ±15 % (max. 37 V in 10 s)
Max. input current	2.2 A
Average input current for the frequency converter	0.9 A
Max cable length	75 m
Input capacitance load	< 10 uF
Power-up delay	< 0.6 s

The inputs are protected.

Terminal numbers:

Terminal 35: - external 24 V DC supply.

Terminal 36: + external 24 V DC supply.

Follow these steps:

1. Remove the LCP or Blind Cover
2. Remove the Terminal Cover
3. Remove the Cable De-coupling Plate and the plastic cover underneath
4. Insert the 24 V DC Backup External Supply Option in the Option Slot
5. Mount the Cable De-coupling Plate
6. Attach the Terminal Cover and the LCP or Blind Cover.

When MCB 107, 24 V backup option is supplying the control circuit, the internal 24 V supply is automatically disconnected.

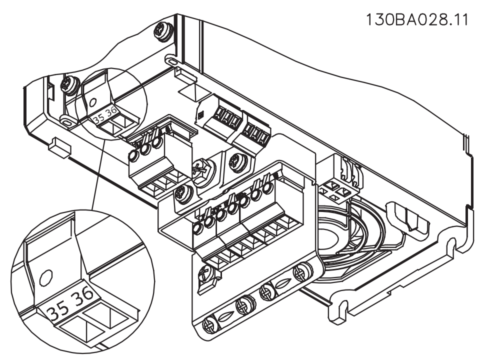


Illustration 3.21: Connection to 24 V backup supplier (A2-A3).

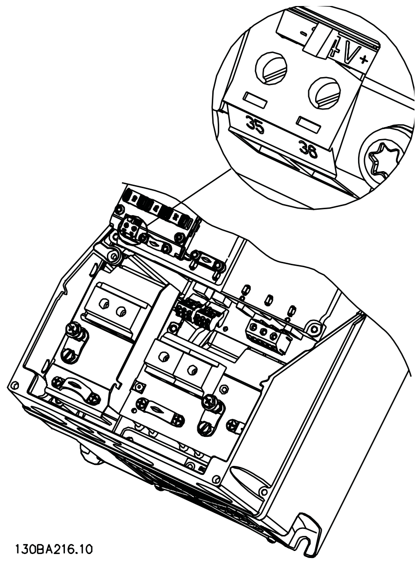


Illustration 3.22: Connection to 24 V backup supplier (A5-C2).

3.6.9 Analog I/O Option MCB 109

The Analog I/O card is supposed to be used in e.g. the following cases:

- Providing battery back-up of clock function on control card
- As general extension of analog I/O selection available on control card, e.g. for multi-zone control with three pressure transmitters
- Turning frequency converter into de-central I/O block supporting Building Management System with inputs for sensors and outputs for operating dampers and valve actuators
- Support Extended PID controllers with I/Os for set point inputs, transmitter/sensor inputs and outputs for actuators.

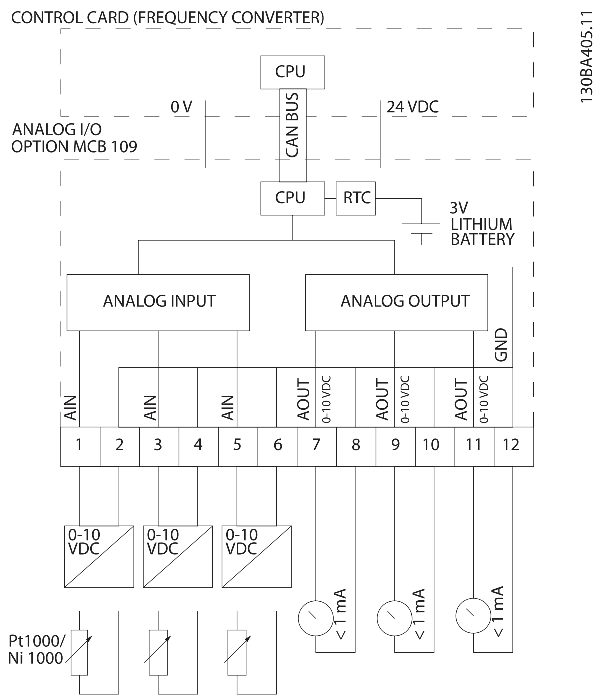


Illustration 3.23: Principle diagram for Analog I/O mounted in frequency converter.

Analog I/O configuration

3 x Analog Inputs, capable of handling following:

- 0 - 10 VDC

OR

- 0-20 mA (voltage input 0-10V) by mounting a 510Ω resistor across terminals (see NB!)
- 4-20 mA (voltage input 2-10V) by mounting a 510Ω resistor across terminals (see NB)
- Ni1000 temperature sensor of 1000 Ω at 0° C. Specifications according to DIN43760
- Pt1000 temperature sensor of 1000 Ω at 0° C. Specifications according to IEC 60751

3 x Analog Outputs supplying 0-10 VDC.

NB!
Please note the values available within the different standard groups of resistors:
E12: Closest standard value is 470Ω, creating an input of 449.9Ω and 8.997V.
E24: Closest standard value is 510Ω, creating an input of 486.4Ω and 9.728V.
E48: Closest standard value is 511Ω, creating an input of 487.3Ω and 9.746V.
E96: Closest standard value is 523Ω, creating an input of 498.2Ω and 9.964V.

Analog inputs - terminal X42/1-6
Parameter group for read out: 18-3*. See also *Programming Guide.*

Parameter groups for set-up: 26-0*, 26-1*, 26-2* and 26-3*. See also *Programming Guide.*

3 x Analog inputs	Operating range	Resolution	Accuracy	Sampling	Max load	Impedance
Used as temperature sensor input	-50 to +150 °C	11 bits	-50 °C ±1 Kelvin +150 °C ±2 Kelvin	3 Hz	-	-
Used as voltage input	0 - 10 VDC	10 bits	0.2% of full scale at cal. temperature	2.4 Hz	+/- 20 V continuously	Approximately 5 kΩ

When used for voltage, analog inputs are scalable by parameters for each input.

When used for temperature sensor, analog inputs scaling is preset to necessary signal level for specified temperature span.

When analog inputs are used for temperature sensors, it is possible to read out feedback value in both °C and °F.

When operating with temperature sensors, maximum cable length to connect sensors is 80 m non-screened / non-twisted wires.

Analog outputs - terminal X42/7-12
Parameter group for read out and write: 18-3*. See also *Programming Guide*
Parameter groups for set-up: 26-4*, 26-5* and 26-6*. See also *Programming Guide*

3 x Analog outputs	Output signal level	Resolution	Linearity	Max load
Volt	0-10 VDC	11 bits	1% of full scale	1 mA

Analog outputs are scalable by parameters for each output.

The function assigned is selectable via a parameter and have same options as for analog outputs on control card.

For a more detailed description of parameters, please refer to the *Programming Guide*.

Real-time clock (RTC) with back-up
The data format of RTC includes year, month, date, hour, minutes and weekday.

Accuracy of clock is better than ± 20 ppm at 25 °C.

The built-in lithium back-up battery lasts on average for minimum 0 years, when frequency converter is operating at 40 °C ambient temperature. If battery pack back-up fails, analog I/O option must be exchanged.

3.6.10 Extended Cascade Controller MCO 101 and Advanced Cascade Controller, MCO 102

Cascade control is a common control system used to control parallel pumps or fans in an energy efficient way.

The Cascade Controller option provides the capability to control multiple pumps configured in parallel in a way that makes them appear as a single larger pump.

When using Cascade Controllers, the individual pumps are automatically turned on (staged) and turned off (de-staged) as needed in order to satisfy the required system output for flow or pressure. The speed of pumps connected to VLT Automation VT Drive is also controlled to provide a continuous range of system output.

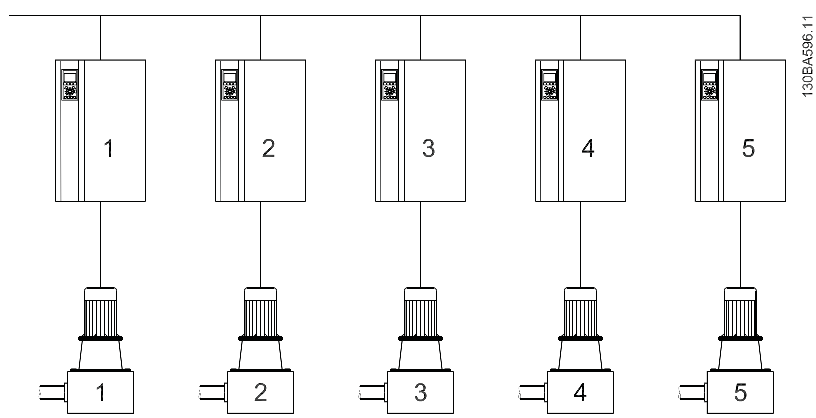


Illustration 3.24: Cascade control of multiple pumps

The Cascade Controllers are optional hardware and software components that can be added to the VLT Automation VT Drive. It consists of an option board containing 3 relays that is installed in the B option location on the Drive. Once options are installed the parameters needed to support the Cascade Controller functions will be available through the control panel in the 27-** parameter group. The Extended Cascade Controller offers more functionality than the Basic Cascade Controller. It can be used to extend the Basic Cascade with 3 relays and even to 8 relays with the Advanced Cascade Control card installed.

While the Cascade controller is designed for pumping applications and this document describes the cascade controller for this application, it is also possible to use the Cascade Controllers for any application requiring multiple motors configured in parallel.

3.6.11 General Description

The Cascade Controller software runs from a single VLT Automation VT Drive with the Cascade Controller option card installed. This frequency converter is referred to as the Master Drive. It controls a set of pumps each controlled by a frequency converter or connected directly to mains through a contactor or through a soft starter.

Each additional frequency converter in the system is referred to as a Follower Drive. These frequency converters do not need the Cascade Controller option card installed. They are operated in open loop mode and receive their speed reference from the Master Drive. The pumps connected to these frequency converters are referred to as Variable Speed Pumps.

Each additional pump connected to mains through a contactor or through a soft starter is referred to as a Fixed Speed Pump.

Each pump, variable speed or fixed speed, is controlled by a relay in the Master Drive. The frequency converter with the Cascade Controller option card installed has five relays available for controlling pumps. Two (2) relays are standard in the FC and additional 3 relays are found on the option card MCO 101 or 8 relays and 7 digital inputs on option card MCO 102.

The Cascade Controller is capable of controlling a mix of variable speed and fixed speed pumps. Possible configurations are described in more detail in the next section. For simplicity of description within this manual, Pressure and Flow will be used to describe the variable output of the set of pumps controlled by the cascade controller.

3.6.12 Extended Cascade Control MCO 101

The MCO 101 option includes 3 pieces of change-over contacts and can be fitted into option slot B.

Electrical Data:	
Max terminal load (AC)	240 V AC 2A
Max terminal load (DC)	24 V DC 1 A
Min terminal load (DC)	5 V 10 mA
Max switching rate at rated load/min load	6 min^{-1}/20 sec^{-1}

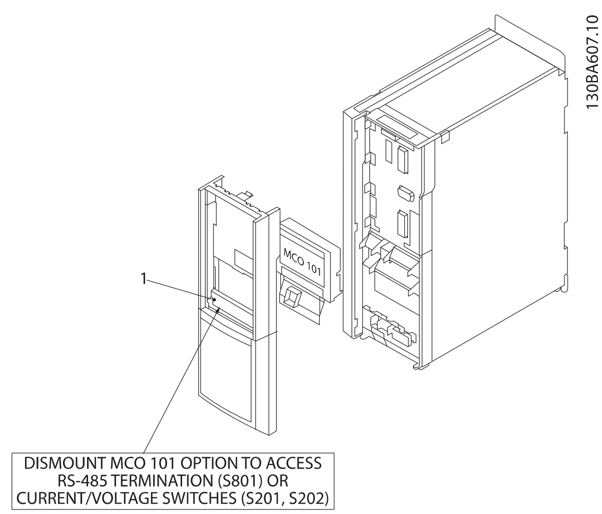


Illustration 3.25: Mounting of B-options

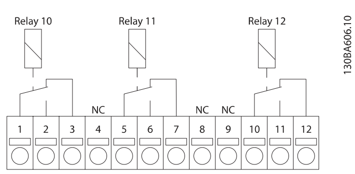
Warning Dual supply

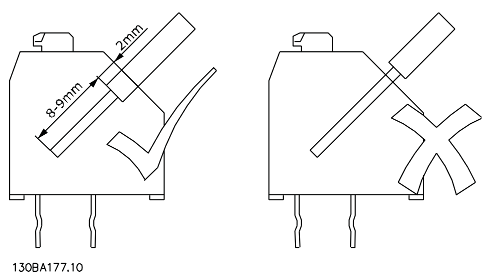
NB!
The label MUST be placed on the LCP frame as shown (UL approved).

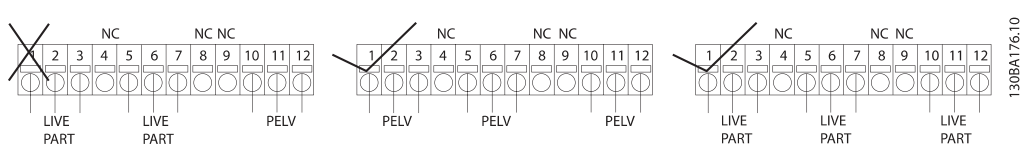
How to add the MCO 101 option:

- The power to the frequency converter must be disconnected.
- The power to the live part connections on relay terminals must be disconnected.
- Remove the LCP, the terminal cover and the cradle from the FC322.
- Fit the MCO 101 option in slot B.
- Connect the control cables and relief the cables by the enclosed cable strips.
- Various systems must not be mixed.
- Fit the extended cradle and terminal cover.
- Replace the LCP
- Connect power to the frequency converter.

Wiring the Terminals







Do not combine low voltage parts and PELV systems.

3.6.13 Brake Resistors

In applications where the motor is used as a brake, energy is generated in the motor and send back into the frequency converter. If the energy can not be transported back to the motor it will increase the voltage in the converter DC-line. In applications with frequent braking and/or high inertia loads this increase may lead to an over voltage trip in the converter and finally a shut down. Brake resistors are used to dissipate the excess energy resulting from the regenerative braking. The resistor is selected in respect to its ohmic value, its power dissipation rate and its physical size. Danfoss offers a wide variety of different resistors that are specially designed to our frequency converters. See the section *Control with brake function* for the dimensioning of brake resistors. Code numbers can be found in the section *How to order*.

3

3.6.14 Remote Mounting Kit for LCP

The Local Control Panel can be moved to the front of a cabinet by using the remote build in kit. The enclosure is the IP65. The fastening screws must be tightened with a torque of max. 1 Nm.

Technical data	
Enclosure:	IP 65 front
Max. cable length between and unit:	3 m
Communication std:	RS 485

Ordering no. 130B1113

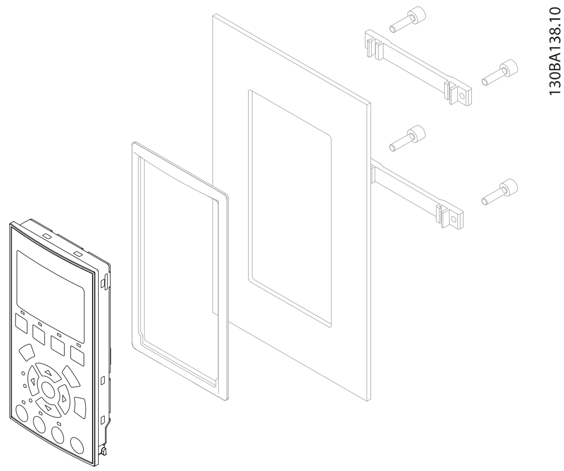


Illustration 3.26: LCP Kit with graphical LCP, fasteners, 3 m cable and gasket.

Ordering no. 130B1114

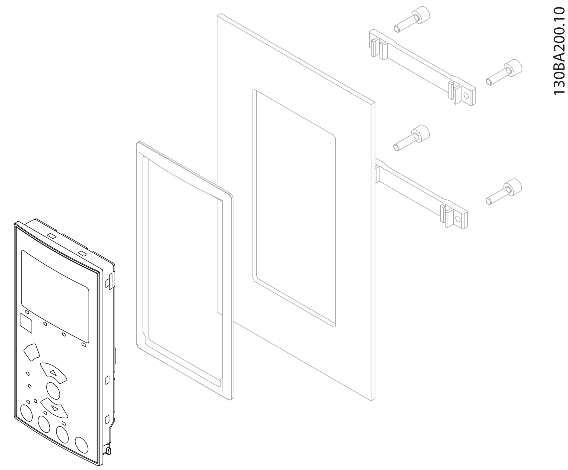
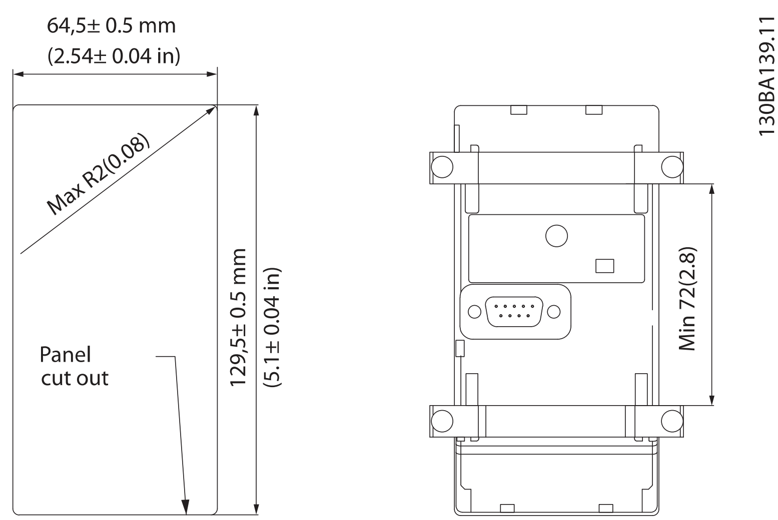


Illustration 3.27: LCP Kit with numerical LCP, fasternes and gasket.

LCP Kit without LCP is also available. Ordering number: 130B1117
For IP55 units the ordering number is 130B1129.



3.6.15 IP 21/IP 4X/ TYPE 1 Enclosure Kit

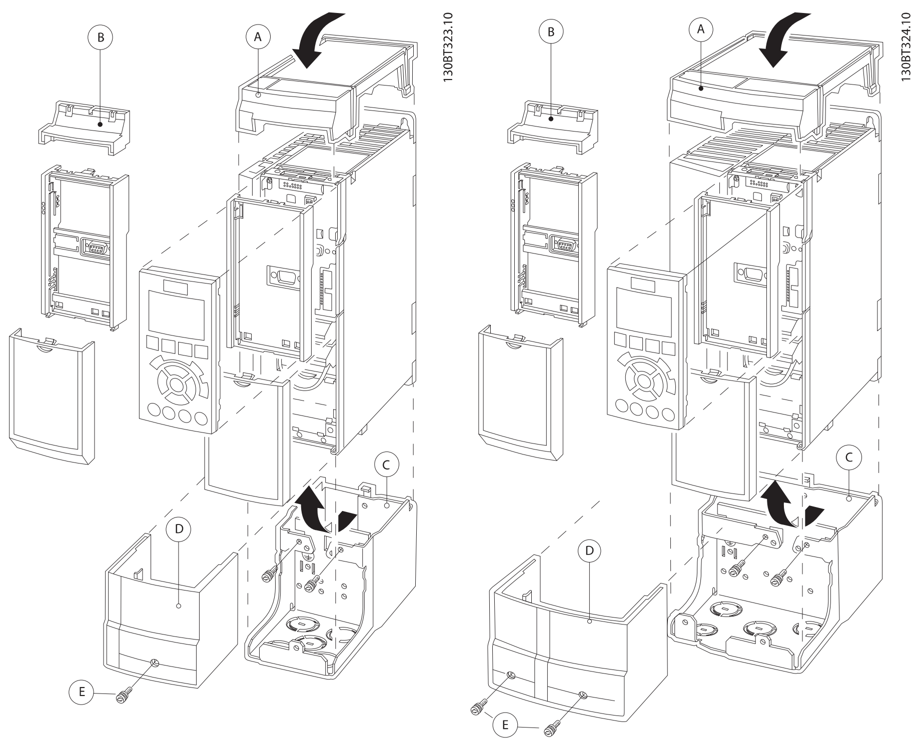
IP 20/IP 4X top/ TYPE 1 is an optional enclosure element available for IP 20 Compact units, enclosure size A2-A3 up to 7.5 kW.
If the enclosure kit is used, an IP 20 unit is upgraded to comply with enclosure IP 21/ 4X top/TYPE 1.

The IP 4X top can be applied to all standard IP 20 VLT Automation VT Drive variants.

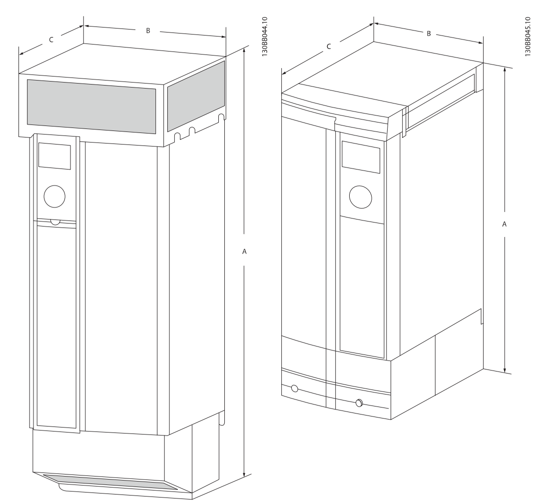
A – Top cover
B – Brim
C – Base part
D – Base cover
E – Screw(s)

Place the top cover as shown. If an A or B option is used the brim must be fitted to cover the top inlet. Place the base part C at the bottom of the drive and use the clamps from the accessory bag to correctly fasten the cables. Holes for cable glands:

Size A2: 2x M25 and 3xM32
Size A3: 3xM25 and 3xM32



A2 Enclosure   A3 Enclosure



A2, A3, B3   B4, C3, C4

3.6.16 Input Filters

Harmonic current distortion is caused by the 6-pulse diode rectifier of the variable speed drive. The harmonic currents are affecting the installed serial equipment identical to reactive currents. Consequently harmonic current distortion can result in overheating of the supply transformer, cables etc. Depending on the impedance of the power grid, harmonic current distortion can lead to voltage distortion also affecting other equipment powered by the same transformer. Voltage distortion is increasing losses, causes premature aging and worst of all erratic operation. The majority of harmonics are reduced by the built-in DC coil but if additional reduction is needed, Danfoss offers two types of passive filters.

The Danfoss AHF 005 and AHF 010 are advanced harmonic filters, not to be compared with traditional harmonic trap filters. The Danfoss harmonic filters have been specially designed to match the Danfoss frequency converters.

AHF 010 is reducing the harmonic currents to less than 10% and the AHF 005 is reducing harmonic currents to less than 5% at 2% background distortion and 2% imbalance.

3.6.17 Output Filters

The high speed switching of the frequency converter produces some secondary effects, which influence the motor and the enclosed environment. These side effects are addressed by two different filter types, -the du/dt and the Sine-wave filter.

du/dt filters
Motor insulation stresses are often caused by the combination of rapid voltage and current increase. The rapid energy changes can also be reflected back to the DC-line in the inverter and cause shut down. The du/dt filter is designed to reduce the voltage rise time/the rapid energy change in the motor and by that intervention avoid premature aging and flashover in the motor insulation. du/dt filters have a positive influence on the radiation of magnetic noise in the cable that connects the drive to the motor. The voltage wave form is still pulse shaped but the du/dt ratio is reduced in comparison with the installation without filter.

Sine-wave filters
Sine-wave filters are designed to let only low frequencies pass. High frequencies are consequently shunted away which results in a sinusoidal phase to phase voltage waveform and sinusoidal current waveforms.
With the sinusoidal waveforms the use of special frequency converter motors with reinforced insulation is no longer needed. The acoustic noise from the motor is also damped as a consequence of the wave condition.
Besides the features of the du/dt filter, the sine-wave filter also reduces insulation stress and bearing currents in the motor thus leading to prolonged motor lifetime and longer periods between services. Sine-wave filters enable use of longer motor cables in applications where the motor is installed far from the drive. The length is unfortunately limited because the filter does not reduce leakage currents in the cables.

3.7 High Power Options

3.7.1 Installation of Duct Cooling Kit in Rittal Enclosures

This section deals with the installation of IP00 / chassis enclosed frequency converters with duct work cooling kits in Rittal enclosures. In addition to the enclosure a 200 mm base/plinth is required.

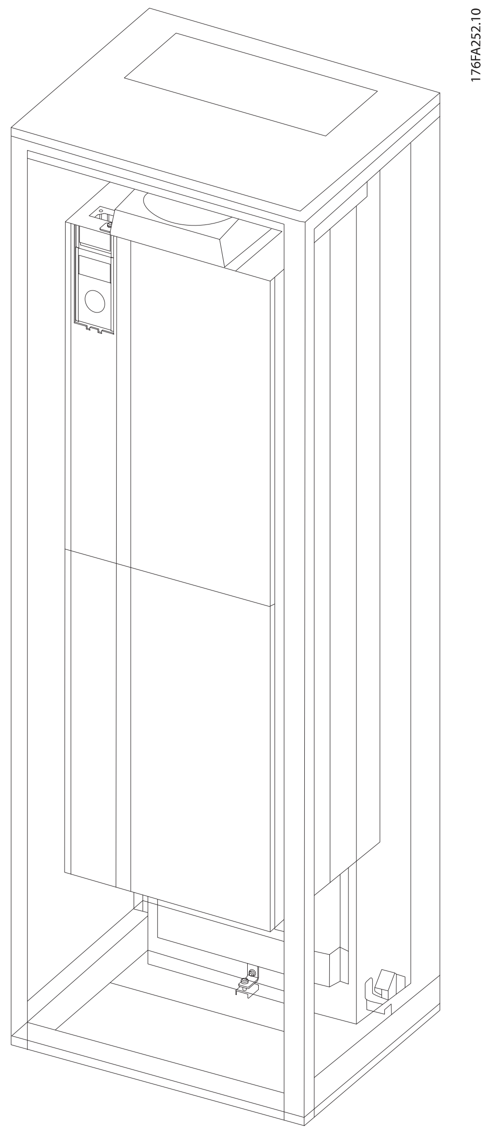


Illustration 3.28: Installation of IP00 in Rittal TS8 enclosure.

The minimum enclosure dimension is:

- D3 and D4 frame: Depth 500 mm and width 600 mm.
- E2 frame: Depth 600 mm and width 800 mm.

The maximum depth and width are as required by the installation. When using multiple frequency converters in one enclosure it is recommended that each drive is mounted on its own back panel and supported along the mid-section of the panel. These duct work kits do not support the "in frame" mounting of the panel (see Rittal TS8 catalogue for details). The duct work cooling kits listed in the table below are suitable for use only with IP 00 / Chassis frequency converters in Rittal TS8 IP 20 and UL and NEMA 1 and IP 54 and UL and NEMA 12 enclosures.

For the E2 frames it is important to mount the plate at the absolute rear of the Rittal enclosure due to the weight of the frequency converter.

NB!
A door-fan(s) is required on the Rittal cabinet to remove the loses not contained in the back-channel of the drive. The minimum door-fan(s) airflow required at the drive maximum ambient for the D3 and D4 is 391 m^3/h (230 cfm). The minimum door-fan(s) airflow required at the drive maximum ambient for the E2 is 782 m^3/h (460 cfm). If the ambient is below maximum or if additional components, heat loses, are added within the enclosure a calculation must be made to ensure the proper airflow is provided to cool the inside of the Rittal enclosure.

Ordering Information

Rittal TS-8 Enclosure	Frame D3 Kit Part No.	Frame D4Kit Part No.	Frame E2 Part No.
1800 mm	176F1824	176F1823	Not possible
2000 mm	176F1826	176F1825	176F1850
2200 mm			176F0299

Kit Contents

- Ductwork components
- Mounting hardware
- Gasket material
- Delivered with D3 and D4 frame kits:
  - 175R5639 - Mounting templates and top/bottom cut out for Rittal enclosure.
- Delivered with E2 frame kits:
  - 175R1036 - Mounting templates and top/bottom cut out for Rittal enclosure.

All fasteners are either:

- 10 mm, M5 Nuts torque to 2.3 Nm (20 in-lbs)
- T25 Torx screws torque to 2.3 Nm (20 in-lbs)

NB!
Please see the *Duct Kit Instruction Manual, 175R5640,* for further information

External ducts

If additional duct work is added externally to the Rittal cabinet the pressure drop in the ducting must be calculated. Use the charts below to derate the frequency converter according to the pressure drop.

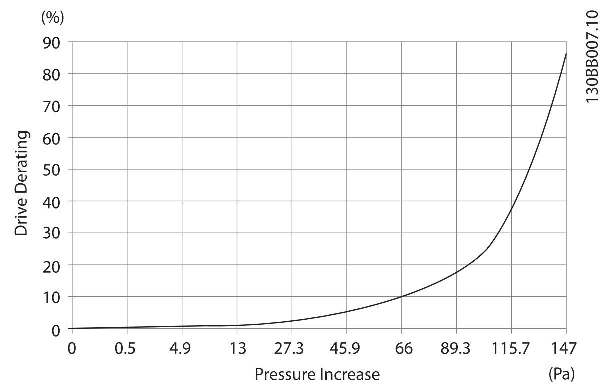


Illustration 3.29: D Frame Derating vs. Pressure Change

Drive air flow: 450 cfm (765 m3/h)

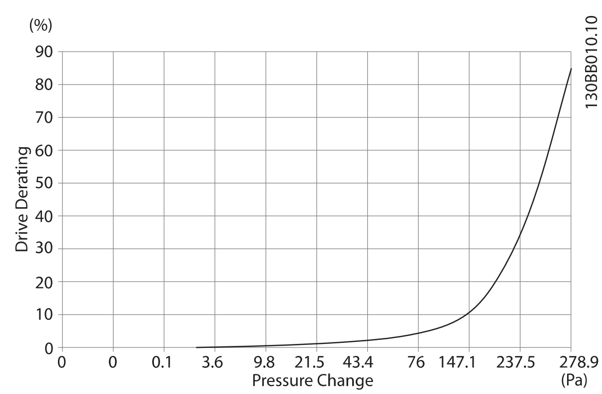


Illustration 3.30: E Frame Derating vs. Pressure Change (Small Fan), P250T5 and P355T7-P400T7

Drive air flow: 650 cfm (1105 m3/h)

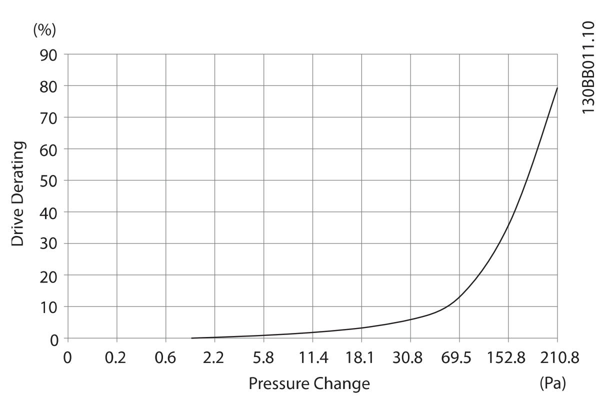
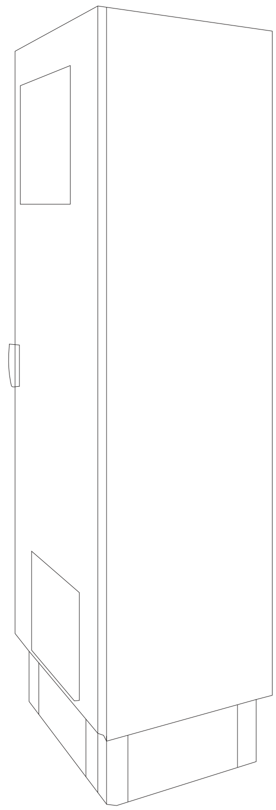


Illustration 3.31: E Frame Derating vs. Pressure Change (Large Fan), P315T5-P400T5 and P500T7-P560T7

Drive air flow: 850 cfm (1445 m3/h)

3

3.7.2 Outside Installation/ NEMA 3R Kit for Rittal Enclosures



This section is for the installation of NEMA 3R kits available for the frequency converter frames D3, D4 and E2. These kits are designed and tested to be used with IP00/ Chassis versions of these frames in Rittal TS8 NEMA 3R or NEMA 4 enclosures. The NEMA-3R enclosure is an outdoor enclosure that provides a degree of protection against rain and ice. The NEMA-4 enclosure is an outdoor enclosure that provides a greater degree of protection against weather and hosed water.

The minimum enclosure depth is 500 mm (600 mm for E2 frame) and the kit is designed for a 600 mm (800 mm for E2 frame) wide enclosure. Other enclosure widths are possible, however additional Rittal hardware is required. The maximum depth and width are as required by the installation.

NB!

The current rating of drives in D3 and D4 frames are de-rated by 3%, when adding the NEMA 3R kit. Drives in E2 frames require no derating

NB!

A door-fan(s) is required on the Rittal cabinet to remove the loses not contained in the back-channel of the drive. The minimum door-fan(s) airflow required at the drive maximum ambient for the D3 and D4 is 391 m^3/h (230 cfm). The minimum door-fan(s) airflow required at the drive maximum ambient for the E2 is 782 m^3/h (460 cfm). If the ambient is below maximum or if additional components, heat loses, are added within the enclosure a calculation must be made to ensure the proper airflow is provided to cool the inside of the Rittal enclosure.

Ordering information
Frame size D3: 176F4600
Frame size D4: 176F4601
Frame size E2: 176F1852

Kit contents:

- Ductwork components
- Mounting hardware
- 16 mm, M5 torx screws for top vent cover
- 10 mm, M5 for attaching drive mounting plate to enclosure
- M10 nuts to attach drive to mounting plate
- Gasket material

NB!
Please see the instructions *175R5922* for further information

3.7.3 Installation on Pedestal

This section describes the installation of a pedestal unit available for the frequency converters frames D1 and D2. This is a 200 mm high pedestal that allows these frames to be floor mounted. The front of the pedestal has openings for input air to the power components.

The frequency converter gland plate must be installed to provide adequate cooling air to the control components of the frequency converter via the door fan and to maintain the IP21/NEMA 1 or IP54/NEMA 12 degrees of enclosure protections.

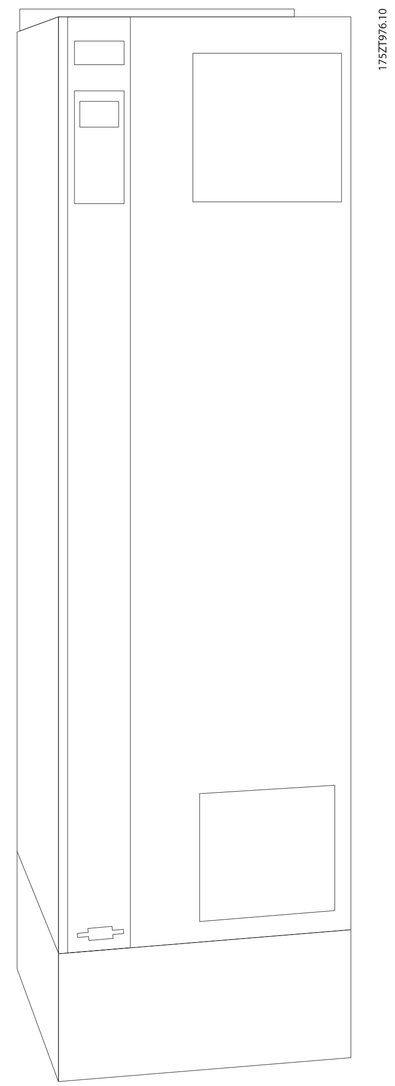


Illustration 3.32: Drive on pedestal

There is one pedestal that fits both frames D1 and D2. Its ordering number is 176F1827. The pedestal is standard for E1 frame.

Required Tools:

- Socket wrench with 7-17 mm sockets
- T30 Torx Driver

Torques:

- M6 - 4.0 Nm (35 in-lbs)
- M8 - 9.8 Nm (85 in-lbs)
- M10 - 19.6 Nm (170 in-lbs)

Kit Contents:

- Pedestal parts
- Instruction manual

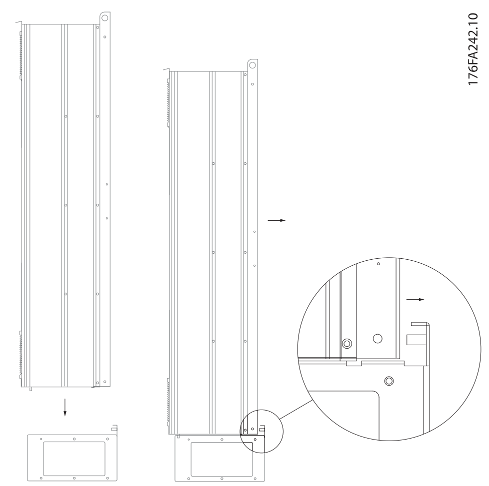


Illustration 3.33: Mounting of drive to pedestal.

3.7.4 Floor Mounting - Pedestal Installation IP21 (NEMA1) and IP54 (NEMA12)

Install the pedestal on the floor. Fixing holes are to be drilled according to this figure:

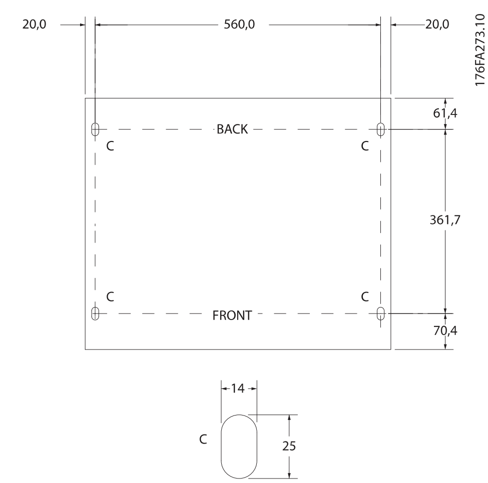


Illustration 3.34: Drill master for fixing holes in floor.

3

Mount the drive on the pedestal and fix it with the included bolts to the pedestal as shown on the illustration.

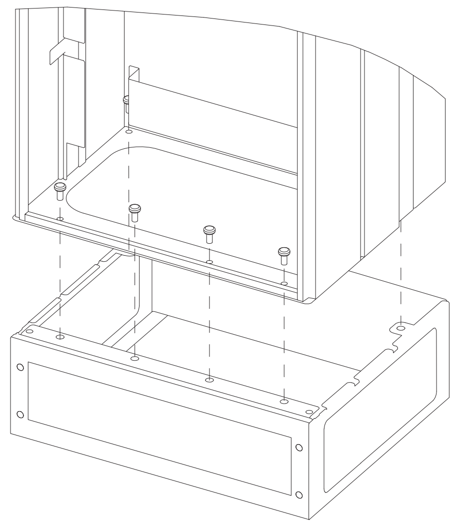


Illustration 3.35: Mounting of drive to pedestal

NB!
Please see the *Pedestal Kit Instruction Manual, 175R5642*, for further information.

3.7.5 Input Plate Option

This section is for the field installation of input option kits available for frequency converters in all D and E frames.
Do not attempt to remove RFI filters from input plates. Damage may occur to RFI filters if they are removed from the input plate.

NB!
Where RFI filters are available, there are two different type of RFI filters depending on the input plate combination and the RFI filters interchangeable. Field installable kits in certain cases are the same for all voltages.

	380 - 480 V	Fuses	Disconnect Fuses	RFI	RFI Fuses	RFI Disconnect Fuses
D1	All D1 power sizes	176F8442	176F8450	176F8444	176F8448	176F8446
D2	All D2 power sizes	176F8443	176F8441	176F8445	176F8449	176F8447
E1	315 kW	176F0253	176F0255	176F0257	176F0258	176F0260
	355 - 450 kW	176F0254	176F0256	176F0257	176F0259	176F0262

	525 - 690 V	Fuses	Disconnect Fuses	RFI	RFI Fuses	RFI Disconnect Fuses
D1	45-90 kW	175L8829	175L8828	175L8777	NA	NA
	110-160 kW	175L8442	175L8445	175L8777	NA	NA
D2	All D2 power sizes	175L8827	175L8826	175L8825	NA	NA
E1	450-500 kW	176F0253	176F0255	NA	NA	NA
	560-630 kW	176F0254	176F0258	NA	NA	NA

Kit contents

- Input plate assembled
- Instruction sheet 175R5795
- Modification Label
- Disconnect handle template (units w/ mains disconnect)

Cautions

- Frequency converter contains dangerous voltages when connected to line voltage. No disassembly should be attempted with power applied
- Electrical parts of the frequency converter may contain dangerous voltages even after the mains have been disconnected. Wait the minimum time listed on the drive label after disconnecting the mains before touching any internal components to ensure that capacitors have fully discharged
- The input plates contain metal parts with sharp edges. Use hand protection when removing and reinstalling.
- E frames input plates are heavy (20-35 kg depending on configuration). It is recommended that the disconnect switch be removed from input plate for easier installation and be reinstalled on the input plate after the input plate has been installed on the drive

NB!
For further information, please see the Instruction Sheet, *175R5795*

3.7.6 Installation of Mains Shield for Frequency Converters

This section is for the installation of a mains shield for the frequency converter series with D1, D2 and E1 frames. It is not possible to install in the IP00/ Chassis versions as these have included as standard a metal cover. These shields satisfy VBG-4 requirements.

Ordering numbers:
Frames D1 and D2 : 176F0799
Frame E1: 176F1851

Torque requirements

M6 - 35 in-lbs (4.0 N-M)

M8 - 85 in-lbs (9.8 N-M)

M10 - 170 in-lbs (19.6 N-M)

NB!
For further information, please see the Instruction Sheet, *175R5923*

3

3.7.7 Frame size F Panel Options

Space Heaters and Thermostat
Mounted on the cabinet interior of frame size F frequency converters, space heaters controlled via automatic thermostat help control humidity inside the enclosure, extending the lifetime of drive components in damp environments.

Cabinet Light with Power Outlet
A light mounted on the cabinet interior of frame size F frequency converters increase visibility during servicing and maintenance. The housing the light includes a power outlet for temporarily powering tools or other devices, available in two voltages:

- 230V, 50Hz, 2.5A, CE/ENEC
- 120V, 60Hz, 5A, UL/cUL

Transformer Tap Setup
If the Cabinet Light & Outlet and/or the Space Heaters & Thermostat are installed Transformer T1 requires it taps to be set to the proper input voltage. A 380-480/ 500 V380-480 V drive will initially be set to the 525 V tap and a 525-690 V drive will be set to the 690 V tap to insure no over-voltage of secondary equipment occurs if the tap is not changed prior to power being applied. See the table below to set the proper tap at terminal T1 located in the rectifier cabinet. For location in the drive, see illustration of rectifier in the *Power Connections* section.

Input Voltage Range	Tap to Select
380V-440V	400V
441V-490V	460V
491V-550V	525V
551V-625V	575V
626V-660V	660V
661V-690V	690V

NAMUR Terminals
NAMUR is an international association of automation technology users in the process industries, primarily chemical and pharmaceutical industries in Germany. Selection of this option provides terminals organized and labeled to the specifications of the NAMUR standard for drive input and output terminals. This requires MCB 112 PTC Thermistor Card and MCB 113 Extended Relay Card.

RCD (Residual Current Device)
Uses the core balance method to monitor ground fault currents in grounded and high-resistance grounded systems (TN and TT systems in IEC terminology). There is a pre-warning (50% of main alarm set-point) and a main alarm set-point. Associated with each set-point is an SPDT alarm relay for external use. Requires an external “window-type” current transformer (supplied and installed by customer).

- Integrated into the drive’s safe-stop circuit
- IEC 60755 Type B device monitors AC, pulsed DC, and pure DC ground fault currents
- LED bar graph indicator of the ground fault current level from 10–100% of the set-point
- Fault memory
- TEST / RESET button

Insulation Resistance Monitor (IRM)
Monitors the insulation resistance in ungrounded systems (IT systems in IEC terminology) between the system phase conductors and ground. There is an ohmic pre-warning and a main alarm set-point for the insulation level. Associated with each set-point is an SPDT alarm relay for external use. Note: only one insulation resistance monitor can be connected to each ungrounded (IT) system.

- Integrated into the drive’s safe-stop circuit
- LCD display of the ohmic value of the insulation resistance

- Fault Memory
- INFO, TEST, and RESET buttons

IEC Emergency Stop with Pilz Safety Relay

Includes a redundant 4-wire emergency-stop push-button mounted on the front of the enclosure and a Pilz relay that monitors it in conjunction with the drive's safe-stop circuit and the mains contactor located in the options cabinet.

Manual Motor Starters

Provide 3-phase power for electric blowers often required for larger motors. Power for the starters is provided from the load side of any supplied contactor, circuit breaker, or disconnect switch. Power is fused before each motor starter, and is off when the incoming power to the drive is off. Up to two starters are allowed (one if a 30A, fuse-protected circuit is ordered). Integrated into the drive's safe-stop circuit.
Unit features include:

- Operation switch (on/off)
- Short-circuit and overload protection with test function
- Manual reset function

30 Ampere, Fuse-Protected Terminals

- 3-phase power matching incoming mains voltage for powering auxiliary customer equipment
- Not available if two manual motor starters are selected
- Terminals are off when the incoming power to the drive is off
- Power for the fused protected terminals will be provided from the load side of any supplied contactor, circuit breaker, or disconnect switch.

24 VDC Power Supply

- 5 amp, 120 W, 24 VDC
- Protected against output over-current, overload, short circuits, and over-temperature
- For powering customer-supplied accessory devices such as sensors, PLC I/O, contactors, temperature probes, indicator lights, and/or other electronic hardware
- Diagnostics include a dry DC-ok contact, a green DC-ok LED, and a red overload LED

External Temperature Monitoring

Designed for monitoring temperatures of external system components, such as the motor windings and/or bearings. Includes eight universal input modules plus two dedicated thermistor input modules. All ten modules are integrated into the drive's safe-stop circuit and can be monitored via a fieldbus network (requires the purchase of a separate module/bus coupler).

Universal inputs (8)

Signal types:

- RTD inputs (including Pt100), 3-wire or 4-wire
- Thermocouple
- Analog current or analog voltage

Additional features:

- One universal output, configurable for analog voltage or analog current
- Two output relays (N.O.)
- Dual-line LC display and LED diagnostics
- Sensor lead wire break, short-circuit, and incorrect polarity detection
- Interface setup software

Dedicated thermistor inputs (2)

Features:

- Each module capable of monitoring up to six thermistors in series
- Fault diagnostics for wire breakage or short-circuits of sensor leads
- ATEX/UL/CSA certification
- A third thermistor input can be provided by the PTC Thermistor Option Card MCB 112, if necessary

4 How to Order

4.1 Ordering Form

4.1.1 Drive Configurator

It is possible to design a VLT Automation VT Drive frequency converter according to the application requirements by using the ordering number system.

For the VLT Automation VT Drive, you can order standard drives and drives with integral options by sending a type code string describing the product a to the Danfoss sales office, i.e.:

FC-322P18KT4E21H1XGCXXXSXXXXAGBKCXXXXDX

The meaning of the characters in the string can be located in the pages containing the ordering numbers in the chapter *How to Select Your VLT*. In the example above, a Profibus LON works option and a General purpose I/O option is included in the drive.

Ordering numbers for VLT Automation VT Drive standard variants can also be located in the chapter *How to Select Your VLT*.

From the Internet based Drive Configurator, you can configure the right drive for the right application and generate the type code string. The Drive Configurator will automatically generate an eight-digit sales number to be delivered to your local sales office.
Furthermore, you can establish a project list with several products and send it to a Danfoss sales representative.

The Drive Configurator can be found on the global Internet site: www.danfoss.com/drives.

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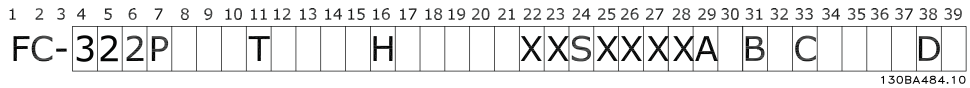
4.1.2 Type Code String



Description	Pos.:	Possible choice
Product group & VLT Series	1-6	FC322
Power rating	7-10	0.25 - 1200 kW
Number of phases	11	Three phases (T)
Mains voltage	11-12	S2: 220-240 VAC single phase S4: 380-480 VAC single phase T 2: 200-240 VAC T 4: 380-480 VAC T 6: 525-600 VAC T 7: 525-690 VAC
Enclosure	13-15	E20: IP20 E21: IP 21/NEMA Type 1 E55: IP 55/NEMA Type 12 E2M: IP21/NEMA Type 1 w/mains shield E5M: IP 55/NEMA Type 12 w/mains shield E66: IP66 F21: IP21 kit without backplate G21: IP21 kit with backplate P20: IP20/Chassis with backplate P21: IP21/NEMA Type 1 w/backplate P55: IP55/NEMA Type 12 w/backplate
RFI filter	16-17	HX: No RFI filter H1: RFI filter class A1/B H2: RFI filter class A2 H3: RFI filter class A1/B (reduced cable length) H4: RFI filter class A2/A1
Brake	18	X: No brake chopper included B: Brake chopper included T: Safe Stop U: Safe + brake
Display	19	G: Graphical Local Control Panel (GLCP) N: Numeric Local Control Panel (NLCP) X: No Local Control Panel
Coating PCB	20	X. No coated PCB C: Coated PCB
Mains option	21	D: Loadsharing X: No Mains disconnect switch 8: Mains Disconnect + Loadsharing
Cable entries	22	X: Standard cable entries O: European metric thread in cable entries
	23	Reserved
Software release	24-27	Actual software version
Software language	28	
A options	29-30	AX: No options

Description	Pos.:	Possible choice
		A0: MCA 101 Profibus DP V1 A4: MCA 104 DeviceNet AN: MCA 121 Ethernet IP
B options	31-32	BX: No option BK: MCB 101 General purpose I/O option BP: MCB 105 Relay option BO:MCB 109 Analog I/O option BY: MCO 101 Extended Cascade Control
C_0 options	33-34	CX: No options
C_1 options	35	X: No options 5: MCO 102 Advanced Cascade Control
C option software	36-37	XX: Standard software
D options	38-39	DX: No option D0: DC backup
The various options are described further in this Design Guide.		

Table 4.1: Type code description.

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4.1.3 Type Code String High Power

Ordering type code frame sizes D and E

Description	Pos	Possible choice
Product group	1-3	
Drive series	4-6	
Power rating	8-10	45-560 kW
Phases	11	Three phases (T)
Mains voltage	11- 12	T 5: 380-500 V AC T 7: 525-690 V AC
Enclosure	13- 15	E00: IP00/Chassis C00: IP00/Chassis w/ stainless steel back channel E0D: IP00/Chassis, D3 P37K-P75K, T7 C0D: IP00/Chassis w/ stainless steel back channel, D3 P37K-P75K, T7 E21: IP 21/ NEMA Type 1 E54: IP 54/ NEMA Type 12 E2D: IP 21/ NEMA Type 1, D1 P37K-P75K, T7 E5D: IP 54/ NEMA Type 12, D1 P37K-P75K, T7 E2M: IP 21/ NEMA Type 1 with mains shield E5M: IP 54/ NEMA Type 12 with mains shield
RFI filter	16- 17	H2: RFI filter, class A2 (standard) H4: RFI filter class A1 1) H6: RFI filter Maritime use 2)
Brake	18	B: Brake IGBT mounted X: No brake IGBT R: Regeneration terminals (E frames only)
Display	19	G: Graphical Local Control Panel LCP N: Numerical Local Control Panel (LCP) X: No Local Control Panel (D frames IP00 and IP 21 only)
Coating PCB	20	C: Coated PCB X. No coated PCB (D frames 380-480/500 V only)
Mains option	21	X: No mains option 3: Mains disconnect and Fuse 5: Mains disconnect, Fuse and Load sharing 7: Fuse A: Fuse and Load sharing D: Load sharing
Adaptation	22	Reserved
Adaptation	23	Reserved
Software release	24- 27	Actual software
Software language	28	
A options	29-30	AX: No options A0: MCA 101 Profibus DP V1 A4: MCA 104 DeviceNet AN: MCA 121 Ethernet IP
B options	31-32	BX: No option BK: MCB 101 General purpose I/O option BP: MCB 105 Relay option BO:MCB 109 Analog I/O option BY: MCO 101 Extended Cascade Control
C_0 options	33-34	CX: No options
C_1 options	35	X: No options 5: MCO 102 Advanced Cascade Control
C option software	36-37	XX: Standard software
D options	38-39	DX: No option D0: DC backup
The various options are described further in this Design Guide.		
1): Available for all D frames. E frames 380-480/500 V only		
2) Consult factory for applications requiring maritime certification		

4.2 Ordering Numbers

4.2.1 Ordering Numbers: Options and Accessories

Type	Description	Ordering no.	
Miscellaneous hardware			
DC link connector	Terminal block for DC link connection, frame size A2/A3	130B1064	
IP 21/4X top/TYPE 1 kit	Enclosure, frame size A2: IP21/IP 4X Top/TYPE 1	130B1122	
IP 21/4X top/TYPE 1 kit	Enclosure, frame size A3: IP21/IP 4X Top/TYPE 1	130B1123	
IP21/TYPE 1 Kit	Top and bottom, frame size B3	130B1187	
IP21/TYPE 1 Kit	Top and bottom, frame size B4	130B1189	
IP21/TYPE 1 Kit	Top and bottom, frame size C3	130B1191	
IP21/TYPE 1 Kit	Top and bottom, frame size C4	130B1193	
IP21/TYPE 1 Kit	Top, frame size B3	130B1188	
IP21/TYPE 1 Kit	Top, frame size B4	130B1190	
IP21/TYPE 1 Kit	Top, frame size C3	130B1192	
IP21/TYPE 1 Kit	Top, frame size C4	130B1194	
MCF 110 panel	Panel Through Mounting Kit, frame size A5	130B1028	
MCF 110 panel	Panel Through Mounting Kit, frame size B1	130B1046	
MCF 110 panel	Panel Through Mounting Kit, frame size B2	130B1047	
MCF 110 panel	Panel Through Mounting Kit, frame size C1	130B1048	
MCF 110 panel	Panel Through Mounting Kit, frame size C2	130B1049	
Profibus D-Sub 9	Connector kit for IP20	130B1112	
MCF 103	USB Cable 350 mm, IP55/66	130B1155	
MCF 103	USB Cable 650 mm, IP55/66	130B1156	
Profibus top entry kit	Top entry kit for Profibus connection - only A enclosures	130B0524[1)]	
Terminal blocks	Screw terminal blocks for replacing spring loaded terminals 1 pc 10 pin 1 pc 6 pin and 1 pc 3 pin connectors	130B1116	
Backplate	IP21 / NEMA 1 enclosure Top Cover A2	130B1132	
Backplate	IP21 / NEMA 1 enclosure Top Cover A3	130B1133	
Backplate	A5, IP55 / NEMA 12	130B1098	
Backplate	B1, IP21 / IP55 / NEMA 12	130B3383	
Backplate	B2, IP21 / IP55 / NEMA 12	130B3397	
Backplate	C1, IP21 / IP55 / NEMA 12	130B3910	
Backplate	C2, IP21 / IP55 / NEMA 12	130B3911	
Backplate	A5, IP66 / NEMA 4x	130B3242	
Backplate	B1, IP66 / NEMA 4x	130B3434	
Backplate	B2, IP66 / NEMA 4x	130B3465	
Backplate	C1, IP66 / NEMA 4x	130B3468	
Backplate	C2, IP66 / NEMA 4x	130B3491	
LCP			
LCP 101	Numerical Local Control Panel (NLCP)	130B1124	
LCP 102	Graphical Local Control Panel (GLCP)	130B1107	
LCP cable	Separate LCP cable, 3 m	175Z0929	
LCP kit	Panel mounting kit including graphical LCP, fasteners, 3 m cable and gasket	130B1113	
LCP kit	Panel mounting kit including numerical LCP, fasteners and gasket	130B1114	
LCP kit	Panel mounting kit for all LCPs including fasteners, 3 m cable and gasket	130B1117	
LCP kit	Panel mounting kit for all LCPs including fasteners and gasket - without cable	130B1170	
LCP kit	Panel mounting kit for all LCPs including fasteners, 8 m cable, glands and gasket for IP55/66 enclosures	130B1129	
Options for Slot A Uncoated / Coated		**Uncoated**	**Coated**
MCA 101	Profibus option DP V0/V1	130B1100	130B1200
MCA 104	DeviceNet option	130B1102	130B1202
MCA 108	LON works	130B1106	130B1206

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Type	Description	Ordering no.	
Options for Slot B			
MCB 101	General purpose Input Output option	130B1125	130B1212
MCB 105	Relay option	130B1110	130B1210
MCB 109	Analog I/O option	130B1143	130B1243
MCB 114	PT 100 / PT 1000 sensor input	130B1172	10B1272
MCO 101	Extended Cascade Control	130B1118	130B1218
Options for C0			
Mounting kit for frame size A2 and A3 (40 mm for one C option)		130B7530	
Mounting kit for frame size A2 and A3 (60 mm for C0 + C1 option)		130B7531	
Mounting kit for frame size A5		130B7532	
Mounting kit for frame size B, C, D. E and F2 and 3 (except B3)		130B7533	
Mounting kit for frame size B3 (40 mm for one C option)		130B1413	
Mounting kit for frame size B3 (60 mm for C0 + C1 option)		130B1414	
Option for Slot C			
MCO 102	Advanced Cascade Control	130B1154	130B1254
Option for Slot D			
MCB 107	24 V DC back-up	130B1108	130B1208

Type	Description	Ordering no.	
External Options			
Ethernet IP	Ethernet	130B1119	130B1219
Spare Parts			
Control board VLT Automation VT Drive	With Safe Stop Function		130B1167
Control board VLT Automation VT Drive	Without Safe Stop Function		130B1168
Accessory bag Control Terminals		130B0295	
Fan A2	Fan, frame size A2	130B1009	
Fan A3	Fan, frame size A3	130B1010	
Fan A5	Fan, frame size A5	130B1017	
Fan B1	Fan external, frame size B1	130B1013	
Fan B2	Fan external, frame size B2	130B1015	
Fan B3	Fan external, frame size B3		130B3563
Fan B4	Fan external, frame size B4		130B3699
Fan B4	Fan external, frame size B5		130B3701
Fan C1	Fan external, frame size C1	130B3865	
Fan C2	Fan external, frame size C2	130B3867	
Fan C3	Fan external, frame size C3		130B4292
Fan C4	Fan external, frame size C4		130B4294
Accessory bag A2	Accessory bag, frame size A2	130B0509	
Accessory bag A3	Accessory bag, frame size A3	130B0510	
Accessory bag A5	Accessory bag, frame size A5	130B1023	
Accessory bag B1	Accessory bag, frame size B1	130B2060	
Accessory bag B2	Accessory bag, frame size B2	130B2061	
Accessory bag B3	Accessory bag, frame size B3	130B0980	
Accessory bag B4	Accessory bag, frame size B4	130B1300	Small
Accessory bag B4	Accessory bag, frame size B4	130B1301	Big
Accessory bag C1	Accessory bag, frame size C1	130B0046	
Accessory bag C2	Accessory bag, frame size C2	130B0047	
Accessory bag C3	Accessory bag, frame size C3	130B0981	
Accessory bag C4	Accessory bag, frame size C4	130B0982	Small
Accessory bag C4	Accessory bag, frame size C4	130B0983	Big

1) Only IP21 / > 11 kW

Options can be ordered as factory built-in options, see ordering information.

For information on fieldbus and application option compatibility with older software versions, please contact your Danfoss supplier.

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4.2.2 Ordering Numbers: Harmonic Filters

Harmonic filters are used to reduce mains harmonics.

- AHF 010: 10% current distortion
- AHF 005: 5% current distortion

380-415V, 50Hz

$I_{AHF,N}$	Typical Motor Used [kW]	Danfoss ordering number		Frequency converter size
		AHF 005	AHF 010	
10 A	1.1 - 4	175G6600	175G6622	P1K1, P4K0
19 A	5.5 - 7.5	175G6601	175G6623	P5K5 - P7K5
26 A	11	175G6602	175G6624	P11K
35 A	15 - 18.5	175G6603	175G6625	P15K - P18K
43 A	22	175G6604	175G6626	P22K
72 A	30 - 37	175G6605	175G6627	P30K - P37K
101A	45 - 55	175G6606	175G6628	P45K - P55K
144 A	75	175G6607	175G6629	P75K
180 A	90	175G6608	175G6630	P90K
217 A	110	175G6609	175G6631	P110
289 A	132 - 160	175G6610	175G6632	P132 - P160
324 A		175G6611	175G6633	
370 A	200	175G6688	175G6691	P200
506 A	250	175G6609 + 175G6610	175G6631 + 175G6632	P250
578 A	315	2x 175G6610	2x 175G6632	P315
648 A	400	2x175G6611	2x175G6633	P400

380 - 415V, 60Hz

$I_{AHF,N}$	Typical Motor Used [HP]	Danfoss ordering number		Frequency converter size
		AHF 005	AHF 010	
19 A	10 - 15	130B2460	130B2472	P5K5 - P7K5
26 A	20	130B2461	130B2473	P11K
35 A	25 - 30	130B2462	130B2474	P15K, P18K
43 A	40	130B2463	130B2475	P22K
72 A	50 - 60	130B2464	130B2476	P30K - P37K
101A	75	130B2465	130B2477	P45K - P55K
144 A	100 - 125	130B2466	130B2478	P75K
180 A	150	130B2467	130B2479	P90K
217 A	200	130B2468	130B2480	P110
289 A	250	130B2469	130B2481	P132
324 A	300	130B2470	130B2482	P160
370 A	350	130B2471	130B2483	P200
506 A	450	130B2468 + 130B2469	130B2480 + 130B2481	P250
578 A	500	2x 130B2469	2x 130B2481	P315
648 A	500	2x130B2470	2x130B2482	P355

440-480V, 60Hz

$I_{AHF,N}$	Typical Motor Used [HP]	Danfoss ordering number		Frequency converter size
		AHF 005	AHF 010	
19 A	10 - 15	175G6612	175G6634	P11K
26 A	20	175G6613	175G6635	P15K
35 A	25 - 30	175G6614	175G6636	P18K, P22K
43 A	40	175G6615	175G6637	P30K
72 A	50 - 60	175G6616	175G6638	P37K - P45K
101A	75	175G6617	175G6639	P55K
144 A	100 - 125	175G6618	175G6640	P75K
180 A	150	175G6619	175G6641	P90
217 A	200	175G6620	175G6642	P110
289 A	250	175G6621	175G6643	P132 - P160
324 A	300	175G6689	175G6692	
370 A	350	175G6690	175G6693	P200
434 A	350	2x175G6620	2x175G6642	P250
578 A	500	2x 175G6621	2x 175G6643	P315 - P355
659 A	550-600	175G6690 + 175G6621	175G6693 + 175G6643	P400

Matching the frequency converter and filter is pre-calculated based on 400V/480V and on a typical motor load (4 pole) and 110 % torque.

500-525V, 50Hz

$I_{AHF,N}$	Typical Motor Used [kW]	Danfoss ordering number		Frequency converter size
		AHF 005	AHF 010	
10 A	0.75 - 5.5	175G6644	175G6656	PK75 - P5K5
19 A	7.5 - 11	175G6645	175G6657	P7K5 - P11K
26 A	15 18.5	175G6646	175G6658	P15K - P18K
35 A	22	175G6647	175G6659	P22K
43 A	30	175G6648	175G6660	P30K
72 A	37 -45	175G6649	175G6661	P37K - P45K
101 A	55 - 75	175G6650	175G6662	P55K - P75K
144 A	90 - 110	175G6651	175G6663	P90K - P110
180 A	132	175G6652	175G6664	P132
217 A	160	175G6653	175G6665	P160
289 A	200	175G6654	175G6666	P200
324 A	250	175G6655	175G6667	P250
370 A	315	2x175G6653	2x175G6665	P315 - P400
578 A	400	2X 175G6654	2X 175G6666	P500 - P560

690V, 50Hz

$I_{AHF,N}$	Typical Motor Used [kW]	Danfoss ordering number		Frequency converter size
		AHF 005	AHF 010	
43	37 - 45	130B2328	130B2293	
72	55 - 75	130B2330	130B2295	P37K - P45K
101	90	130B2331	130B2296	P55K - P75K
144 A	110 - 132	130B2333	130B2298	P90K - P110
180 A	160	130B2334	130B2299	P132
217 A	200	130B2335	130B2300	P160
289 A	250	130B2331+2333	130B2301	P200
324 A	315	130B2333+2334	130B2302	P250
370 A	400	130B2334+2335	130B2304	P315

4.2.3 Ordering Numbers: Sine Wave Filter Modules, 200-500 VAC

Mains supply 3 x 200 to 500 V

Frequency converter size			Minimum switching frequency	Maximum output frequency	Part No. IP20	Part No. IP00	Rated filter current at 50Hz
200-240V	**380-440V**	**440-500V**					
PK25	PK37	PK37	5 kHz	120 Hz	130B2439	130B2404	2.5 A
PK37	PK55	PK55	5 kHz	120 Hz	130B2439	130B2404	2.5 A
	PK75	PK75	5 kHz	120 Hz	130B2439	130B2404	2.5 A
PK55	P1K1	P1K1	5 kHz	120 Hz	130B2441	130B2406	4.5 A
	P1K5	P1K5	5 kHz	120 Hz	130B2441	130B2406	4.5 A
PK75	P2K2	P2K2	5 kHz	120 Hz	130B2443	130B2408	8 A
P1K1	P3K0	P3K0	5 kHz	120 Hz	130B2443	130B2408	8 A
P1K5			5 kHz	120 Hz	130B2443	130B2408	8 A
	P4K0	P4K0	5 kHz	120 Hz	130B2444	130B2409	10 A
P2K2	P5K5	P5K5	5 kHz	120 Hz	130B2446	130B2411	17 A
P3K0	P7K5	P7K5	5 kHz	120 Hz	130B2446	130B2411	17 A
P4K0			5 kHz	120 Hz	130B2446	130B2411	17 A
P5K5	P11K	P11K	4 kHz	60 Hz	130B2447	130B2412	24 A
P7K5	P15K	P15K	4 kHz	60 Hz	130B2448	130B2413	38 A
	P18K	P18K	4 kHz	60 Hz	130B2448	130B2413	38 A
P11K	P22K	P22K	4 kHz	60 Hz	130B2307	130B2281	48 A
P15K	P30K	P30K	3 kHz	60 Hz	130B2308	130B2282	62 A
P18K	P37K	P37K	3 kHz	60 Hz	130B2309	130B2283	75 A
P22K	P45K	P55K	3 kHz	60 Hz	130B2310	130B2284	115 A
P30K	P55K	P75K	3 kHz	60 Hz	130B2310	130B2284	115 A
P37K	P75K	P90K	3 kHz	60 Hz	130B2311	130B2285	180 A
P45K	P90K	P110	3 kHz	60 Hz	130B2311	130B2285	180 A
	P110	P132	3 kHz	60 Hz	130B2312	130B2286	260 A
	P132	P160	3 kHz	60 Hz	130B2312	130B2286	260 A
	P160	P200	3 kHz	60 Hz	130B2313	130B2287	410 A
	P200	P250	3 kHz	60 Hz	130B2313	130B2287	410 A
	P250	P315	3 kHz	60 Hz	130B2314	130B2288	480 A
	P315	P355	2 kHz	60 Hz	130B2315	130B2289	660 A
	P355	P400	2 kHz	60 Hz	130B2315	130B2289	660 A
	P400	P450	2 kHz	60 Hz	130B2316	130B2290	750 A
	P450	P500	2 kHz	60 Hz	130B2317	130B2291	880 A
	P500	P560	2 kHz	60 Hz	130B2317	130B2291	880 A
	P560	P630	2 kHz	60 Hz	130B2318	130B2292	1200 A
	P630	P710	2 kHz	60 Hz	130B2318	130B2292	1200 A

NB!

When using Sine-wave filters, the switching frequency should comply with filter specifications in par. 14-01 *Switching Frequency*.

4.2.4 Ordering Numbers: Sine Wave Filter Modules, 200-500 VAC

Mains supply 3 x 200 to 500 V

Frequency converter size			Minimum switching frequency	Maximum output frequency	Part No. IP20	Part No. IP00	Rated filter current at 50Hz
200-240V	**380-440V**	**440-500V**					
PK25	PK37	PK37	5 kHz	120 Hz	130B2439	130B2404	2.5 A
PK37	PK55	PK55	5 kHz	120 Hz	130B2439	130B2404	2.5 A
	PK75	PK75	5 kHz	120 Hz	130B2439	130B2404	2.5 A
PK55	P1K1	P1K1	5 kHz	120 Hz	130B2441	130B2406	4.5 A
	P1K5	P1K5	5 kHz	120 Hz	130B2441	130B2406	4.5 A
PK75	P2K2	P2K2	5 kHz	120 Hz	130B2443	130B2408	8 A
P1K1	P3K0	P3K0	5 kHz	120 Hz	130B2443	130B2408	8 A
P1K5			5 kHz	120 Hz	130B2443	130B2408	8 A
	P4K0	P4K0	5 kHz	120 Hz	130B2444	130B2409	10 A
P2K2	P5K5	P5K5	5 kHz	120 Hz	130B2446	130B2411	17 A
P3K0	P7K5	P7K5	5 kHz	120 Hz	130B2446	130B2411	17 A
P4K0			5 kHz	120 Hz	130B2446	130B2411	17 A
P5K5	P11K	P11K	4 kHz	60 Hz	130B2447	130B2412	24 A
P7K5	P15K	P15K	4 kHz	60 Hz	130B2448	130B2413	38 A
	P18K	P18K	4 kHz	60 Hz	130B2448	130B2413	38 A
P11K	P22K	P22K	4 kHz	60 Hz	130B2307	130B2281	48 A
P15K	P30K	P30K	3 kHz	60 Hz	130B2308	130B2282	62 A
P18K	P37K	P37K	3 kHz	60 Hz	130B2309	130B2283	75 A
P22K	P45K	P55K	3 kHz	60 Hz	130B2310	130B2284	115 A
P30K	P55K	P75K	3 kHz	60 Hz	130B2310	130B2284	115 A
P37K	P75K	P90K	3 kHz	60 Hz	130B2311	130B2285	180 A
P45K	P90K	P110	3 kHz	60 Hz	130B2311	130B2285	180 A
	P110	P132	3 kHz	60 Hz	130B2312	130B2286	260 A
	P132	P160	3 kHz	60 Hz	130B2312	130B2286	260 A
	P160	P200	3 kHz	60 Hz	130B2313	130B2287	410 A
	P200	P250	3 kHz	60 Hz	130B2313	130B2287	410 A
	P250	P315	3 kHz	60 Hz	130B2314	130B2288	480 A
	P315	P355	2 kHz	60 Hz	130B2315	130B2289	660 A
	P355	P400	2 kHz	60 Hz	130B2315	130B2289	660 A
	P400	P450	2 kHz	60 Hz	130B2316	130B2290	750 A
	P450	P500	2 kHz	60 Hz	130B2317	130B2291	880 A
	P500	P560	2 kHz	60 Hz	130B2317	130B2291	880 A
	P560	P630	2 kHz	60 Hz	130B2318	130B2292	1200 A
	P630	P710	2 kHz	60 Hz	130B2318	130B2292	1200 A

NB!
When using Sine-wave filters, the switching frequency should comply with filter specifications in par. 14-01 *Switching Frequency*.

4.2.5 Ordering Numbers: Sine Wave Filters, 525-600/690 VAC

Frequency converter size [kW]				Part No. Danfoss	
525-600 V	**525-690 V**	Current at 50 Hz [A]	Minimum switching frequency [kHz]	**IP00**	**IP20**
0.75	-	13	2	130B2321	130B2341
1.1	-				
1.5	-				
2.2	-				
3.0	-				
4.0	-				
5.5	-				
7.5	-				
-	11	28	2	130B2322	130B2342
11	15				
15	18.5				
18.5	22				
22	30	45	2	130B2323	130B2343
30	37				
37	45	76	2	130B2324	130B2344
45	55				
55	75	115	2	130B2325	130B2345
75	90				
90	110	165	2	130B2326	130B2346
110	132				
150	160	260	2	130B2327	130B2347
180	200				
220	250	303	2	130B2329	130B2348
260	315	430	1.5	130B2241	130B2270
300	400				
375	500	530	1.5	130B2242	130B2271
450	560	660	1.5	130B2337	130B2381
480	630				
560	710	765	1.5	130B2338	130B2382
670	800	940	1.5	130B2339	130B2383
-	900				
820	1000	1320	1.5	130B2340	130B2384
970	1200				

Table 4.2: Mains supply 3x525-690 V

4.2.6 Ordering Numbers: du/dt Filters, 380-480 VAC

Mains supply 3x380 to 3x480 V

Frequency converter size		Minimum switching frequency	Maximum output frequency	Part No. IP20	Part No. IP00	Rated filter current at 50 Hz
380-440V	**441-480V**					
11 kW	11 kW	4 kHz	60 Hz	130B2396	130B2385	24 A
15 kW	15 kW	4 kHz	60 Hz	130B2397	130B2386	45 A
18.5 kW	18.5 kW	4 kHz	60 Hz	130B2397	130B2386	45 A
22 kW	22 kW	4 kHz	60 Hz	130B2397	130B2386	45 A
30 kW	30 kW	3 kHz	60 Hz	130B2398	130B2387	75 A
37 kW	37 kW	3 kHz	60 Hz	130B2398	130B2387	75 A
45 kW	55 kW	3 kHz	60 Hz	130B2399	130B2388	110 A
55 kW	75 kW	3 kHz	60 Hz	130B2399	130B2388	110 A
75 kW	90 kW	3 kHz	60 Hz	130B2400	130B2389	182 A
90 kW	110 kW	3 kHz	60 Hz	130B2400	130B2389	182 A
110 kW	132 kW	3 kHz	60 Hz	130B2401	130B2390	280 A
132 kW	160 kW	3 kHz	60 Hz	130B2401	130B2390	280 A
160 kW	200 kW	3 kHz	60 Hz	130B2402	130B2391	400 A
200 kW	250 kW	3 kHz	60 Hz	130B2402	130B2391	400 A
250 kW	315 kW	3 kHz	60 Hz	130B2277	130B2275	500 A
315 kW	355 kW	2 kHz	60 Hz	130B2278	130B2276	750 A
355 kW	400 kW	2 kHz	60 Hz	130B2278	130B2276	750 A
400 kW	450 kW	2 kHz	60 Hz	130B2278	130B2276	750 A
450 kW	500 kW	2 kHz	60 Hz	130B2405	130B2393	910 A
500 kW	560 kW	2 kHz	60 Hz	130B2405	130B2393	910 A
560 kW	630 kW	2 kHz	60 Hz	130B2407	130B2394	1500 A
630 kW	710 kW	2 kHz	60 Hz	130B2407	130B2394	1500 A
710 kW	800 kW	2 kHz	60 Hz	130B2407	130B2394	1500 A
800 kW	1000 kW	2 kHz	60 Hz	130B2407	130B2394	1500 A
1000 kW	1100 kW	2 kHz	60 Hz	130B2410	130B2395	2300 A

4.2.7 Ordering Numbers: du/dt Filters, 525-600/690 VAC

Frequency converter size [kW]				Part No. Danfoss	
525-600 V	**525-690 V**	Current [A]	Minimum switching frequency [Hz]	**IP00**	**IP20**
-	11	28	4	130B2414	130B2423
11	15				
15	18.5				
18.5	22				
22	30	45	4	130B2415	130B2424
30	37				
37	45	75	3	130B2416	130B2425
45	55				
55	75	115	3	130B2417	130B2426
75	90				
90	110	165	3	130B2418	130B2427
110	132				
150	160	260	3	130B2419	130B2428
180	200				
220	250	310	3	130B2420	130B2429
260	315	430	3	130B2235	130B2238
300	400				
375	500	530	2	130B2236	130B2239
450	560	630	2	130B2280	130B2274
480	630				
560	710	765	2	130B2421	130B2430
-	-				
670	800	1350	2	130B2422	130B2431
-	900				
820	1000				
970	1200				

Table 4.3: Mains supply 3x525-690 V

4

4.2.8 Ordering Numbers: Brake Resistors

NB!

When/where two resistors are listed in the tables - order two resistors.

Ordering Numbers: Brake Resistors

Mains 200-240 VAC (T2-LP+MP)

				VLT Automation VT Drive											
				Selected resistor											
				Standard IP 20								Flatpack IP65 for horizontal conveyors			Max. brake torque with R_{rec}
				Duty Cycle 10%				Duty Cycle 40%							
Size:	P_{motor}	R_{min}	$R_{br,nom}$	R_{rec}	$P_{br\ avg}$	Order no.	Period	R_{rec}	$P_{br\ avg}$	Order no.	Period	R_{rec} per item	Duty cycle	Order no.	
	[kW]	[Ω]	[Ω]	[Ω]	[kW]	175Uxxxx	[s]	[Ω]	[kW]	175Uxxxx	[s]	[Ω/w]	%	175Uxxxx	%
PK25	0.25	380	679	425	0.095	1841	120	425	0.43	1941	120	430/100	40	1002	110 (110)
PK37	0.37	380	459	425	0.095	1841	120	425	0.43	1941	120	430/100	40	1002	110 (110)
PK55	0.55	275	307	310	0.25	1842	120	310	0.80	1942	120	330/100	27	1003	109 (110)
PK55	0.55	275	307	310	0.25	1842	120	310	0.80	1942	120	310/200	55	0984	109 (110)
PK75	0.75	188	224	210	0.285	1843	120	210	1.35	1943	120	220/100	20	1004	110 (110)
PK75	0.75	188	224	210	0.285	1843	120	210	1.35	1943	120	210/200	37	0987	110 (110)
P1K1	1.1	130	152	145	0.065	1820	120	145	0.26	1920	120	150/100	14	1005	110 (110)
P1K1	1.1	130	152	145	0.065	1820	120	145	0.26	1920	120	150/200	27	0989	110 (110)
P1K5	1.5	81	110	90	0.095	1821	120	90	0.43	1921	120	100/100	10	1006	110 (110)
P1K5	1.5	81	110	90	0.095	1821	120	90	0.43	1921	120	100/200	19	0991	110 (110)
P2K2	2.2	58	74.2	65	0.25	1822	120	65	0.80	1922	120	72/200	14	0992	110 (110)
P3K0	3	45	53.8	50	0.285	1823	120	50	1.0	1923	120	50/200	10	0993	110 (110)
P3K7	3.7	31.5	43.1	35	0.43	1824	120	35	1.35	1924	120	35/200	7	0994	110 (110)
P3K7	3.7	31.5	43.1	35	0.43	1824	120	35	1.35	1924	120	72/200	14	2X0992	110 (110)
P5K5	5.5	22.5	28.7	25	0.8	1825	120	25	3.0	1925	120	60/200	11	2x0996	110 (110)
P7K5	7.5	18	20.8	20	2.0	1826	120	20	-	-	-	-	-	-	110 (110)
P11K	11	12.6	14.0	15	2.0	1827	120	15	-	-	-	-	-	-	103 (110)
P15K	15	9	10.2	10	2.8	1828	120	10	-	-	-	-	-	-	110 (110)
P18K	18.5	6.3	8.2	7	4	1829	120	7	-	-	-	-	-	-	110 (110)
P22K	22	5.4	6.9	6	4.8	1830	120	6	-	-	-	-	-	-	110 (110)
P30K	30	4.2	5.0	4.7	6	1954	300	4.7	-	-	-	-	-	-	110 (110)
P37K	37	2.9	4.0	3.3	8	1955	300	3.3	-	-	-	-	-	-	110 (110)
P45K	45	2.4	3.3	2.7	10	1956	300	2.7	-	-	-	-	-	-	110 (110)

Ordering Numbers: Brake Resistors

Mains 380-480 VAC (T4-LP+MP+HP)				VLT Automation VT Drive – Selected resistor											
				Standard IP 20								Flatpack IP65 for horizontal conveyors			Max. brake torque with R_{rec}
				Duty Cycle 10%				Duty Cycle 40%							
Size:	P_{motor}	R_{min}	$R_{br,nom}$	R_{rec}	$P_{br\ avg}$	Order no.	Period	R_{rec}	$P_{br\ avg}$	Order no.	Period	R_{rec} per item	Duty cycle	Order no.	
	[kW]	[Ω]	[Ω]	[Ω]	[kW]	175Uxxxx	[s]	[Ω]	[kW]	175Uxxxx	[s]	[Ω/W]	%	175Uxxxx	%
PK37	0.37	620	1825	620	0.065	1840	120	620	0.26	1940	120	830/100	30	1000	110 (110)
PK55	0.55	620	1228	620	0.065	1840	120	620	0.26	1940	120	830/100	20	1000	110 (110)
PK75	0.75	485	896	620	0.065	1840	120	620	0.26	1940	120	830/100	20	1000	110 (110)
P1K1	1.1	329	608	620	0.065	1840	120	620	0.26	1940	120	630	-	-	110 (110)
P1K5	1.5	240	443	425	0.095	1841	120	425	1.0	1941	120	430/100	10	1002	110 (110)
P1K5	1.5	240	443	425	0.095	1841	120	425	1.0	1941	120	430/200	20	0983	110 (110)
P2K2	2.2	161	299	310	0.25	1842	120	310	1.6	1942	120	320/200	14	0984	110 (110)
P3K0	3	117	217	210	0.285	1843	120	210	2.5	1943	120	215/200	10	0987	110 (110)
P4K0	4	86.9	161	150	0.43	1844	120	150	3.7	1944	120	150/200	14	0989	110 (110)
P4K0	4	86.9	161	150	0.43	1844	120	150	3.7	1944	120	300/200	7	2X0985	110 (110)
P5K5	5.5	62.5	115	110	0.6	1845	120	110	4.7	1945	120	120/200	6	2X0990	110 (110)
P7K5	7.5	45.3	83.7	80	0.85	1846	120	80	6.1	1946	120	82/240	5	2X0090	110 (110)
P11K	11	34.9	56.4	40	2	1848	120	40	11	1948	120	-	-	-	110 (110)
P15K	15	25.3	40.9	40	2	1848	120	40	11	1948	120	-	-	-	110 (110)
P18K	18.5	20.3	32.8	30	2.8	1849	120	30	18	1949	120	-	-	-	110 (110)
P22K	22	16.9	27.3	25	3.5	1850	120	25	23	1950	120	-	-	-	110 (110)
P30K	30	13.2	20	20	4	1851	120	20	25	1951	120	-	-	-	110 (110)
P37K	37	10.6	16.1	15	4.8	1852	120	15	32	1952	120	-	-	-	110 (110)
P45K	45	8.7	13.2	12	5.5	1853	120	12	40	1953	120	-	-	-	110 (110)
P55K	55	6.6	10.8	10	15	2008	120	10	62	2007	120	-	-	-	110 (110)
P75K	75	6.6	8	7	13	0069	120	7	72	0068	120	-	-	-	110 (110)
P90K	90	3.6	7	5	18	1959	300	-	-	-	-	-	-	-	110 (110)
P110	110	3	5	5	18	1959	300	-	-	-	-	-	-	-	110 (110)
P132	132	2.5	5	4	22	1960	300	-	-	-	-	-	-	-	110 (110)
P160	160	2	4	3.8	22	1960	300	-	-	-	-	-	-	-	106 (110)
P200	200	1.6	2.9	2.6	32	1962	300	-	-	-	-	-	-	-	110 (110)
P250	250	1.2	2.4	2.1	39	1963	300	-	-	-	-	-	-	-	110 (110)
P315	315	1.2	1.9	2.1	39	1963	300	-	-	-	-	-	-	-	98 (110)
P355	355	1.2	1.7	-	-	-	-	-	-	-	-	-	-	-	(110)
P400	400	1.2	1.5	-	-	-	-	-	-	-	-	-	-	-	(110)
P450	450	1.2	1.3	-	-	-	-	-	-	-	-	-	-	-	(110)
P500	500	1.2	1.3	-	-	-	-	-	-	-	-	-	-	-	(100)
P560	560	1.2	1.3	-	-	-	-	-	-	-	-	-	-	-	(89)
P630	630	1.2	1.3	-	-	-	-	-	-	-	-	-	-	-	(79)
P710	710	1.2	1.3	-	-	-	-	-	-	-	-	-	-	-	(70)
P800	800	1.2	1.3	-	-	-	-	-	-	-	-	-	-	-	(62)
P1M0	1000	1.2	1.3	-	-	-	-	-	-	-	-	-	-	-	(50)

4

Ordering Numbers: Brake Resistors

Mains 525-690 VAC (T7-HP)				VLT Automation VT Drive								
				Selected resistor								
				Standard IP 20								Max. brake torque with R_{rec}
				Duty Cycle 10%				Duty Cycle 40%				
Size:	P_{motor}	R_{min}	$R_{br,nom}$	R_{rec}	$P_{br\ avg}$	Order no.	Period	R_{rec}	$P_{br\ avg}$	Order no.	Period	
	[kW]	[Ω]	[Ω]	[Ω]	[kW]	130Bxxxx	[s]	[Ω]	[kW]	130Bxxxx	[s]	%
P37K	37	22.5	32.1	20	52	2118	600	20	32	2118	600	110 (110)
P45K	45	22.5	26.4	15	64	2119	600	15	39	2119	600	110 (110)
P55K	55	18	21.6	15	76	2120	600	15	47	2120	600	110 (110)
P75K	75	13.5	15.6	9.8	104	2121	600	9.8	64	2121	600	110 (110)
P90K	90	8.8	13	9.8	126	2122	600	9.8	77	2122	600	110 (110)
P110	110	8.8	10.7	7.3	153	2123	600	7.3	93	2123	600	110 (110)
P132	132	6.6	8.9	4.7	185	2124	600	4.7	113	2124	600	110 (110)
P160	160	6.6	7.3	4.7	224	2125	600	4.7	137	2125	600	110 (110)
P200	200	4.2	5.9	3.8	147	2X2126	600	3.8	90	2X2126	600	110 (110)
P250	250	4.2	4.7	2.6	173	2X2127	600	2.6	106	2X2127	600	110 (110)
P315	315	3.4	3.7	2.6	212	2X2128	600	2.6	130	2X2128	600	108 (110)
P400	355	2.3	3.3	2.6	72	2x1062	300	-	-	-	-	110 (110)
P450	400	2.3	2.9	2.6	72	2x1062	300	-	-	-	-	110 (110)
P500	500	2.1	2.3	2.3	90	2x1063	300	-	-	-	-	110 (110)
P560	560	1.9	2.1	2.1	100	2x1064	300	-	-	-	-	110 (110)
P630	630	1.7	1.9	-	-	-	-	-	-	-	-	-
P710	710	1.5	1.7	-	-	-	-	-	-	-	-	-
P800	800	1.3	1.5	-	-	-	-	-	-	-	-	-
P900	900	1.2	1.3	-	-	-	-	-	-	-	-	-
P1M0	1000	1.2	1.3	-	-	-	-	-	-	-	-	-

5 How to Install

5.1 Mechanical Installation

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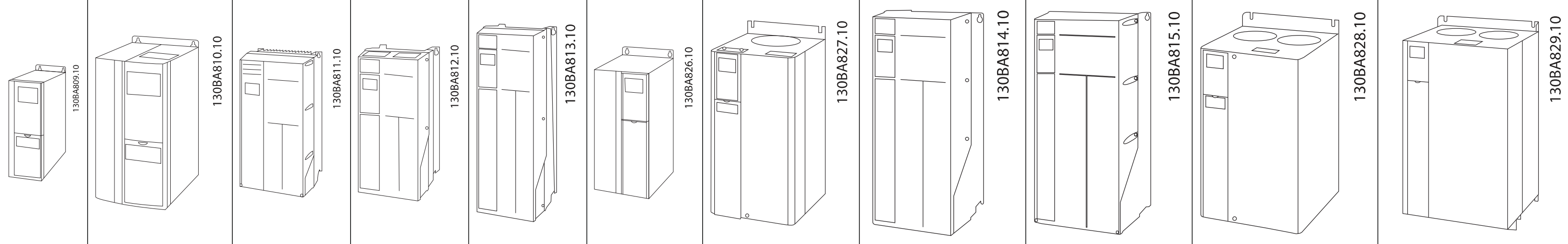
5

5.1.1 Mechanical Front Views



A2	A3	A5	B1	B2	B3	B4	C1	C2	C3	C4
IP20/21	IP20/21	IP55/66	IP21/55/66	IP21/55/66	IP20	IP20	IP21/55/66	IP21/55/66	IP20	IP20

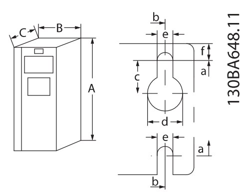


Illustration 5.1: Top and bottom mounting holes.

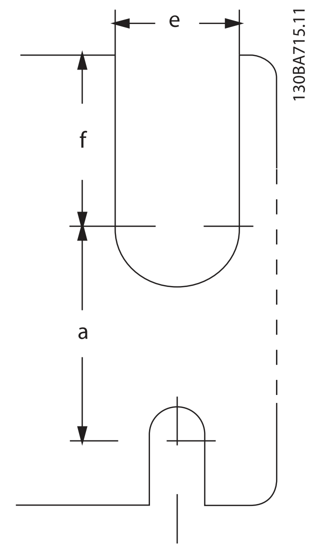


Illustration 5.2: Top and bottom mounting holes. (B4+C3+C4 only)

Accessory bags containing necessary brackets, screws and connectors are included with the drives upon delivery.

All measurements in mm.

5

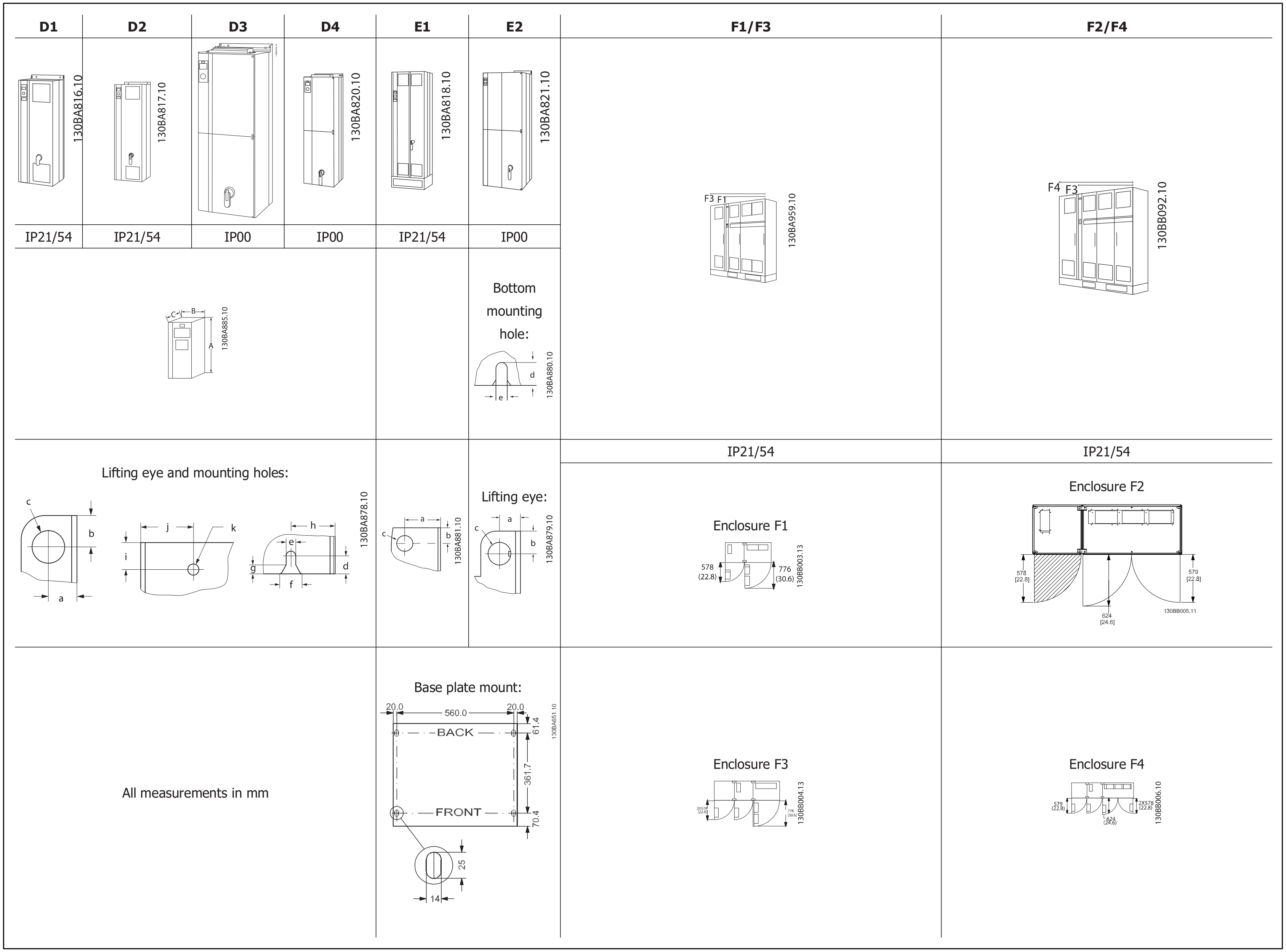
5.1.2 Mechanical Dimensions

Mechanical dimensions

Frame size (kW):		**A2**		**A3**		**A5**	**B1**	**B2**	**B3**	**B4**	**C1**	**C2**	**C3**	**C4**
200-240 V		**0.25-3.0**		**3.7**		**0.25-3.70.**	**5.5-11**	**15**	**5.5-11**	**15-18.5**	**18.5-30**	**37-45**	**22-30**	**37-45**
380-480 V		**0.37-4.0**		**5.5-7.5**		**75-7.5**	**11-18.5**	**22-30**	**11-18.5**	**22-37**	**37-55**	**75-90**	**45-55**	**75-90**
525-690 V		-		**0.75-7.5**		**0.37-7.5**	**11-18.5**	**22-30**	**11-18.5**	**22-37**	**37-55**	**75-90**	**45-55**	**75-90**
		-		-		-	-	**11-30**	-	-	-	**37-90**	-	-
IP NEMA		20 Chassis	21 Type 1	20 Chassis	21 Type 1	55/66 Type 12	21/ 55/66 Type 1/12	21/55/66 Type 1/12	20 Chassis	20 Chassis	21/55/66 Type 1/12	21/55/66 Type 1/12	20 Chassis	20 Chassis
Height (mm)														
Enclosure	A**	246	372	246	372	420	480	650	350	460	680	770	490	600
..with de-coupling plate	A2	374	-	374	-	-	-	-	419	595	-	-	630	800
Back plate	A1	268	375	268	375	420	480	650	399	520	680	770	550	660
Distance between mount. holes	a	257	350	257	350	402	454	624	380	495	648	739	521	631
Width (mm)														
Enclosure	B	90	90	130	130	242	242	242	165	231	308	370	308	370
With one C option	B	130	130	170	170	242	242	242	205	231	308	370	308	370
Back plate	B	90	90	130	130	242	242	242	165	231	308	370	308	370
Distance between mount. holes	b	70	70	110	110	215	210	210	140	200	272	334	270	330
Depth (mm)														
Without option A/B	C	205	205	205	205	200	260	260	248	242	310	335	333	333
With option A/B	C*	220	220	220	220	200	260	260	262	242	310	335	333	333
Screw holes (mm)														
	c	8.0	8.0	8.0	8.0	8.2	12	12	8	-	12	12	-	-
Diameter ø	d	11	11	11	11	12	19	19	12	-	19	19	-	-
Diameter ø	e	5.5	5.5	5.5	5.5	6.5	9	9	6.8	8.5	9.0	9.0	8.5	8.5
	f	9	9	9	9	9	9	9	7.9	15	9.8	9.8	17	17
Max weight (kg)		4.9	5.3	6.6	7.0	14	23	27	12	23.5	45	65	35	50

* Depth of enclosure will vary with different options installed.

** The free space requirements are above and below the bare enclosure height measurement A. See section 3.2.3 for further information.


D1
D2
D3
D4
E1
E2
F1/F3
F2/F4
130BA816.10
130BA817.10
130BA820.10
130BA818.10
130BA821.10
130BA959.10
130BB092.10
F3 F1
F4 F3
IP21/54
IP21/54
IP00
IP00
IP21/54
IP00
130BA885.10
Bottom mounting hole:
130BA880.10
IP21/54
IP21/54
Lifting eye and mounting holes:
130BA878.10
130BA881.10
Lifting eye:
130BA879.10
Enclosure F1
578 (22.8)
776 (30.6)
130BB003.13
Enclosure F2
578 [22.8]
624 [24.6]
579 [22.8]
130BB005.11
All measurements in mm
Base plate mount:
20.0
560.0
20.0
BACK
FRONT
61.4
361.7
70.4
25
14
130BA651.10
Enclosure F3
130BB004.13
Enclosure F4
130BB006.10

5

Mechanical dimensions

Enclosure size (kW)		D1	D2	D3	D4	E1	E2	F1	F2	F3	F4
380-480 VAC		**110-132**	**160-250**	**110-132**	**160-250**	**315-450**	**315-450**	**500-710**	**800-1000**	**500-710**	**800-1000**
525-690 VAC		**45-160**	**200-400**	**45-160**	**200-400**	**450-630**	**450-630**	**710-900**	**1000-1200**	**710-900**	**1000-1200**
IP		21/54	21/54	00	00	21/54	00	21/54	21/54	21/54	21/54
NEMA		Type 1/12	Type 1/12	Chassis	Chassis	Type 1/12	Chassis	Type 1/12	Type 1/12	Type 1/12	Type 1/12
Shipping dimensions (mm):											
Width		1730	1730	1220	1490	2197	1705	2324	2324	2324	2324
Height		650	650	650	650	840	831	1569	1962	2159	2559
Depth		570	570	570	570	736	736	927	927	927	927
FC dimensions: (mm)											
Height											
Back plate	A	1209	1589	1046	1327	2000	1547	2281	2281	2281	2281
Width											
Back plate	B	420	420	408	408	600	585	1400	1800	2000	2400
Depth											
	C	380	380	375	375	494	494	607	607	607	607
Dimensions brackets (mm/inch)											
Centre hole to edge	a	22/0.9	22/0.9	22/0.9	22/0.9	56/2.2	23/0.9				
Centre hole to edge	b	25/1.0	25/1.0	25/1.0	25/1.0	25/1.0	25/1.0				
Hole diameter	c	25/1.0	25/1.0	25/1.0	25/1.0	25/1.0	25/1.0				
	d	20/0.8	20/0.8	20/0.8	20/0.8		27/1.1				
	e	11/0.4	11/0.4	11/0.4	11/0.4		13/0.5				
	f	22/0.9	22/0.9	22/0.9	22/0.9						
	g	10/0.4	10/0.4	10/0.4	10/0.4						
	h	51/2.0	51/2.0	51/2.0	51/2.0						
	i	25/1.0	25/1.0	25/1.0	25/1.0						
	j	49/1.9	49/1.9	49/1.9	49/1.9						
Hole diameter	k	11/0.4	11/0.4	11/0.4	11/0.4						
Max weight (kg)		104	151	91	138	313	277	1004	1246	1299	1541

Please contact Danfoss for more detailed information and CAD drawings for your own planning purposes.

5.1.3 Mechanical Mounting

1. Drill holes in accordance with the measurements given.
2. You must provide screws suitable for the surface on which you want to mount the frequency converter. Retighten all four screws.

The frequency converter allows side-by-side installation.

The back wall must always be solid.

Enclosure	Air space (mm)
A2 A3 A5	100
B1 B2	200
B3	200
B4	200
C1	200
C2	225
C3	200
C4	225
D1/D2/D3/D4	225
E1/E2	225
F1/F2/F3/F4	225

Table 5.1: Required free air space above and below frequency converter

5.1.4 Safety Requirements of Mechanical Installation

Pay attention to the requirements that apply to integration and field mounting kit. Observe the information in the list to avoid serious damage or injury, especially when installing large units.

The frequency converter is cooled by means of air circulation.

To protect the unit from overheating, it must be ensured that the ambient temperature *does not exceed the maximum temperature stated for the frequency converter* and that the 24-hour average temperature *is not exceeded*. Locate the maximum temperature and 24-hour average in the paragraph *Derating for Ambient Temperature*.

If the ambient temperature is in the range of 45 °C - 55 ° C, derating of the frequency converter will become relevant, see *Derating for Ambient Temperature*.

The service life of the frequency converter is reduced if derating for ambient temperature is not taken into account.

5.1.5 Field Mounting

For field mounting the IP 21/IP 4X top/TYPE 1 kits or IP 54/55 units are recommended.

5.2 Pre-installation

5.2.1 Planning the Installation Site

NB!
Before performing the installation it is important to plan the installation of the frequency converter. Neglecting this may result in extra work during and after installation.

Select the best possible operation site by considering the following (see details on the following pages, and the respective Design Guides):

- Ambient operating temperature
- Installation method
- How to cool the unit
- Position of the frequency converter
- Cable routing
- Ensure the power source supplies the correct voltage and necessary current
- Ensure that the motor current rating is within the maximum current from the frequency converter
- If the frequency converter is without built-in fuses, ensure that the external fuses are rated correctly.

5.2.2 Receiving the Frequency Converter

When receiving the frequency converter please make sure that the packaging is intact, and be aware of any damage that might have occurred to the unit during transport. In case damage has occurred, contact immediately the shipping company to claim the damage.

5.2.3 Transportation and Unpacking

Before unpacking the frequency converter it is recommended that it is located as close as possible to the final installation site.
Remove the box and handle the frequency converter on the pallet, as long as possible.

NB!
The card box cover contains a drilling master for the mounting holes in the D frames. For the E size, please refer to section *Mechanical Dimensions* later in this chapter.

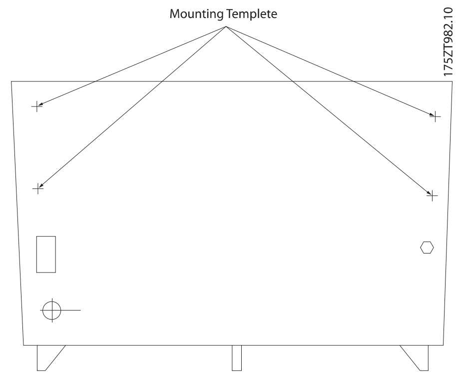


Illustration 5.3: Mounting Template

5.2.4 Lifting

Always lift the frequency converter in the dedicated lifting eyes. For all D and E2 (IP00) frames, use a bar to avoid bending the lifting holes of the frequency converter.

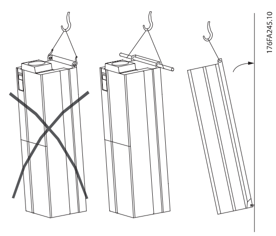


Illustration 5.4: Recommended lifting method, frame sizes D and E .

NB!

The lifting bar must be able to handle the weight of the frequency converter. See *Mechanical Dimensions* for the weight of the different frame sizes. Maximum diameter for bar is 25 cm (1 inch). The angle from the top of the drive to the lifting cable should be 60 degrees or greater.

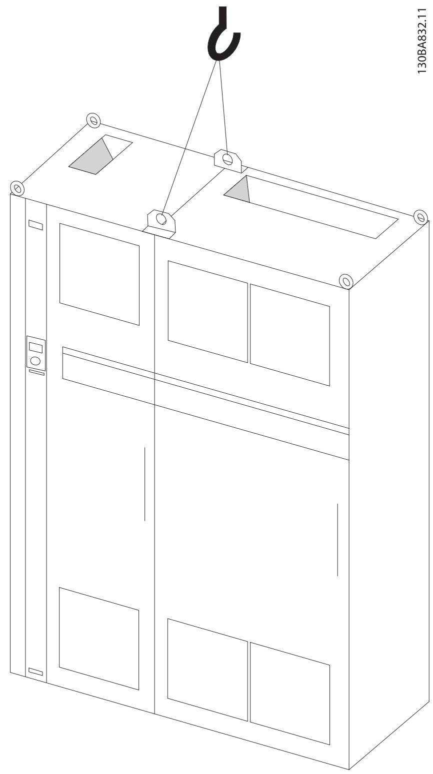


Illustration 5.5: Recommended lifting method, frame size F1.

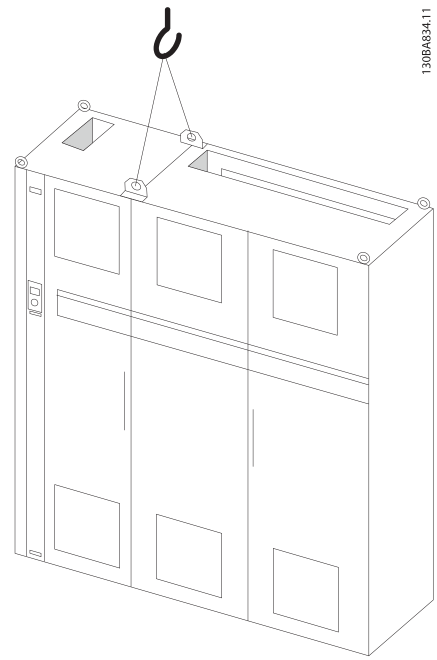


Illustration 5.6: Recommended lifting method, frame size F2.

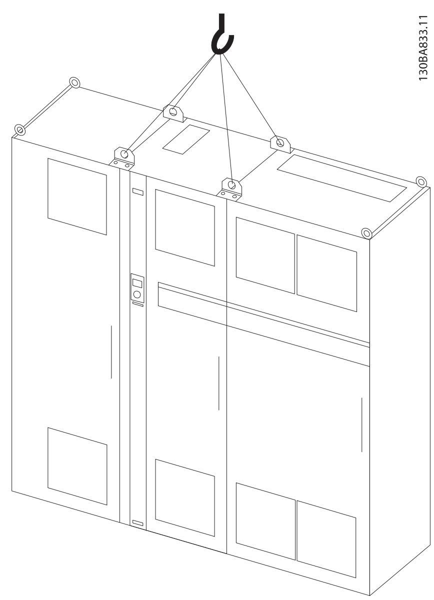


Illustration 5.7: Recommended lifting method, frame size F3.

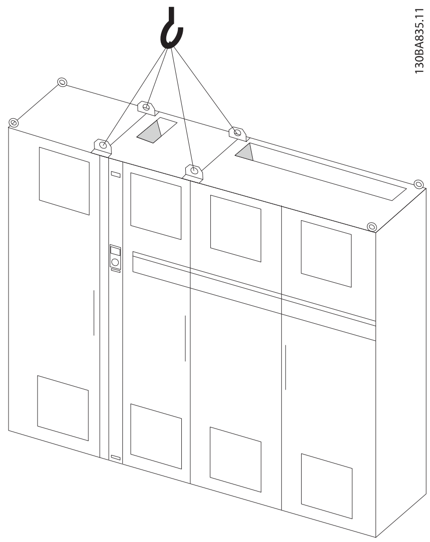


Illustration 5.8: Recommended lifting method, frame size F4.

5.2.5 Tools Needed

To perform the mechanical installation the following tools are needed:

- Drill with 10 or 12 mm drill
- Tape measure
- Wrench with relevant metric sockets (7-17 mm)
- Extensions to wrench
- Sheet metal punch for conduits or cable glands in IP 21/Nema 1 and IP 54 units
- Lifting bar to lift the unit (rod or tube max. Ø 25 mm (1 inch), able to lift minimum 400 kg (880 lbs)).
- Crane or other lifting aid to place the frequency converter in position
- A Torx T50 tool is needed to install the E1 in IP21 and IP54 enclosure types.

5.2.6 General Considerations

Space

Ensure proper space above and below the frequency converter to allow airflow and cable access. In addition space in front of the unit must be considered to enable opening of the door of the panel.

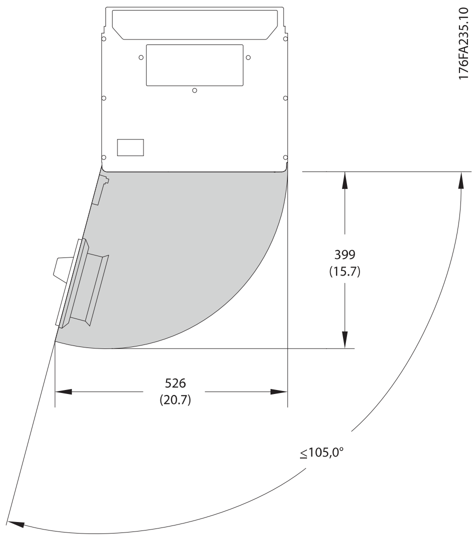


Illustration 5.9: Space in front of IP21/IP54 enclosure type, frame size D1 and D2 .

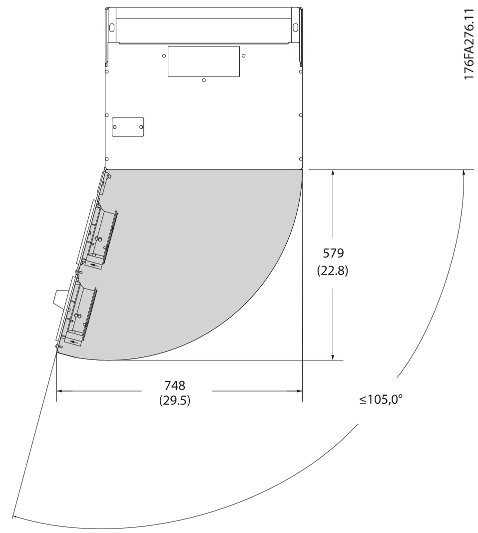


Illustration 5.10: Space in front of IP21/IP54 enclosure type, frame size E1.

NB!
For frame size F, please see section *Mechanical Installation High Power*.

Wire access

Ensure that proper cable access is present including necessary bending allowance. As the IP00 enclosure is open to the bottom cables must be fixed to the back panel of the enclosure where the frequency converter is mounted, i.e. by using cable clamps.

NB!
All cable lugs/ shoes must mount within the width of the terminal bus bar

5.2.7 Cooling and Airflow

Cooling

Cooling can be obtained in different ways, by using the cooling ducts in the bottom and the top of the unit, by taking air in and out the back of the unit or by combining the cooling possibilities.

Duct cooling

A dedicated option has been developed to optimize installation of IP00/chassis frame frequency converters in Rittal TS8 enclosures utilizing the fan of the frequency converter for forced air cooling of the backchannel. The air out the top of the enclosure could but ducted outside a facility so the heat loses from the backchannel are not dissipated within the control room reducing air-conditioning requirements of the facility.
Please see *Installation of Duct Cooling Kit in Rittal enclosures*, for further information.

Back cooling

The backchannel air can also be ventilated in and out the back of a Rittal TS8 enclosure. This offers a solution where the backchannel could take air from outside the facility and return the heat loses outside the facility thus reducing air-conditioning requirements.

NB!
A doorfan(s) is required on the Rittal cabinet to remove the loses not contained in the backchannel of the drive. The minimum doorfan(s) airflow required at the drive maximum ambient for the D3 and D4 is 391 m^3/h (230 cfm). The minimum doorfan(s) airflow required at the drive maximum ambient for the E2 is 782 m^3/h (460 cfm). If the ambient is below maximum or if additional components, heat loses, are added within the enclosure a calculation must be made to ensure the proper airflow is provided to cool the inside of the Rittal enclosure.

Airflow

The necessary airflow over the heat sink must be secured. The flow rate is shown below.

Enclosure protection	Frame size	Door fan / Top fan airflow	Airflow over heatsink
IP21 / NEMA 1	D1 and D2	170 m^3/h (100 cfm)	765 m^3/h (450 cfm)
IP54 / NEMA 12	E1	340 m^3/h (200 cfm)	1444 m^3/h (850 cfm)
IP21 / NEMA 1	F1, F2, F3 and F4	700 m^3/h (412 cfm)*	985 m^3/h (580 cfm)
IP54 / NEMA 12	F1, F2, F3 and F4	525 m^3/h (309 cfm)*	985 m^3/h (580 cfm)
IP00 / Chassis	D3 and D4	255 m^3/h (150 cfm)	765 m^3/h (450 cfm)
	E2	255 m^3/h (150 cfm)	1444 m^3/h (850 cfm)
* Airflow per fan. Frame size F contain multiple fans.			

Table 5.2: Heatsink Air Flow

5.2.8 Gland/Conduit Entry - IP21 (NEMA 1) and IP54 (NEMA12)

Cables are connected through the gland plate from the bottom. Remove the plate and plan where to place the entry for the glands or conduits. Prepare holes in the marked area on the drawing.

NB!
The gland plate must be fitted to the frequency converter to ensure the specified protection degree, as well as ensuring proper cooling of the unit. If the gland plate is not mounted, the frequency converter may trip on Alarm 69, Pwr. Card Temp

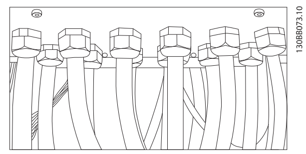
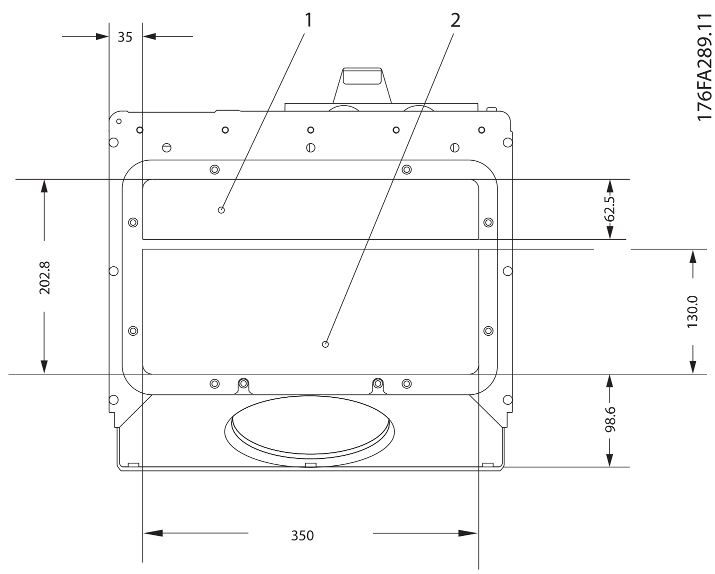
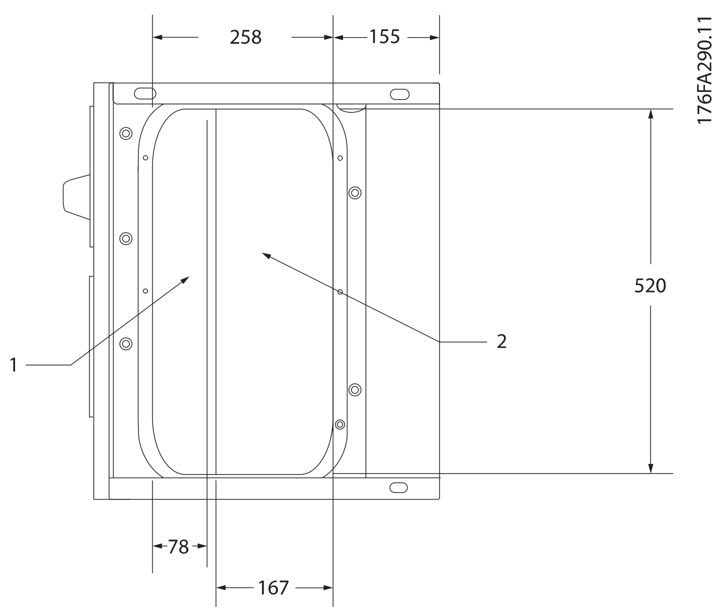


Illustration 5.11: Example of proper installation of the gland plate.

Frame size D1 + D2



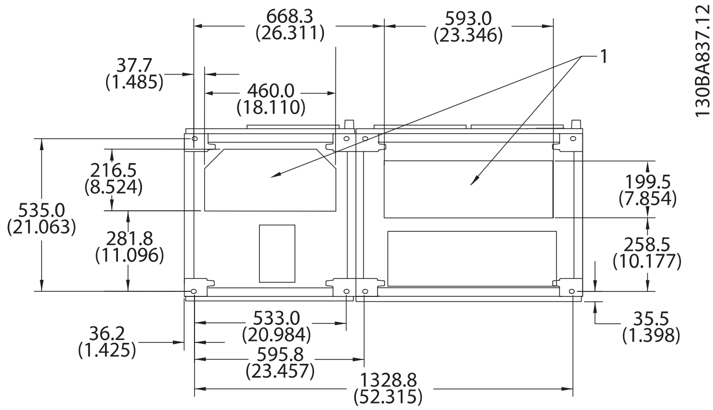
Frame size E1



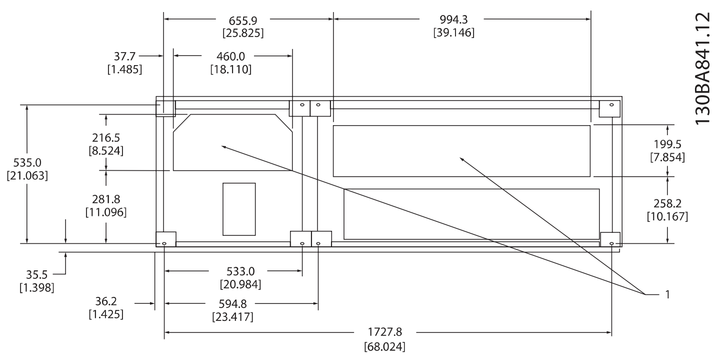
Cable entries viewed from the bottom of the frequency converter - 1) Mains side 2) Motor side

5

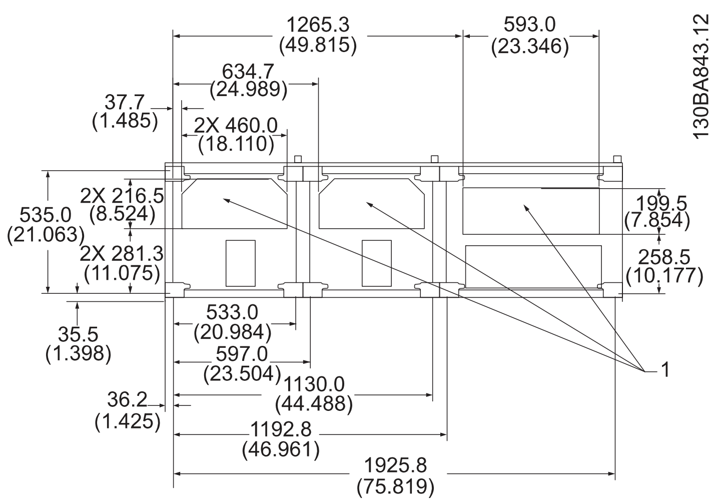
Frame size F1



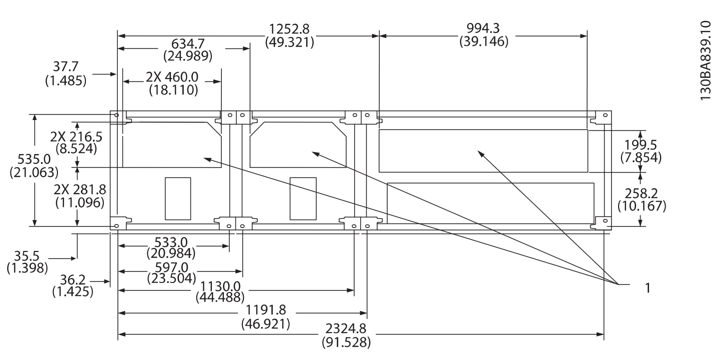
Frame size F2



Frame size F3



Frame size F4



F1-F4: Cable entries viewed from the bottom of the frequency converter - 1) Place conduits in marked areas

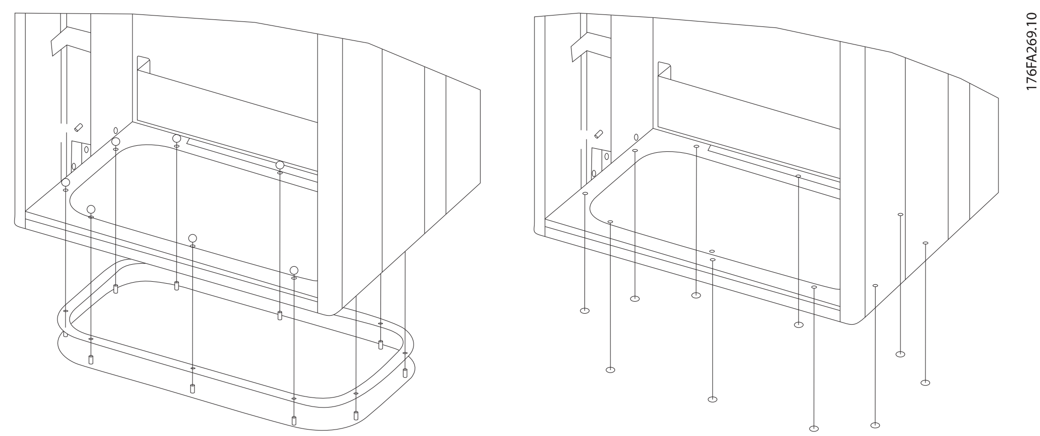


Illustration 5.12: Mounting of bottom plate,Frame size E1.

The bottom plate of the E1 frame can be mounted from either in- or outside of the enclosure, allowing flexibility in the installation process, i.e. if mounted from the bottom the glands and cables can be mounted before the frequency converter is placed on the pedestal.

5.2.9 IP21 Drip Shield Installation (frame size D1 and D2)

To comply with the IP21 rating, a separate drip shield is to be installed as explained below:

- Remove the two front screws
- Insert the drip shield and replace screws
- Torque the screws to 5,6 Nm (50 in-lbs)

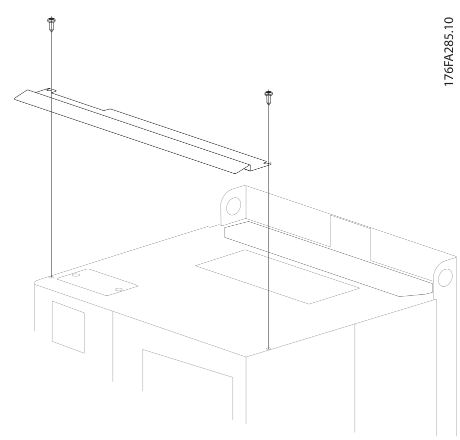


Illustration 5.13: Drip shield installation.

5.3 Electrical Installation

5.3.1 Cables General

NB!
Cables General
Always comply with national and local regulations on cable cross-sections.

Details of terminal tightening torques.

	Power (kW)			Torque (Nm)					
Enclosure	200-240 V	380-480 V	525-690 V	Mains	Motor	DC connection	Brake	Earth	Relay
A2	0.25 - 3.0	0.37 - 4.0		1.8	1.8	1.8	1.8	3	0.6
A3	3.7	5.5 - 7.5	0.75 - 7.5	1.8	1.8	1.8	1.8	3	0.6
A5	0.25 - 3.7	0.37 - 7.5	1.1 - 7.5	1.8	1.8	1.8	1.8	3	0.6
B1	5.5 -11	11 - 18	-	1.8	1.8	1.5	1.5	3	0.6
B2	- 15	22 30	11 - 30	2.5 4.5	2.5 4.5	3.7 3.7	2.5 4.5	3 3	0.6 0.6
B3	5.5 - 7.5	11 - 15	- -	1.8	1.8	1.8	1.8	2 - 3	0.5 - 0.6
B4	11 - 15	18.5 - 30	- -	4.5	4.5	4.5	4.5	2 - 3	0.5 - 0.6
C1	18.5 - 30	37 - 55	-	10	10	10	10	3	0.6
C2	37 - 45	75 90	30 - 90	14 24	14 24	14 14	14 14	3 3	0.6 0.6
C3	18.5 - 22	37 - 45	- -	10	10	10	10	2 - 3	0.5 - 0.6
C4*	30 37	55 75	- -	14 24	14 24	14 24	14 24	2 - 3	0.5 - 0.6
D1/D3	-	110 132	110 132	19 19	19 19	9.6 9.6	9.6 9.6	19	0.6
D2/D4	-	160-250	160-315	19	19	9.6	9.6	19	0.6
E1/E2	-	315-450	355-560	19	19	9.6	9.6	19	0.6
Enclosure	200-240 V	380-480 V	525-690 V	Mains	Motor	DC Connection	Brake	Regen	Relay
F1/F2/F3/F4	-	500-1000	710-1200	19	19	9.6	9.5	19	0.6

Table 5.3: Tightening of terminals.

* For C4, tigtening torque depends on cable dimensions used - 35-95 mm^2 or 120-150 mm^2.

5.3.2 Removal of Knockouts for Extra Cables

1. Remove cable entry from the frequency converter (Avoiding foreign parts falling into the frequency converter when removing knockouts)
2. Cable entry has to be supported around the knockout you intend to remove.
3. The knockout can now be removed with a strong mandrel and a hammer.
4. Remove burrs from the hole.

5. Mount Cable entry on frequency converter.

5.3.3 Connection to Mains and Earthing

NB!
The plug connector for power can be removed.

1. Make sure the frequency converter is properly earthed. Connect to earth connection (terminal 95). Use screw from the accessory bag.
2. Place plug connector 91, 92, 93 from the accessory bag onto the terminals labelled MAINS at the bottom of the frequency converter.
3. Connect mains wires to the mains plug connector.

The earth connection cable cross section must be at least 10 mm^2 or 2 rated mains wires terminated separately according to EN 50178.

The mains connection is fitted to the main switch if this is included.

NB!
Check that mains voltage corresponds to the mains voltage of the frequency converter name plate.

IT Mains
Do not connect 400 V frequency converters with RFI-filters to mains supplies with a voltage between phase and earth of more than 440 V.
For IT mains and delta earth (grounded leg), mains voltage may exceed 440 V between phase and earth.

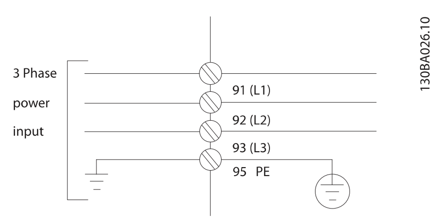


Illustration 5.14: Terminals for mains and earthing.

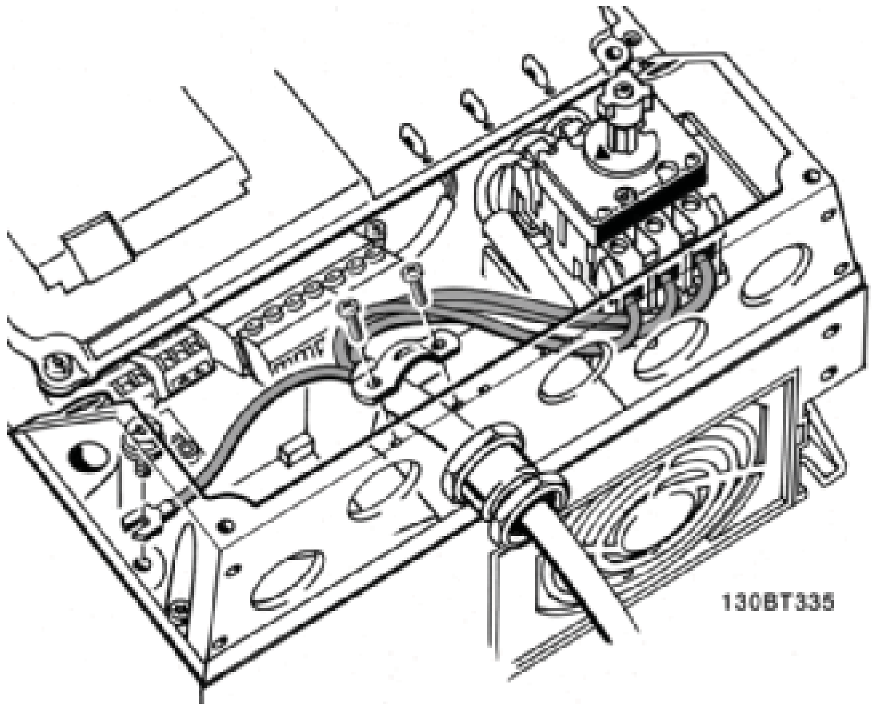


Illustration 5.15: How to connect to mains and earthing with disconnector (A5 enclosure).

5.3.4 Motor Cable Connection

NB!

Motor cable must be screened/armoured. If an unscreened / unarmoured cable is used, some EMC requirements are not complied with. For more information, see *EMC specifications*.

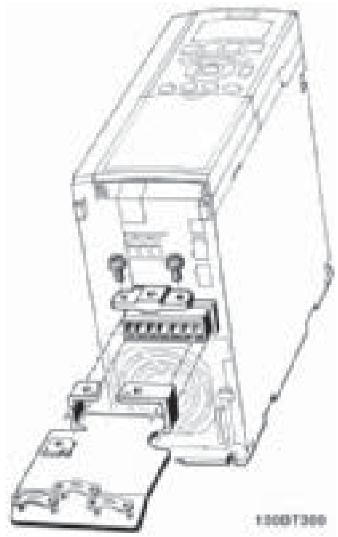
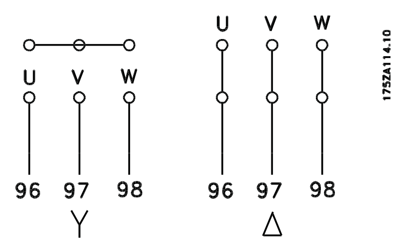


Illustration 5.16: Mounting of decoupling plate.

1. Fasten decoupling plate to the bottom of the frequency converter with screws and washers from the accessory bag.
2. Attach motor cable to terminals 96 (U), 97 (V), 98 (W).
3. Connect to earth connection (terminal 99) on decoupling plate with screws from the accessory bag.
4. Insert terminals 96 (U), 97 (V), 98 (W) and motor cable to terminals labelled MOTOR.
5. Fasten screened cable to decoupling plate with screws and washers from the accessory bag.

All types of three-phase asynchronous standard motors can be connected to the frequency converter. Normally, small motors are star-connected (230/400 V, D/Y). Large motors are delta-connected (400/6090 V, D/Y). Refer to the motor name plate for correct connection mode and voltage.



NB!
In motors without phase insulation paper or other insulation reinforcement suitable for operation with voltage supply (such as a frequency converter), fit a Sine-wave filter on the output of the frequency converter.

No.	96	97	98	Motor voltage 0-100% of mains voltage
	U	V	W	3 wires out of motor
	U1 W2	V1 U2	W1 V2	6 wires out of motor, Delta-connected
	U1	V1	W1	6 wires out of motor, Star-connected U2, V2, W2 to be interconnected separately
No.	99			Earth connection
	PE			

5.3.5 Motor Cables

5

See section *General Specifications* for correct dimensioning of motor cable cross-section and length.

- Use a screened/armoured motor cable to comply with EMC emission specifications.
- Keep the motor cable as short as possible to reduce the noise level and leakage currents.
- Connect the motor cable screen to both the de-coupling plate of the frequency converter and to the metal cabinet of the motor.
- Make the screen connections with the largest possible surface area (cable clamp). This is done by using the supplied installation devices in the frequency converter.
- Avoid mounting with twisted screen ends (pigtails), which will spoil high frequency screening effects.
- If it is necessary to split the screen to install a motor isolator or motor relay, the screen must be continued with the lowest possible HF impedance.

F frame Requirements
F1/F3 requirements: Motor phase cable quantities must be 2, 4, 6, or 8 (multiples of 2, 1 cable is not allowed) to obtain equal amount of wires attached to both inverter module terminals. The cables are required to be equal length within 10% between the inverter module terminals and the first common point of a phase. The recommended common point is the motor terminals.

F2/F4 requirements: Motor phase cable quantities must be 3, 6, 9, or 12 (multiples of 3, 2 cables are not allowed) to obtain equal amount of wires attached to each inverter module terminal. The wires are required to be equal length within 10% between the inverter module terminals and the first common point of a phase. The recommended common point is the motor terminals.

Output junction box requirements: The length, minimum 2.5 meters, and quantity of cables must be equal from each inverter module to the common terminal in the junction box.

5.3.6 Electrical Installation of Motor Cables

Screening of cables
Avoid installation with twisted screen ends (pigtails). They spoil the screening effect at higher frequencies.
If it is necessary to break the screen to install a motor isolator or motor contactor, the screen must be continued at the lowest possible HF impedance.

Cable length and cross-section
The frequency converter has been tested with a given length of cable and a given cross-section of that cable. If the cross-section is increased, the cable capacitance - and thus the leakage current - may increase, and the cable length must be reduced correspondingly.

Switching frequency
When frequency converters are used together with Sine-wave filters to reduce the acoustic noise from a motor, the switching frequency must be set according to the Sine-wave filter instruction in par. 14-01 *Switching Frequency*.

Aluminium conductors
Aluminium conductors are not recommended. Terminals can accept aluminium conductors but the conductor surface has to be clean and the oxidation must be removed and sealed by neutral acid free Vaseline grease before the conductor is connected.

Furthermore, the terminal screw must be retightened after two days due to the softness of the aluminium. It is crucial to keep the connection a gas tight joint, otherwise the aluminium surface will oxidize again.

5.3.7 Fuses

Branch circuit protection:
In order to protect the installation against electrical and fire hazard, all branch circuits in an installation, switch gear, machines etc., must be shortcircuit and overcurrent protected according to the national/international regulations.

Short circuit protection:
The frequency converter must be protected against short-circuit to avoid electrical or fire hazard. Danfoss recommends using the fuses mentioned in tables 5.3 and 5.4 to protect service personnel or other equipment in case of an internal failure in the unit. The frequency converter provides full short circuit protection in case of a short-circuit on the motor output.

Over-current protection:
Provide overload protection to avoid fire hazard due to overheating of the cables in the installation. Over current protection must always be carried out according to national regulations. The frequency converter is equipped with an internal over current protection that can be used for upstream overload protection (UL-applications excluded). See par. 4-18. Fuses must be designed for protection in a circuit capable of supplying a maximum of 100,000 A_{rms} (symmetrical), 500 V/600 V maximum.

Non UL compliance:
If UL/cUL is not to be complied with, Danfoss recommends using the fuses mentioned in table 5.2, which will ensure compliance with EN50178:
In case of malfunction, not following the recommendation may result in unnecessary damage to the frequency converter.

5

Frequency converter:	Max. fuse size:	Voltage:	Type:
200-240 V			
K25-K75	10A[1]	200-240 V	type gG
1K1-2K2	20A[1]	200-240 V	type gG
3K0	30A[1]	200-240 V	type gG
3K7	30A[1]	200-240 V	type gG
5K5	50A[1]	200-240 V	type gG
7K5	63A[1]	200-240 V	type gG
11K	63A[1]	200-240 V	type gG
15K	80A[1]	200-240 V	type gG
18K5	125A[1]	200-240 V	type gG
22K	125A[1]	200-240 V	type gG
30K	160A[1]	200-240 V	type gG
37K	200A[1]	200-240 V	type aR
45K	250A[1]	200-240 V	type aR
380-480 V			
K37-1K5	10A[1]	380-480 V	type gG
2K2-4K0	20A[1]	380-480 V	type gG
5K5-7K5	30A[1]	380-480 V	type gG
11K	63A[1]	380-480 V	type gG
15K	63A[1]	380-480 V	type gG
18K	63A[1]	380-480 V	type gG
22K	63A[1]	380-480 V	type gG
30K	80A[1]	380-480 V	type gG
37K	100A[1]	380-480 V	type gG
45K	125A[1]	380-480 V	type gG
55K	160A[1]	380-480 V	type gG
75K	250A[1]	380-480 V	type aR
90K	250A[1]	380-480 V	type aR

Table 5.4: Non UL fuses 200 V to 480 V

1) Max. fuses - see national/international regulations for selecting an applicable fuse size.

Danfoss PN	Bussmann	Ferraz	Siba
20220	170M4017	6.9URD31D08A0700	20 610 32.700
20221	170M6013	6.9URD33D08A0900	20 630 32.900

Table 5.5: **Additional Fuses for Non-UL Applications, E enclosures, 380-480 V**

UL Compliance

VLT Automation VT Drive	Bussmann	Bussmann	Bussmann	SIBA	Littel fuse	Ferraz-Shawmut	Ferraz-Shawmut
200-240 V							
kW	Type RK1	Type J	Type T	Type RK1	Type RK1	Type CC	Type RK1
K25-1K1	KTN-R10	JKS-10	JJN-10	5017906-010	KLN-R10	ATM-R10	A2K-10R
1K5	KTN-R15	JKS-15	JJN-15	5017906-015	KLN-R15	ATM-R15	A2K-15R
2K2	KTN-R20	JKS-20	JJN-20	5012406-020	KLN-R20	ATM-R20	A2K-20R
3K0	KTN-R25	JKS-25	JJN-25	5012406-025	KLN-R25	ATM-R25	A2K-25R
3K7	KTN-R30	JKS-30	JJN-30	5012406-030	KLN-R30	ATM-R30	A2K-30R
5K5	KTN-R50	JKS-50	JJN-50	5012406-050	KLN-R50	-	A2K-50R
7K5	KTN-R50	JKS-60	JJN-60	5012406-050	KLN-R60	-	A2K-50R
11K	KTN-R60	JKS-60	JJN-60	5014006-063	KLN-R60		A2K-60R
15K	KTN-R80	JKS-80	JJN-80	5014006-080	KLN-R80		A2K-80R
18K5	KTN-R125	JKS-150	JJN-125	2028220-125	KLN-R125		A2K-125R
22K	KTN-R125	JKS-150	JJN-125	2028220-125	KLN-R125		A2K-125R
30K	FWX-150	-	-	2028220-150	L25S-150		A25X-150
37K	FWX-200	-	-	2028220-200	L25S-200		A25X-200
45K	FWX-250	-	-	2028220-250	L25S-250		A25X-250

Table 5.6: UL fuses 200 - 240 V

VLT Automation VT Drive	Bussmann	Bussmann	Bussmann	SIBA	Littel fuse	Ferraz-Shawmut	Ferraz-Shawmut
380-500 V, 525-600							
kW	Type RK1	Type J	Type T	Type RK1	Type RK1	Type CC	Type RK1
11K	KTS-R40	JKS-40	JJS-40	5014006-040	KLS-R40	-	A6K-40R
15K	KTS-R40	JKS-40	JJS-40	5014006-040	KLS-R40	-	A6K-40R
18K	KTS-R50	JKS-50	JJS-50	5014006-050	KLS-R50	-	A6K-50R
22K	KTS-R60	JKS-60	JJS-60	5014006-063	KLS-R60	-	A6K-60R
30K	KTS-R80	JKS-80	JJS-80	2028220-100	KLS-R80	-	A6K-80R
37K	KTS-R100	JKS-100	JJS-100	2028220-125	KLS-R100		A6K-100R
45K	KTS-R125	JKS-150	JJS-150	2028220-125	KLS-R125		A6K-125R
55K	KTS-R150	JKS-150	JJS-150	2028220-160	KLS-R150		A6K-150R
75K	FWH-220	-	-	2028220-200	L50S-225		A50-P225
90K	FWH-250	-	-	2028220-250	L50S-250		A50-P250

Table 5.7: UL fuses 380 - 600 V

KTS-fuses from Bussmann may substitute KTN for 240 V frequency converters.

FWH-fuses from Bussmann may substitute FWX for 240 V frequency converters.

KLSR fuses from LITTEL FUSE may substitute KLNR fuses for 240 V frequency converters.

L50S fuses from LITTEL FUSE may substitute L50S fuses for 240 V frequency converters.

A6KR fuses from FERRAZ SHAWMUT may substitute A2KR for 240 V frequency converters.

A50X fuses from FERRAZ SHAWMUT may substitute A25X for 240 V frequency converters.

5

Frequency converter	Bussmann	Bussmann	Bussmann	SIBA	Littel fuse	Ferraz-Shawmut	Ferraz-Shawmut
UL Compliance - 200-240 V							
kW	Type RK1	Type J	Type T	Type RK1	Type RK1	Type CC	Type RK1
K25-K37	KTN-R05	JKS-05	JJN-05	5017906-005	KLN-R005	ATM-R05	A2K-05R
K55-1K1	KTN-R10	JKS-10	JJN-10	5017906-010	KLN-R10	ATM-R10	A2K-10R
1K5	KTN-R15	JKS-15	JJN-15	5017906-015	KLN-R15	ATM-R15	A2K-15R
2K2	KTN-R20	JKS-20	JJN-20	5012406-020	KLN-R20	ATM-R20	A2K-20R
3K0	KTN-R25	JKS-25	JJN-25	5012406-025	KLN-R25	ATM-R25	A2K-25R
3K7	KTN-R30	JKS-30	JJN-30	5012406-030	KLN-R30	ATM-R30	A2K-30R
5K5	KTN-R50	JKS-50	JJN-50	5012406-050	KLN-R50	-	A2K-50R
7K5	KTN-R50	JKS-60	JJN-60	5012406-050	KLN-R60	-	A2K-50R
11K	KTN-R60	JKS-60	JJN-60	5014006-063	KLN-R60	A2K-60R	A2K-60R
15K	KTN-R80	JKS-80	JJN-80	5014006-080	KLN-R80	A2K-80R	A2K-80R
18K5	KTN-R125	JKS-150	JJN-125	2028220-125	KLN-R125	A2K-125R	A2K-125R
22K	KTN-R125	JKS-150	JJN-125	2028220-125	KLN-R125	A2K-125R	A2K-125R
30K	FWX-150	-	-	2028220-150	L25S-150	A25X-150	A25X-150
37K	FWX-200	-	-	2028220-200	L25S-200	A25X-200	A25X-200
45K	FWX-250	-	-	2028220-250	L25S-250	A25X-250	A25X-250

Table 5.8: **UL fuses 200 - 240 V**

380-500 V, frame sizes D, E and F

The fuses below are suitable for use on a circuit capable of delivering 100,000 Arms (symmetrical), 240V, or 480V, or 500V, or 600V depending on the drive voltage rating. With the proper fusing the drive Short Circuit Current Rating (SCCR) is 100,000 Arms.

Size/ Type	Bussmann E1958 JFHR2**	Bussmann E4273 T/JDDZ**	SIBA E180276 RKI/JDDZ	LittelFuse E71611 JFHR2**	Ferraz-Shawmut E60314 JFHR2**	Bussmann E4274 H/JDDZ**	Bussmann E125085 JFHR2*	Internal Option Bussmann
P90K	FWH-300	JJS-300	2028220-315	L50S-300	A50-P300	NOS-300	170M3017	170M3018
P110	FWH-350	JJS-350	2028220-315	L50S-350	A50-P350	NOS-350	170M3018	170M3018
P132	FWH-400	JJS-400	206xx32-400	L50S-400	A50-P400	NOS-400	170M4012	170M4016
P160	FWH-500	JJS-500	206xx32-500	L50S-500	A50-P500	NOS-500	170M4014	170M4016
P200	FWH-600	JJS-600	206xx32-600	L50S-600	A50-P600	NOS-600	170M4016	170M4016

Table 5.9: Frame size D, Line fuses, 380-500 V

Size/Type	Bussmann PN*	Rating	Ferraz	Siba
P250	170M4017	700 A, 700 V	6.9URD31D08A0700	20 610 32.700
P315	170M6013	900 A, 700 V	6.9URD33D08A0900	20 630 32.900
P355	170M6013	900 A, 700 V	6.9URD33D08A0900	20 630 32.900
P400	170M6013	900 A, 700 V	6.9URD33D08A0900	20 630 32.900

Table 5.10: Frame size E, Line fuses, 380-500 V

Size/Type	Bussmann PN*	Rating	Siba	Internal Bussmann Option
P450	170M7081	1600 A, 700 V	20 695 32.1600	170M7082
P500	170M7081	1600 A, 700 V	20 695 32.1600	170M7082
P560	170M7082	2000 A, 700 V	20 695 32.2000	170M7082
P630	170M7082	2000 A, 700 V	20 695 32.2000	170M7082
P710	170M7083	2500 A, 700 V	20 695 32.2500	170M7083
P800	170M7083	2500 A, 700 V	20 695 32.2500	170M7083

Table 5.11: Frame size F, Line fuses, 380-500 V

Size/Type	Bussmann PN*	Rating	Siba
P450	170M8611	1100 A, 1000 V	20 781 32.1000
P500	170M8611	1100 A, 1000 V	20 781 32.1000
P560	170M6467	1400 A, 700 V	20 681 32.1400
P630	170M6467	1400 A, 700 V	20 681 32.1400
P710	170M8611	1100 A, 1000 V	20 781 32.1000
P800	170M6467	1400 A, 700 V	20 681 32.1400

Table 5.12: Frame size F, Inverter module DC Link Fuses, 380-500 V

*170M fuses from Bussmann shown use the -/80 visual indicator, -TN/80 Type T, -/110 or TN/110 Type T indicator fuses of the same size and amperage may be substituted for external use

**Any minimum 500 V UL listed fuse with associated current rating may be used to meet UL requirements.

525-690 V, frame sizes D, E and F

Size/Type	Bussmann PN*	Rating	Ferraz	Siba
P355	170M4017	700 A, 700 V	6.9URD31D08A0700	20 610 32.700
P400	170M4017	700 A, 700 V	6.9URD31D08A0700	20 610 32.700
P500	170M6013	900 A, 700 V	6.9URD33D08A0900	20 630 32.900
P560	170M6013	900 A, 700 V	6.9URD33D08A0900	20 630 32.900

Table 5.13: Frame size E, 525-690 V

Size/Type	Bussmann PN*	Rating	Siba	Internal Bussmann Option
P630	170M7081	1600 A, 700 V	20 695 32.1600	170M7082
P710	170M7081	1600 A, 700 V	20 695 32.1600	170M7082
P800	170M7081	1600 A, 700 V	20 695 32.1600	170M7082
P900	170M7081	1600 A, 700 V	20 695 32.1600	170M7082
P1M0	170M7082	2000 A, 700 V	20 695 32.2000	170M7082

Table 5.14: Frame size F, Line fuses, 525-690 V

Size/Type	Bussmann PN*	Rating	Siba
P630	170M8611	1100 A, 1000 V	20 781 32. 1000
P710	170M8611	1100 A, 1000 V	20 781 32. 1000
P800	170M8611	1100 A, 1000 V	20 781 32. 1000
P900	170M8611	1100 A, 1000 V	20 781 32. 1000
P1M0	170M8611	1100 A, 1000 V	20 781 32. 1000

Table 5.15: Frame size F, Inverter module DC Link Fuses, 525-690 V

*170M fuses from Bussmann shown use the -/80 visual indicator, -TN/80 Type T, -/110 or TN/110 Type T indicator fuses of the same size and amperage may be substituted for external use.

Suitable for use on a circuit capable of delivering not more than 100 000 rms symmetrical amperes, 500/600/690 Volts maximum when protected by the above fuses.

5.3.8 Access to Control Terminals

All terminals to the control cables are located underneath the terminal cover on the front of the frequency converter. Remove the terminal cover by means of a screwdriver (see illustration).

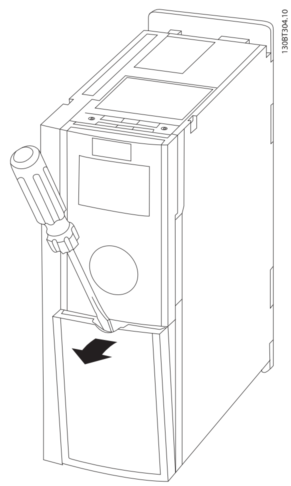


Illustration 5.17: Frame sizes A1, A2, A3,B3, B4, C3 and C4

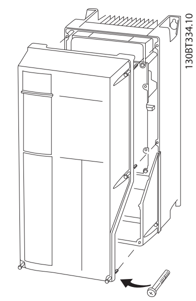


Illustration 5.18: Frame sizes A5, B1, B2, C1 and C2

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5.3.9 Control Terminals

Drawing reference numbers:

1. 10 pole plug digital I/O.
2. 3 pole plug RS485 Bus.
3. 6 pole analog I/O.
4. USB Connection.

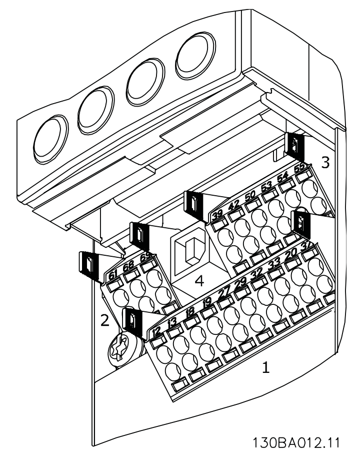
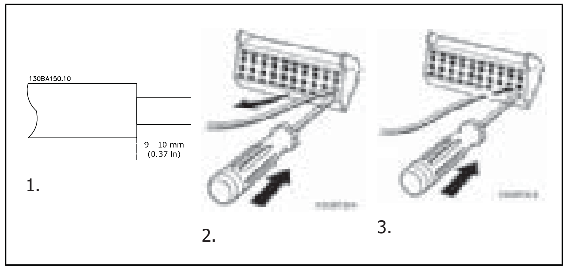


Illustration 5.19: Control terminals (all enclosures)

5.3.10 Control Cable Terminals

To mount the cable to the terminal:

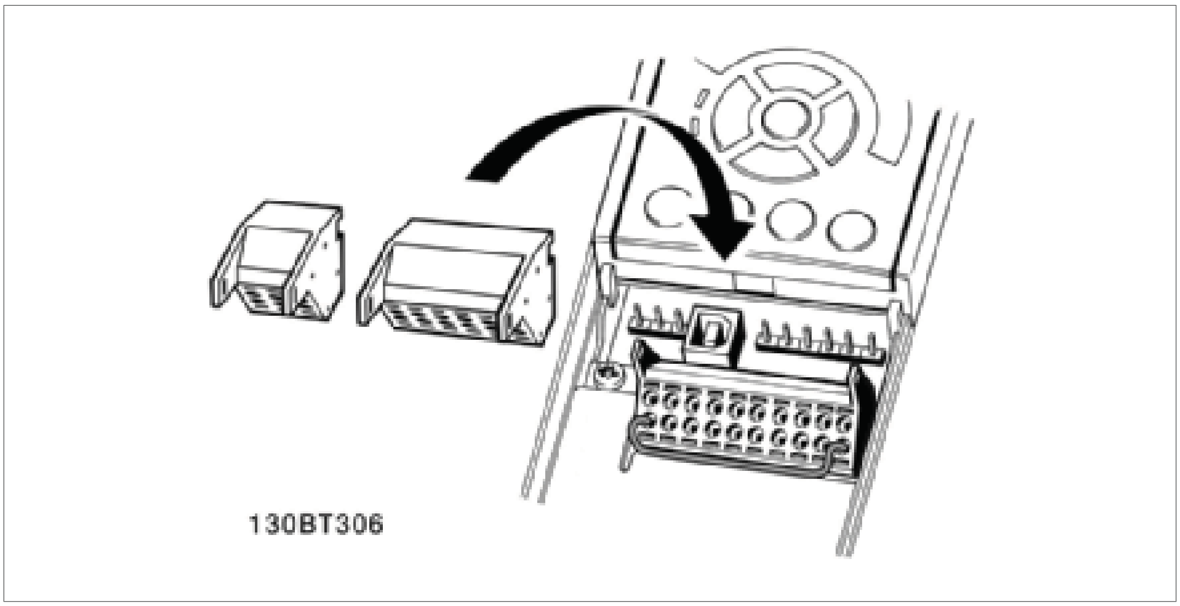
1. Strip isolation of 9-10 mm
2. Insert a screw driver[1)] in the square hole.
3. Insert the cable in the adjacent circular hole.
4. Remove the screw driver. The cable is now mounted to the terminal.



To remove the cable from the terminal:

1. Insert a screw driver[1)] in the square hole.
2. Pull out the cable.

[1)] Max. 0.4 x 2.5 mm



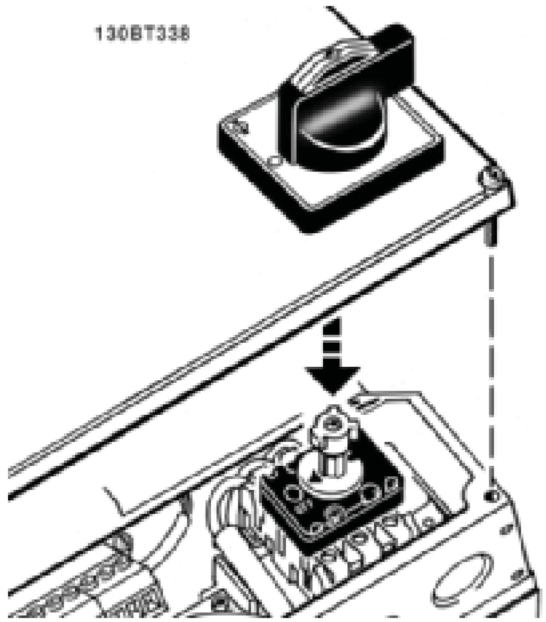


Illustration 5.20: Assembling of IP21 / IP55 / NEMA TYPE 12 housing with mains disconnector.

5.3.11 Basic Wiring Example

1. Mount terminals from the accessory bag to the front of the frequency converter.
2. Connect terminals 18 and 27 to +24 V (terminal 12/13)

Default settings:
18 = Start
27 = stop inverse

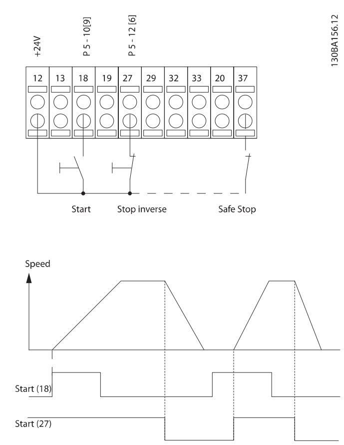


Illustration 5.21: Terminal 37 available with Safe Stop Function only!

5.3.12 Control Cable Length

Digital in / digital out

Dependent on what kind of electronics is being used, the maximum cable impedance may be calculated based on the 4 kΩ frequency converter input impedance.

Analog in / analog out

Again the electronics used puts a limitation on the cable length.

NB!
Noise is always a factor to be reckoned with.

5.3.13 Electrical Installation, Control Cables

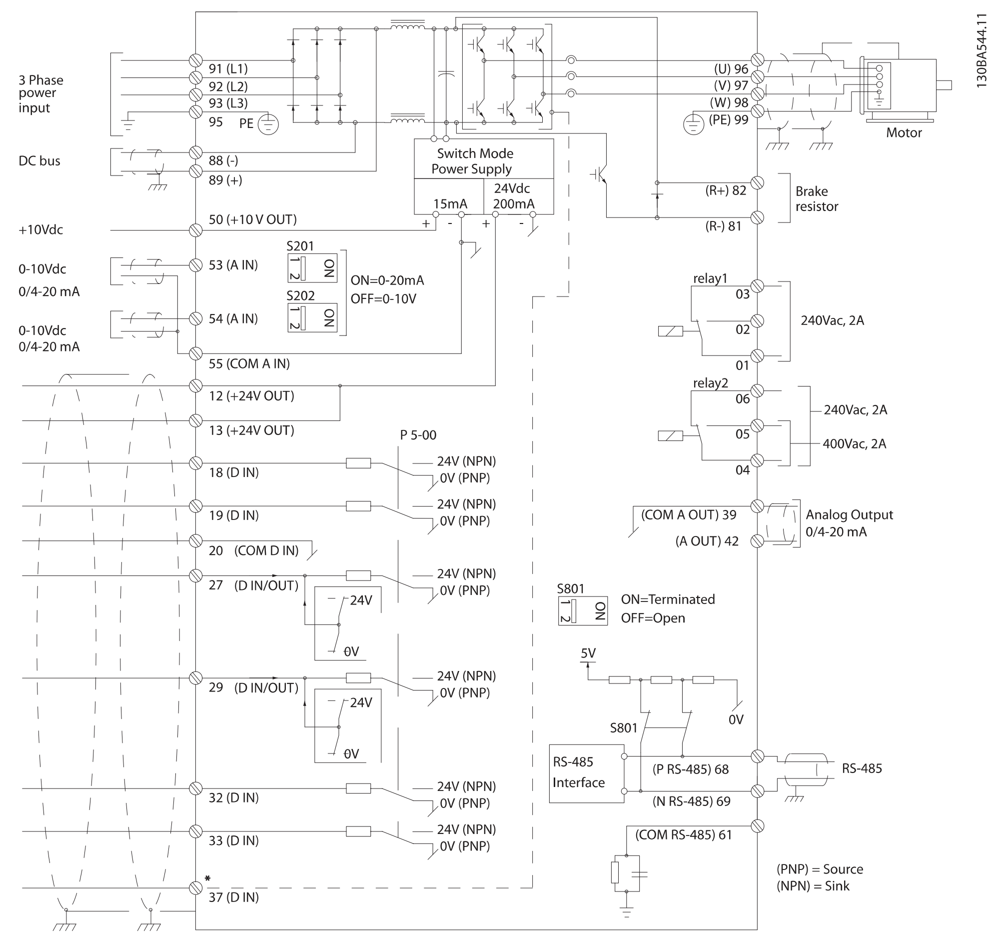


Illustration 5.22: Terminal 37: Safe Stop input available with Safe Stop Function only!

Very long control cables and analog signals may in rare cases and depending on installation result in 50/60 Hz earth loops due to noise from mains supply cables.

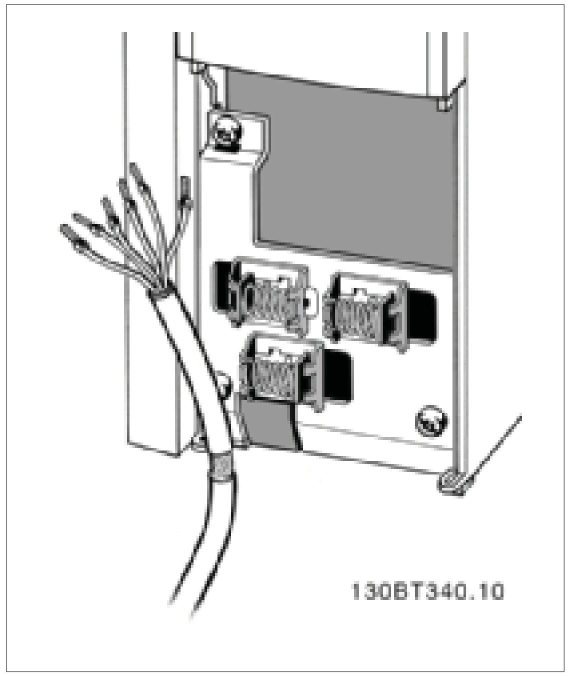
If this occurs, you may have to break the screen or insert a 100 nF capacitor between screen and chassis.

The digital and analog in- and outputs must be connected separately to the VLT Automation VT Drive common inputs (terminal 20, 55, 39) to avoid ground currents from both groups to affect other groups. For example, switching on the digital input may disturb the analog input signal.

NB!
Control cables must be screened/armoured.

1. Use a clamp from the accessory bag to connect the screen to the frequency converter de-coupling plate for control cables.

See section entitled *Earthing of Screened/Armoured Control Cables* for the correct termination of control cables.



5.3.14 Switches S201, S202, and S801

Switches S201 (A53) and S202 (A54) are used to select a current (0-20 mA) or a voltage (0 to 10 V) configuration of the analog input terminals 53 and 54 respectively.

Switch S801 (BUS TER.) can be used to enable termination on the RS-485 port (terminals 68 and 69).

See drawing *Diagram showing all electrical terminals* in section *Electrical Installation.*

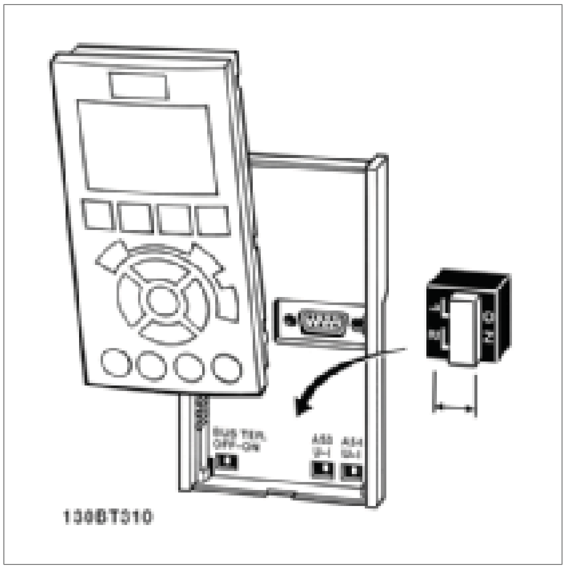
Default setting:

S201 (A53) = OFF (voltage input)

S202 (A54) = OFF (voltage input)

S801 (Bus termination) = OFF

NB!
It is recommended to only change switch position at power off.



5.4 Connections - Frame sizes D, E and F

5.4.1 Power Connections

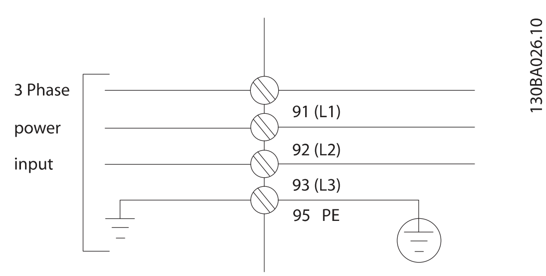
Cabling and Fusing

NB!
Cables General
All cabling must comply with national and local regulations on cable cross-sections and ambient temperature. Copper (75°C) conductors are recommended.

The power cable connections are situated as shown below. Dimensioning of cable cross section must be done in accordance with the current ratings and local legislation. See the *Specifications section* for details.

For protection of the frequency converter, the recommended fuses must be used or the unit must be with built-in fuses. Recommended fuses can be seen in the tables of the fuse section. Always ensure that proper fusing is made according to local regulation.

The mains connection is fitted to the mains switch if this is included.



NB!
The motor cable must be screened/armoured. If an unscreened/unarmoured cable is used, some EMC requirements are not complied with. Use a screened/armoured motor cable to comply with EMC emission specifications. For more information, see *EMC specifications* in the *Design Guide*.

See section *General Specifications* for correct dimensioning of motor cable cross-section and length.

Screening of cables:
Avoid installation with twisted screen ends (pigtails). They spoil the screening effect at higher frequencies. If it is necessary to break the screen to install a motor isolator or motor contactor, the screen must be continued at the lowest possible HF impedance.

Connect the motor cable screen to both the de-coupling plate of the frequency converter and to the metal housing of the motor.

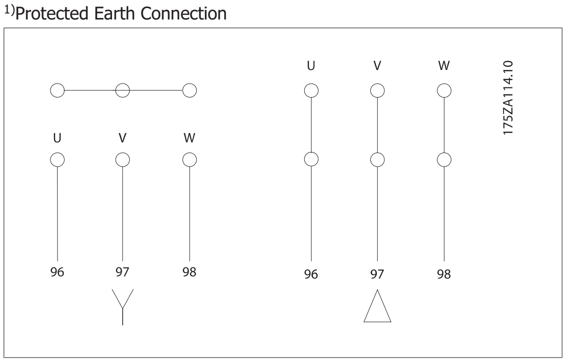
Make the screen connections with the largest possible surface area (cable clamp). This is done by using the supplied installation devices within the frequency converter.

Cable-length and cross-section:
The frequency converter has been EMC tested with a given length of cable. Keep the motor cable as short as possible to reduce the noise level and leakage currents.

Switching frequency:
When frequency converters are used together with Sine-wave filters to reduce the acoustic noise from a motor, the switching frequency must be set according to the instruction in par. 14-01 *Switching Frequency*.

Term. no.	96	97	98	99	
	U	V	W	PE[1)]	Motor voltage 0-100% of mains voltage.
					3 wires out of motor
	U1	V1	W1	PE[1)]	Delta-connected
	W2	U2	V2		6 wires out of motor
	U1	V1	W1	PE[1)]	Star-connected U2, V2, W2
					U2, V2 and W2 to be interconnected separately.

[1)]Protected Earth Connection



NB!
In motors without phase insulation paper or other insulation reinforcement suitable for operation with voltage supply (such as a frequency converter), fit a Sine-wave filter on the output of the frequency converter.

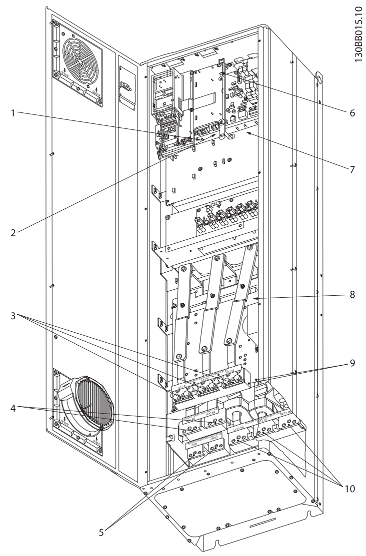


Illustration 5.23: Compact IP 21 (NEMA 1) and IP 54 (NEMA 12), frame size D1

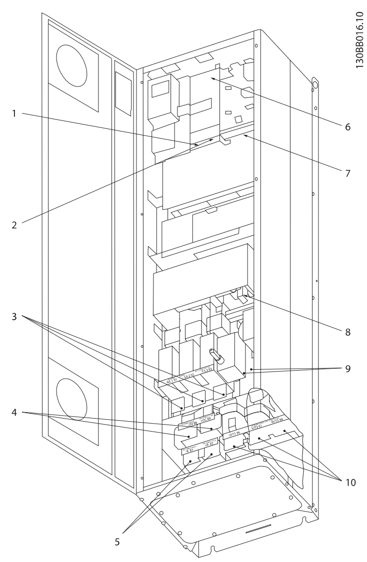


Illustration 5.24: Compact IP 21 (NEMA 1) and IP 54 (NEMA 12) with disconnect, fuse and RFI filter, frame size D2

1)	AUX Relay	5)	Brake
	01 02 03		-R +R
	04 05 06		81 82
2)	Temp Switch	6)	SMPS Fuse (see fuse tables for part number)
	106 104 105	7)	AUX Fan
3)	Line		100 101 102 103
	R S T		L1 L2 L1 L2
	91 92 93	8)	Fan Fuse (see fuse tables for part number)
	L1 L2 L3	9)	Mains ground
4)	Load sharing	10)	Motor
	-DC +DC		U V W
	88 89		96 97 98
			T1 T2 T3

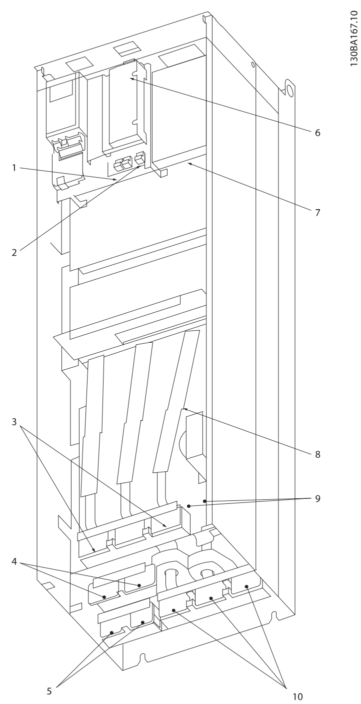


Illustration 5.25: Compact IP 00 (Chassis), frame size D3

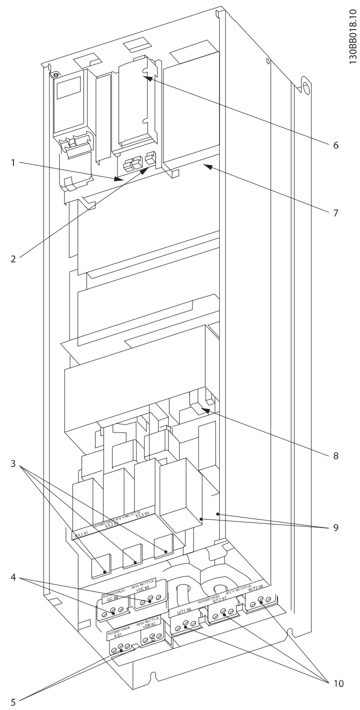


Illustration 5.26: Compact IP 00 (Chassis) with disconnect, fuse and RFI filter, frame size D4

1) AUX Relay

01	02	03
04	05	06

2) Temp Switch

106	104	105

3) Line

R	S	T
91	92	93
L1	L2	L3

4) Load sharing

-DC	+DC
88	89

5) Brake

-R	+R
81	82

6) SMPS Fuse (see fuse tables for part number)

7) AUX Fan

100	101	102	103
L1	L2	L1	L2

8) Fan Fuse (see fuse tables for part number)

9) Mains ground

10) Motor

U	V	W
96	97	98
T1	T2	T3

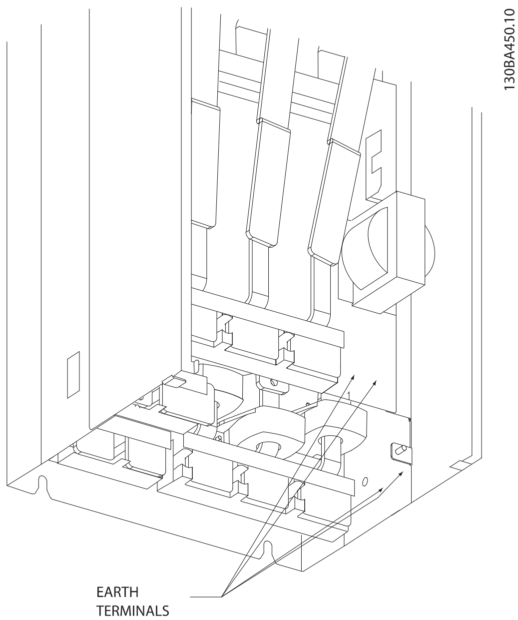


Illustration 5.27: Position of earth terminals IP00, frame sizes D

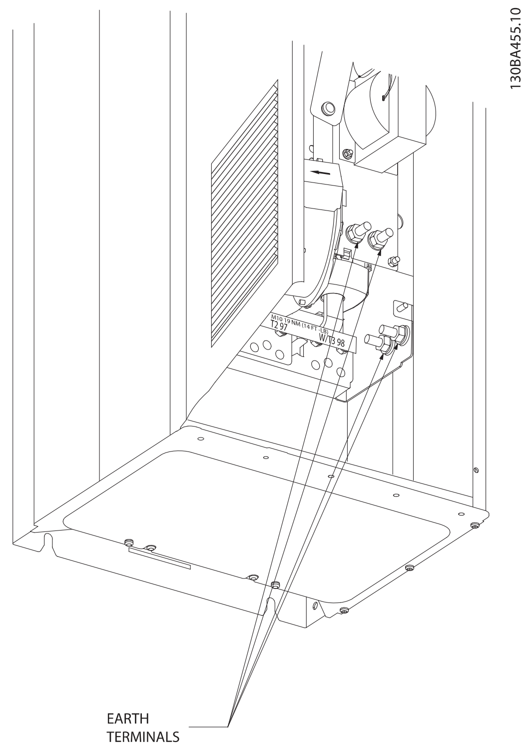


Illustration 5.28: Position of earth terminals IP21 (NEMA type 1) and IP54 (NEMA type 12)

NB!
D2 and D4 shown as examples. D1 and D3 are equivalent.

5

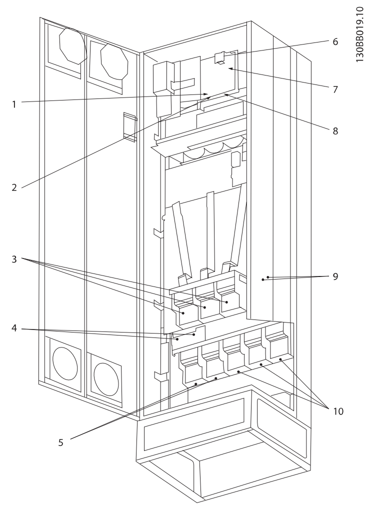


Illustration 5.29: Compact IP 21 (NEMA 1) and IP 54 (NEMA 12) frame size E1

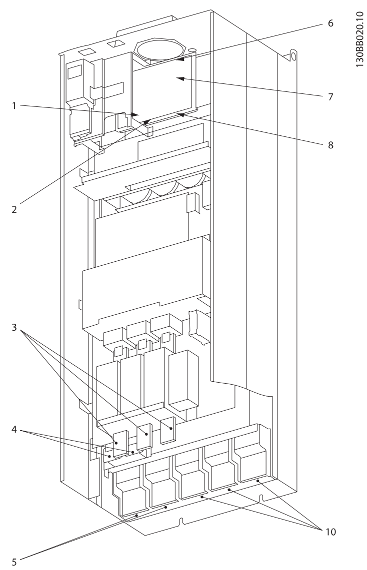


Illustration 5.30: Compact IP 00 (Chassis) with disconnect, fuse and RFI filter, frame size E2

1) AUX Relay

01	02	03
04	05	06

2) Temp Switch

106	104	105

3) Line

R	S	T
91	92	93
L1	L2	L3

4) Brake

-R	+R
81	82

5) Load sharing

-DC	+DC
88	89

6) SMPS Fuse (see fuse tables for part number)

7) Fan Fuse (see fuse tables for part number)

8) AUX Fan

100	101	102	103
L1	L2	L1	L2

9) Mains ground

10) Motor

U	V	W
96	97	98
T1	T2	T3

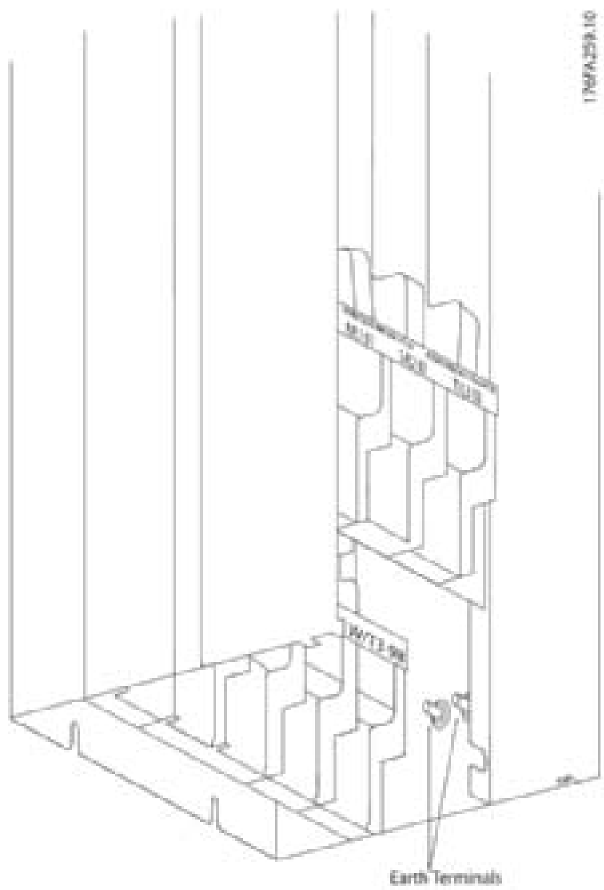


Illustration 5.31: Position of earth terminals IP00, frame sizes E

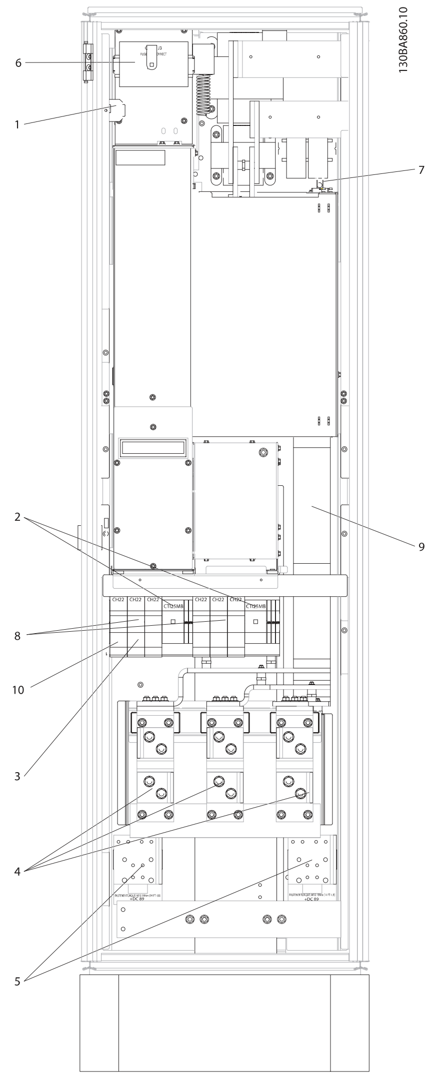


Illustration 5.32: Rectifier Cabinet, frame size F1, F2, F3 and F4

1)	24 V DC, 5 A	5)	Loadsharing
	T1 Output Taps		-DC +DC
	Temp Switch		88 89
	106 104 105	6)	Control Transformer Fuses (2 or 4 pieces). See fuse tables for part numbers
2)	Manual Motor Starters	7)	SMPS Fuse. See fuse tables for part numbers
3)	30 A Fuse Protected Power Terminals	8)	Manual Motor Controller fuses (3 or 6 pieces). See fuse tables for part numbers
4)	Line	9)	Line Fuses, F1 and F2 frame (3 pieces). See fuse tables for part numbers
	R S T	10)	30 Amp Fuse Protected Power fuses
	L1 L2 L3		

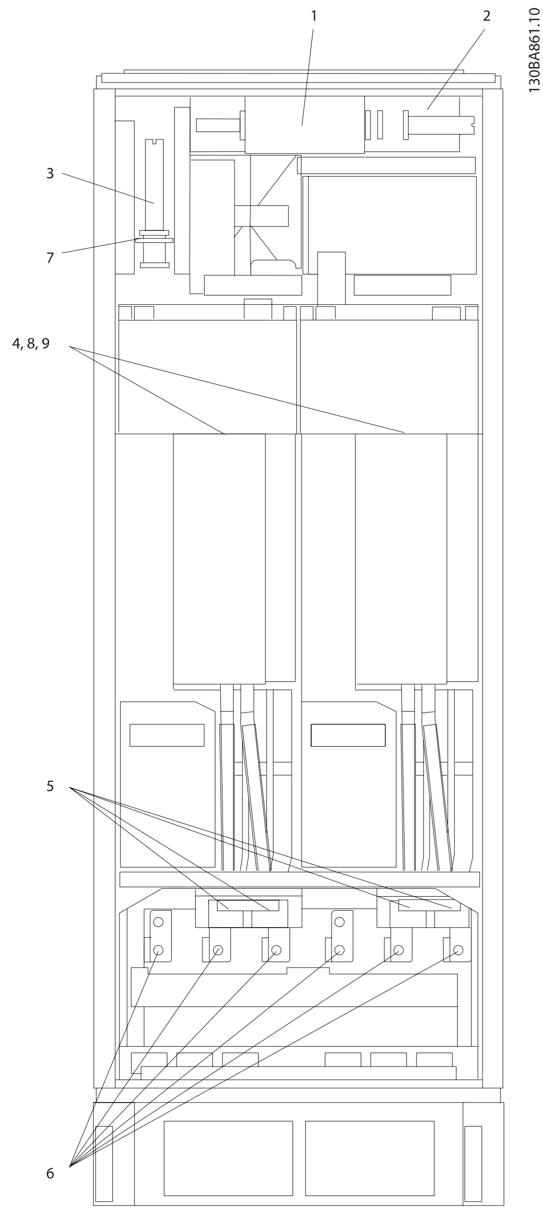


Illustration 5.33: Inverter Cabinet, frame size F1 and F3

1)	External Temperature Monitoring	6)	Motor
2)	AUX Relay		U V W
	01 02 03		96 97 98
	04 05 06		T1 T2 T3
3)	NAMUR	7)	NAMUR Fuse. See fuse tables for part numbers
4)	AUX Fan	8)	Fan Fuses. See fuse tables for part numbers
	100 101 102 103	9)	SMPS Fuses. See fuse tables for part numbers
	L1 L2 L1 L2		
5)	Brake		
	-R +R		
	81 82		

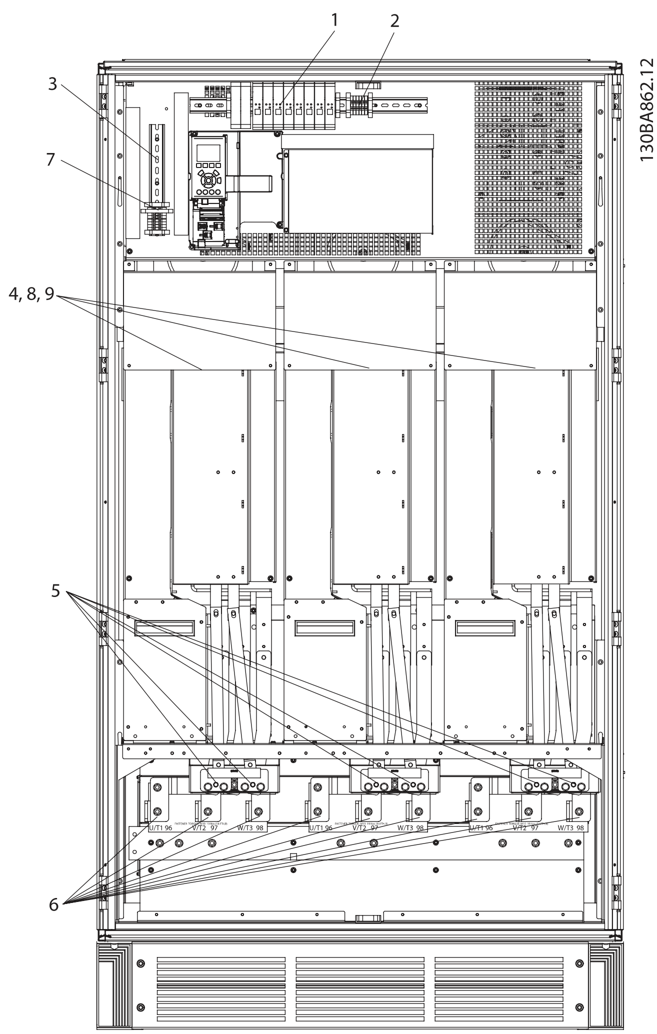


Illustration 5.34: Inverter Cabinet, frame size F2 and F4

1)	External Temperature Monitoring	6)	Motor
2)	AUX Relay		U V W
	01 02 03		96 97 98
	04 05 06		T1 T2 T3
3)	NAMUR	7)	NAMUR Fuse. See fuse tables for part numbers
4)	AUX Fan	8)	Fan Fuses. See fuse tables for part numbers
	100 101 102 103	9)	SMPS Fuses. See fuse tables for part numbers
	L1 L2 L1 L2		
5)	Brake		
	-R +R		
	81 82		

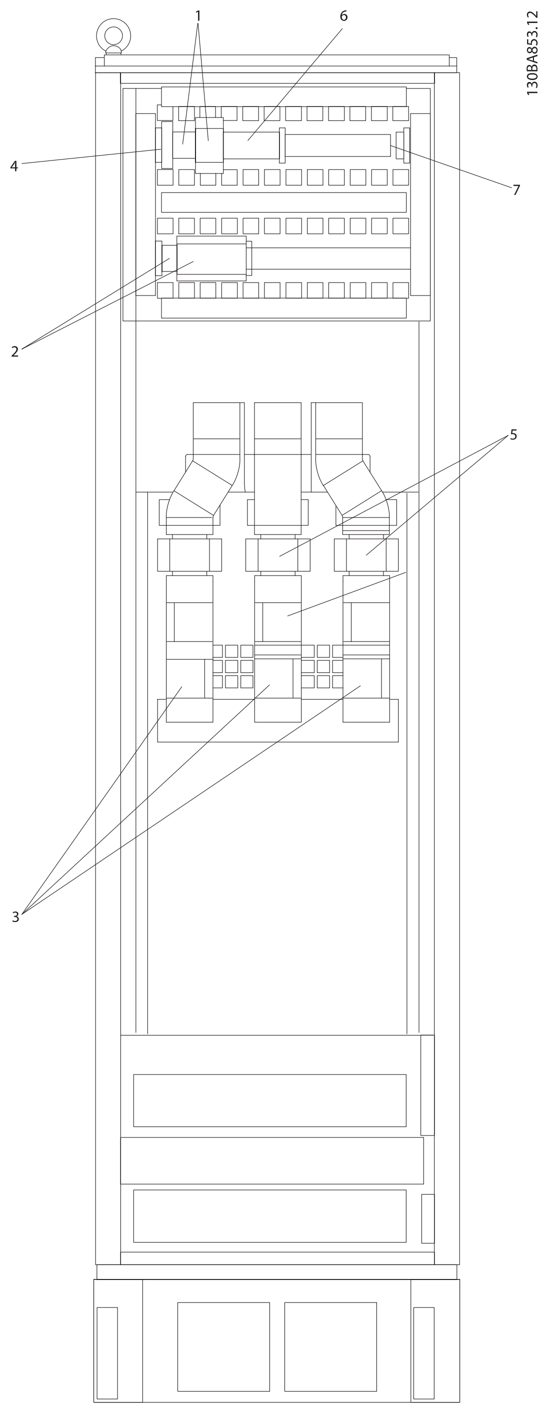


Illustration 5.35: Options Cabinet, frame size F3 and F4

1)	Pilz Relay Terminal	4)	Safety Relay Coil Fuse with PILS Relay See fuse tables for part numbers
2)	RCD or IRM Terminal	5)	Line Fuses, F3 and F4 (3 pieces) See fuse tables for part numbers
3)	Mains R S T 91 92 93 L1 L2 L3	6)	Contactor Relay Coil (230 VAC). N/C and N/O Aux Contacts
		7)	Circuit Breaker Shunt Trip Control Terminals (230 VAC or 230 VDC)

5.4.2 Shielding against Electrical Noise

Before mounting the mains power cable, mount the EMC metal cover to ensure best EMC performance.

NOTE: The EMC metal cover is only included in units with an RFI filter.

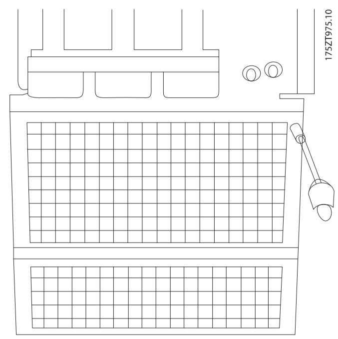


Illustration 5.36: Mounting of EMC shield.

5.4.3 External Fan Supply

In case the frequency converter is supplied by DC or if the fan must run independently of the power supply, an external power supply can be applied. The connection is made on the power card.

Terminal No.	Function
100, 101	Auxiliary supply S, T
102, 103	Internal supply S, T

The connector located on the power card provides the connection of line voltage for the cooling fans. The fans are connected from factory to be supplied form a common AC line (jumpers between 100-102 and 101-103). If external supply is needed, the jumpers are removed and the supply is connected to terminals 100 and 101. A 5 Amp fuse should be used for protection. In UL applications this should be LittleFuse KLK-5 or equivalent.

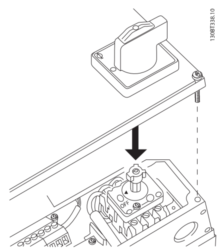
5

5.5 Disconnectors, Circuit Breakers and Contactors

5.5.1 Mains Disconnectors

Assembling of IP55 / NEMA Type 12 (A5 housing) with mains disconnector

Mains switch is placed on left side on frame sizes B1, B2, C1 and C2 . Mains switch on A5 frames is placed on right side



Frame size:	Type:
A5	Kraus&Naimer KG20A T303
B1	Kraus&Naimer KG64 T303
B2	Kraus&Naimer KG64 T303
C1 30 kW High Overload	Kraus&Naimer KG100 T303
C1 37-45 kW High Overload	Kraus&Naimer KG105 T303
C2 55 kW High Overload	Kraus&Naimer KG160 T303
C2 75 kW High Overload	Kraus&Naimer KG250 T303

5.5.2 Mains Disconnectors - Frame Size D, E and F

Frame size	Power & Voltage	Type
D1/D3	P90K-P110 380-500V & P90K-P132 525-690V	ABB OETL-NF200A
D2/D4	P132-P200 380-500V & P160-P315 525-690V	ABB OETL-NF400A
E1/E2	P250 380-500V & P355-P560500HP-750HP 525-690V	ABB OETL-NF600A
E1/E2	P315-P400 380-500V	ABB OETL-NF800A
F3	P450 380-500V & P630-P710 525-690V	Merlin Gerin NPJF36000S12AAYP*
F4	P500-P630 380-500V & P800 525-690V	Merlin Gerin NRK36000S20AAYP*
F4	P710-P800 380-500V & P900-P1M0 525-690V	Merlin Gerin NRK36000S20AAYP*

* Drive SCCR rating maybe less than 100 kA when this option is added. See the drive label for SCCR rating.

5.5.3 F Frame Circuit Breakers

Frame size	Power & Voltage	Type
F3	P450 380-500V & P630-P710 525-690V	Merlin Gerin NPJF36120U31AABSCYP*
F4	P500-P630 380-500V & P800 525-690V	Merlin Gerin NRJF36200U31AABSCYP*
F4	P710 380-500V & P900-P1M0 525-690V	Merlin Gerin NRJF36200U31AABSCYP*
F4	P800 380-500V	Merlin Gerin NRJF36250U31AABSCYP*
* Drive SCCR rating maybe less than 100 kA when this option is added. See the drive label for SCCR rating.		

5.5.4 F Frame Mains Contactors

Frame size	Power & Voltage	Type
F3	P450-P500 380-500V & P630-P800 525-690V	Eaton XTCE650N22A*
F3	P560 380-500V	Eaton XTCE820N22A*
F3	P630380-500V	Eaton XTCEC14P22B*
F4	P900 525-690V	Eaton XTCE820N22A*
F4	P710-P800 380-500V & P1M0 525-690V	Eaton XTCEC14P22B*
* Drive SCCR rating maybe less than 100 kA when this option is added. See the drive label for SCCR rating.		

5.6 Final Set-Up and Test

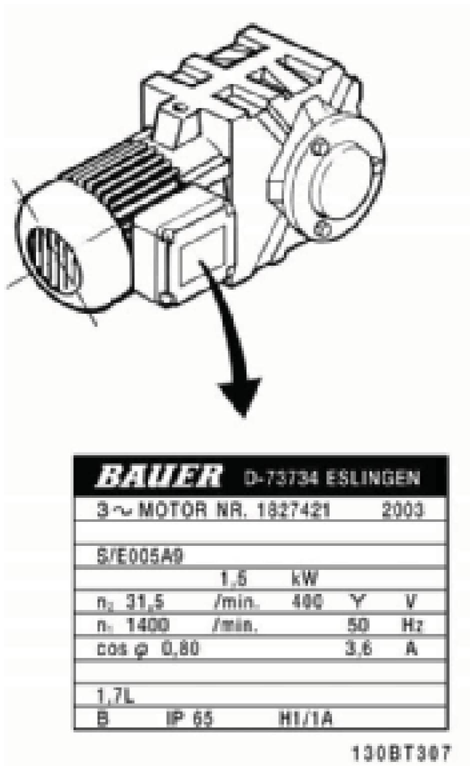
To test the set-up and ensure that the frequency converter is running, follow these steps.

Step 1. Locate the motor name plate.

NB!
The motor is either star- (Y) or delta- connected (Δ). This information is located on the motor name plate data.

Step 2. Enter the motor name plate data in this parameter list.
To access this list first press the [QUICK MENU] key then select "Q2 Quick Setup".

1.	Motor Power [kW] or Motor Power [HP]	par. 1-20 par. 1-21
2.	Motor Voltage	par. 1-22
3.	Motor Frequency	par. 1-23
4.	Motor Current	par. 1-24
5.	Motor Nominal Speed	par. 1-25


BAUER D-73734 ESLINGEN
3 ~ MOTOR NR. 1827421 2003
S/E005A9
1,5 kW
n2 31,5 /min. 400 Y V
n1 1400 /min. 50 Hz
cos φ 0,80 3,6 A
1,7L
B IP 65 H1/1A
130BT307

Step 3. Activate the Automatic Motor Adaptation (AMA).

Performing an AMA will ensure optimum performance. The AMA measures the values from the motor model equivalent diagram.

1. Connect terminal 27 to terminal 12 or set par. 5-12 to 'No function' (par. 5-12 [0])
2. Activate the AMA par. 1-29.
3. Choose between complete or reduced AMA. If an LC filter is mounted, run only the reduced AMA, or remove the LC filter during the AMA procedure.
4. Press the [OK] key. The display shows "Press [Hand on] to start".
5. Press the [Hand on] key. A progress bar indicates if the AMA is in progress.

Stop the AMA during operation

1. Press the [OFF] key - the frequency converter enters into alarm mode and the display shows that the AMA was terminated by the user.

Successful AMA

1. The display shows "Press [OK] to finish AMA".
2. Press the [OK] key to exit the AMA state.

Unsuccessful AMA

1. The frequency converter enters into alarm mode. A description of the alarm can be found in the *Troubleshooting* section.
2. "Report Value" in the [Alarm Log] shows the last measuring sequence carried out by the AMA, before the frequency converter entered alarm mode. This number along with the description of the alarm will assist you in troubleshooting. If you contact Danfoss Service, make sure to mention number and alarm description.

NB!
Unsuccessful AMA is often caused by incorrectly registered motor name plate data or too big difference between the motor power size and the VLT Automation VT Drive power size.

Step 4. Set speed limit and ramp time.

Set up the desired limits for speed and ramp time.

Minimum Reference	par. 3-02
Maximum Reference	par. 3-03

Motor Speed Low Limit	par. 4-11 or 4-12
Motor Speed High Limit	par. 4-13 or 4-14

Ramp-up Time 1 [s]	par. 3-41
Ramp-down Time 1 [s]	par. 3-42

5.7.1 Safe Stop Installation

To carry out an installation of a Category 0 Stop (EN60204) in conformance with Safety Category 3 (EN954-1), follow these instructions:

1. The bridge (jumper) between Terminal 37 and 24 V DC of FC322 must be removed. Cutting or breaking the jumper is not sufficient. Remove it entirely to avoid short-circuiting. See jumper on illustration.
2. Connect terminal 37 to 24 V DC by a short-circuit protected cable. The 24 V DC voltage supply must be interruptible by an EN954-1 Category 3 circuit interrupt device. If the interrupt device and the frequency converter are placed in the same installation panel, you can use a regular cable instead of a protected one.

Illustration 5.37: Bridge jumper between terminal 37 and 24 VDC.

The illustration below shows a Stopping Category 0 (EN 60204-1) with safety Cat. 3 (EN 954-1). The circuit interrupt is caused by an opening door contact. The illustration also shows how to connect a non-safety related hardware coast.

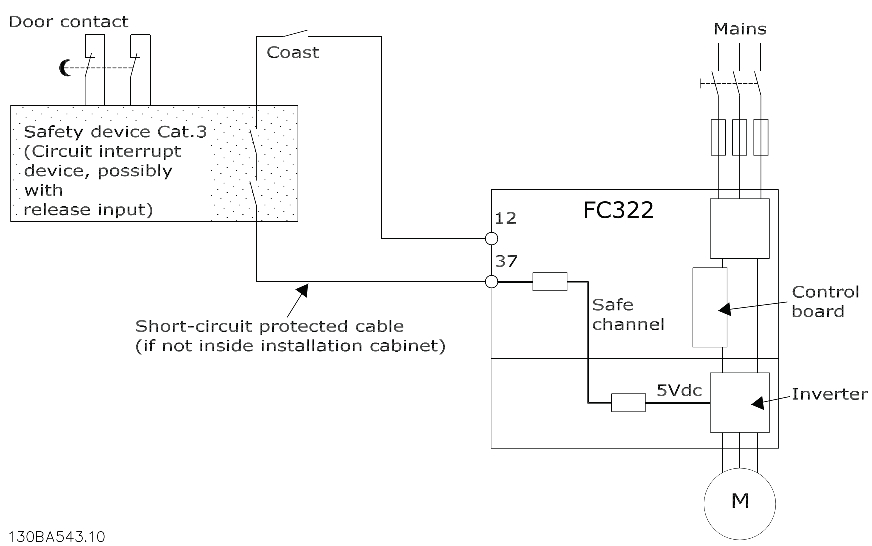


Illustration 5.38: Illustration of the essential aspects of an installation to achieve a Stopping Category 0 (EN 60204-1) with safety Cat. 3 (EN 954-1).

5.7.2 Safe Stop Commissioning Test

After installation and before first operation, perform a commissioning test of an installation or application making use of FC 200 Safe Stop. Moreover, perform the test after each modification of the installation or application, which the FC 200 Safe Stop is part of.

The commissioning test:

1. Remove the 24 V DC voltage supply to terminal 37 by the interrupt device while the motor is driven by the FC322 (i.e. mains supply is not interrupted). The test step is passed if the motor reacts with a coast and the mechanical brake (if connected) is activated.
2. Then send Reset signal (via Bus, Digital I/O, or [Reset] key). The test step is passed if the motor remains in the Safe Stop state, and the mechanical brake (if connected) remains activated.

3. Then reapply 24 V DC to terminal 37. The test step is passed if the motor remains in the coasted state, and the mechanical brake (if connected) remains activated.
4. Then send Reset signal (via Bus, Digital I/O, or [Reset] key). The test step is passed if the motor becomes operational again.
5. The commissioning test is passed if all four test steps are passed.

5

5.7 Additional Connections

5.8.1 Relay Output

Relay 1

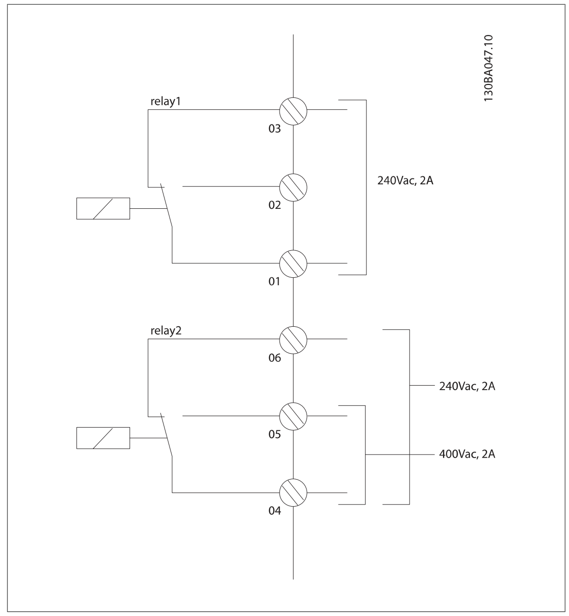
- Terminal 01: common
- Terminal 02: normal open 240 V AC
- Terminal 03: normal closed 240 V AC

Relay 2

- Terminal 04: common
- Terminal 05: normal open 400 V AC
- Terminal 06: normal closed 240 V AC

Relay 1 and relay 2 are programmed in par. 5-40 *Function Relay*, par. 5-41 *On Delay, Relay*, and par. 5-42 *Off Delay, Relay*.

Additional relay outputs by using option module MCB 105.



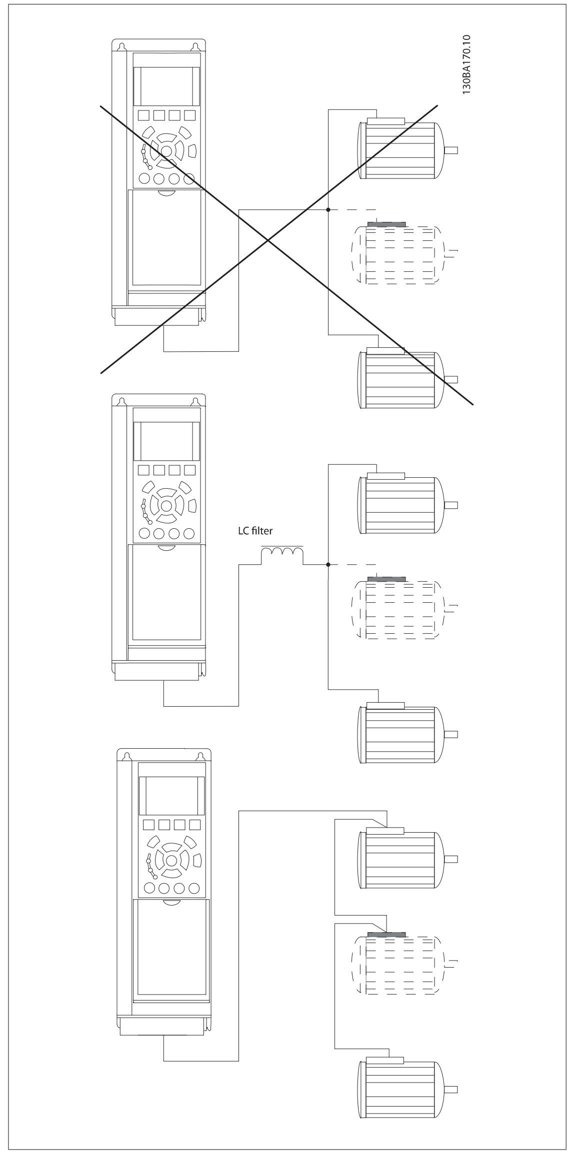
5.8.2 Parallel Connection of Motors

The frequency converter can control several parallel-connected motors. The total current consumption of the motors must not exceed the rated output current I_{INV} for the frequency converter.

NB!
When motors are connected in parallel, par. 1-29 *Automatic Motor Adaptation (AMA)* cannot be used.

Problems may arise at start and at low RPM values if motor sizes are widely different because small motors' relatively high ohmic resistance in the stator calls for a higher voltage at start and at low RPM values.

The electronic thermal relay (ETR) of the frequency converter cannot be used as motor protection for the individual motor of systems with parallel-connected motors. Provide further motor protection by e.g. thermistors in each motor or individual thermal relays. (Circuit breakers are not suitable as protection).



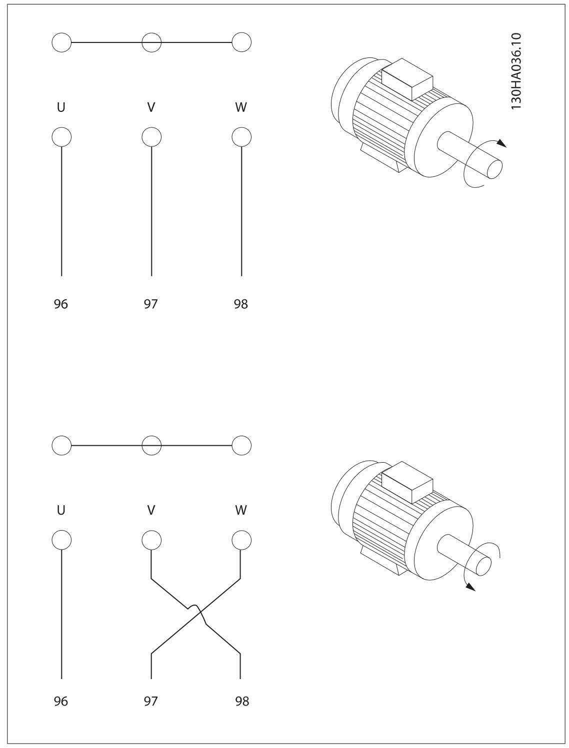
5.8.3 Direction of Motor Rotation

The default setting is clockwise rotation with the frequency converter output connected as follows.

Terminal 96 connected to U-phase
Terminal 97 connected to V-phase
Terminal 98 connected to W-phase

The direction of motor rotation is changed by switching two motor phases.

Motor rotation check can be performed using par. 1-28 *Motor Rotation Check* and following the steps shown in the display.



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5.8.4 Motor Thermal Protection

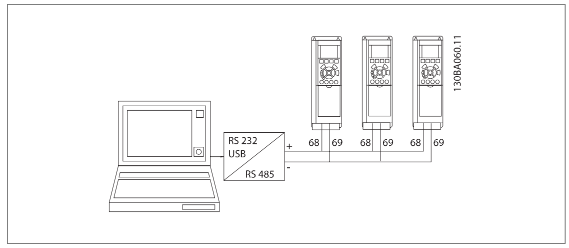
The electronic thermal relay in the frequency converter has received the UL-approval for single motor protection, when par. 1-90 *Motor Thermal Protection* is set for *ETR Trip* and par. 1-24 *Motor Current* is set to the rated motor current (see motor name plate).

5.8 Installation of Misc. Connections

5.9.1 RS 485 Bus Connection

One or more frequency converters can be connected to a control (or master) using the RS485 standardized interface. Terminal 68 is connected to the P signal (TX+, RX+), while terminal 69 is connected to the N signal (TX-,RX-).

If more than one frequency converter is connected to a master, use parallel connections.



In order to avoid potential equalizing currents in the screen, earth the cable screen via terminal 61, which is connected to the frame via an RC-link.

Bus termination
The RS485 bus must be terminated by a resistor network at both ends. For this purpose, set switch S801 on the control card for "ON".
For more information, see the paragraph *Switches S201, S202, and S801*.

NB!
Communication protocol must be set to FC MC 8-30 *Protocol*.

5.9.2 How to Connect a PC to the VLT Automation VT Drive

To control or program the frequency converter from a PC, install the MCT 10 Set-up Software.
The PC is connected via a standard (host/device) USB cable, or via the RS-485 interface as shown in the **VLT Automation VT Drive Design Guide** *How to Install > Installation of misc. connections*.

NB!
The USB connection is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals. The USB connection is connected to protection earth on the frequency converter. Use only isolated laptop as PC connection to the USB connector on the VLT Automation VT Drive.

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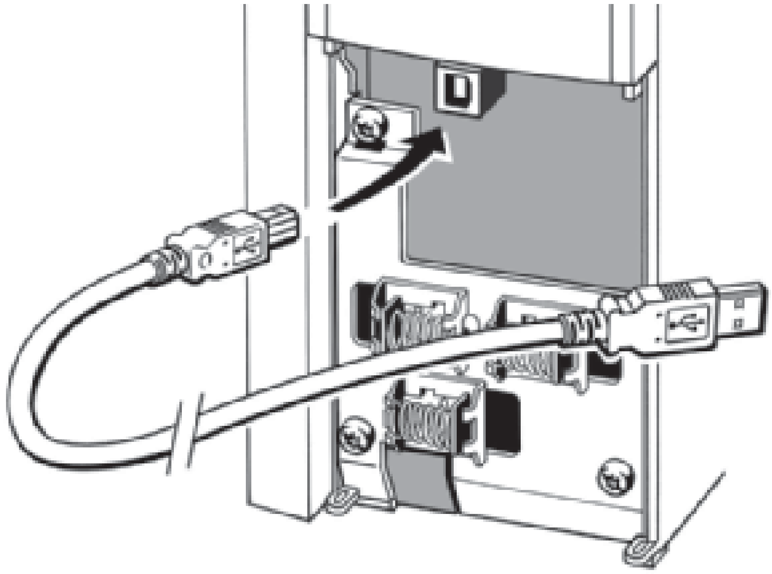


PC Software - MCT 10

All drives are equipped with a serial communication port. We provide a PC tool for communication between PC and frequency converter, VLT Motion Control Tool MCT 10 Set-up Software.

MCT 10 Set-up Software

MCT 10 has been designed as an easy to use interactive tool for setting parameters in our frequency converters.

The MCT 10 Set-up Software will be useful for:

- Planning a communication network off-line. MCT 10 contains a complete frequency converter database
- Commissioning frequency converters on line
- Saving settings for all frequency converters
- Replacing a drive in a network
- Expanding an existing network
- Future developed drives will be supported

MCT 10

Set-up Software support Profibus DP-V1 via a Master class 2 connection. It makes it possible to on line read/write parameters in a frequency converter via the Profibus network. This will eliminate the need for an extra communication network.

Save Drive Settings:

1. Connect a PC to the unit via USB com port
2. Open MCT 10 Set-up Software
3. Choose "Read from drive"
4. Choose "Save as"

All parameters are now stored in the PC.

Load Drive Settings:

1. Connect a PC to the unit via USB com port
2. Open MCT 10 Set-up software

3. Choose "Open"– stored files will be shown
4. Open the appropriate file
5. Choose "Write to drive"

All parameter settings are now transferred to the drive.

A separate manual for MCT 10 Set-up Software is available.

The MCT 10 Set-up Software Modules

The following modules are included in the software package:

MCT 10 Set-up Software
Setting parameters
Copy to and from frequency converters
Documentation and print out of parameter settings incl. diagrams

Ext. User Interface
Preventive Maintenance Schedule
Clock settings
Timed Action Programming
Smart Logic Controller Set-up
Cascade Control Config. Tool

Ordering number:

Please order your CD containing MCT 10 Set-up Software using code number 130B1000.

MCT 10 can also be downloaded from the Danfoss Internet: WWW.DANFOSS.COM, Business Area: Motion Controls.

MCT 31

The MCT 31 harmonic calculation PC tool enables easy estimation of the harmonic distortion in a given application. Both the harmonic distortion of Danfoss frequency converters as well as non-Danfoss frequency converters with different additional harmonic reduction devices, such as Danfoss AHF filters and 12-18-pulse rectifiers, can be calculated.

Ordering number:

Please order your CD containing the MCT 31 PC tool using code number 130B1031.

MCT 31 can also be downloaded from the Danfoss Internet: WWW.DANFOSS.COM, Business Area: Motion Controls.

5.9 Safety

5.10.1 High Voltage Test

Carry out a high voltage test by short-circuiting terminals U, V, W, L_1, L_2 and L_3. Energize maximum 2.15 kV DC for 380-500V frequency converters and 2.525 kV DC for 525-690V frequency converters for one second between this short-circuit and the chassis.

NB!
When running high voltage tests of the entire installation, interrupt the mains and motor connection if the leakage currents are too high.

5.10.2 Safety Earth Connection

The frequency converter has a high leakage current and must be earthed appropriately for safety reasons acording to EN 50178.

The earth leakage current from the frequency converter exceeds 3.5 mA. To ensure a good mechanical connection from the earth cable to the earth connection (terminal 95), the cable cross-section must be at least 10 mm2 or 2 rated earth wires terminated separately.

5.10 EMC-correct Installation

5.11.1 Electrical Installation - EMC Precautions

The following is a guideline to good engineering practice when installing frequency converters. Follow these guidelines to comply with EN 61800-3 *First environment*. If the installation is in EN 61800-3 *Second environment,* i.e. industrial networks, or in an installation with its own transformer, deviation from these guidelines is allowed but not recommended. See also paragraphs *CE Labelling, General Aspects of EMC Emission* and *EMC Test Results*.

Good engineering practice to ensure EMC-correct electrical installation:

- Use only braided screened/armoured motor cables and braided screened/armoured control cables. The screen should provide a minimum coverage of 80%. The screen material must be metal, not limited to but typically copper, aluminium, steel or lead. There are no special requirements for the mains cable.
- Installations using rigid metal conduits are not required to use screened cable, but the motor cable must be installed in conduit separate from the control and mains cables. Full connection of the conduit from the drive to the motor is required. The EMC performance of flexible conduits varies a lot and information from the manufacturer must be obtained.
- Connect the screen/armour/conduit to earth at both ends for motor cables as well as for control cables. In some cases, it is not possible to connect the screen in both ends. If so, connect the screen at the frequency converter. See also *Earthing of Braided Screened/Armoured Control Cables*.
- Avoid terminating the screen/armour with twisted ends (pigtails). It increases the high frequency impedance of the screen, which reduces its effectiveness at high frequencies. Use low impedance cable clamps or EMC cable glands instead.
- Avoid using unscreened/unarmoured motor or control cables inside cabinets housing the drive(s), whenever this can be avoided.

Leave the screen as close to the connectors as possible.

The illustration shows an example of an EMC-correct electrical installation of an IP 20 frequency converter. The frequency converter is fitted in an installation cabinet with an output contactor and connected to a PLC, which is installed in a separate cabinet. Other ways of doing the installation may have just as good an EMC performance, provided the above guide lines to engineering practice are followed.

If the installation is not carried out according to the guideline and if unscreened cables and control wires are used, some emission requirements are not complied with, although the immunity requirements are fulfilled. See the paragraph *EMC test results*.

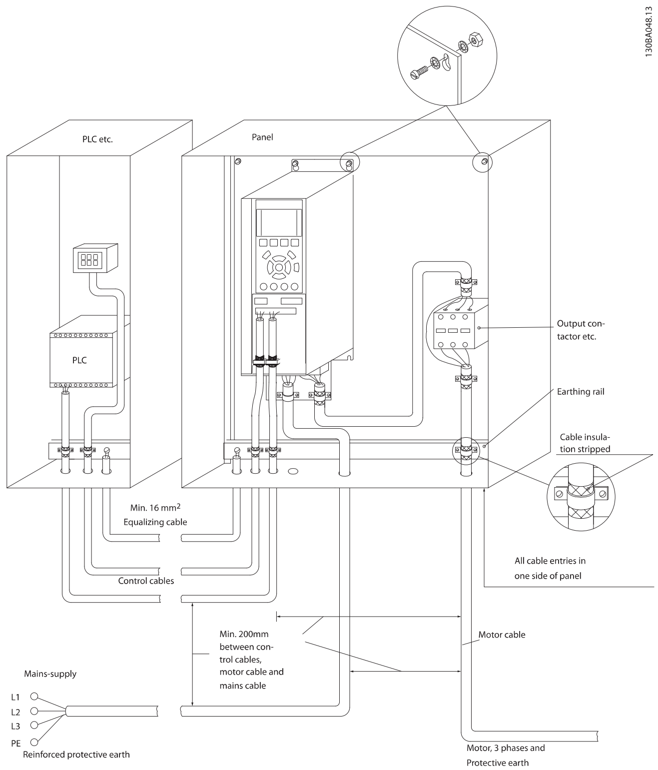


Illustration 5.39: EMC-correct electrical installation of a frequency converter in cabinet.

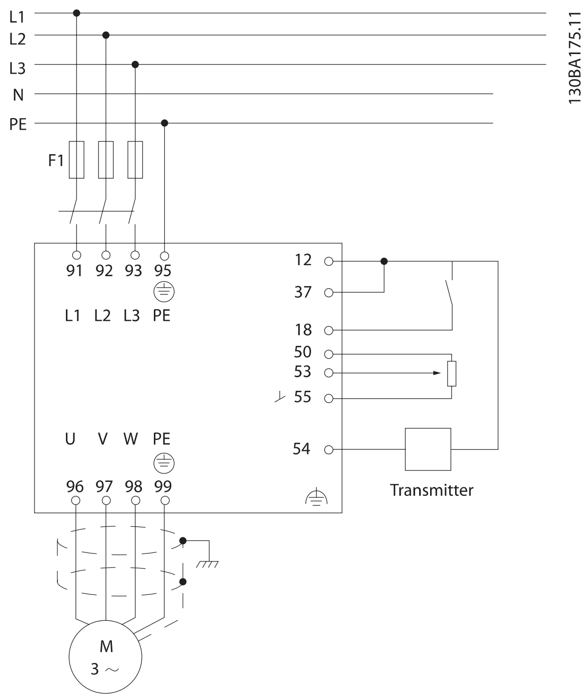


Illustration 5.40: Electrical connection diagram.

5.11.2 Use of EMC-Correct Cables

Danfoss recommends braided screened/armoured cables to optimise EMC immunity of the control cables and the EMC emission from the motor cables.

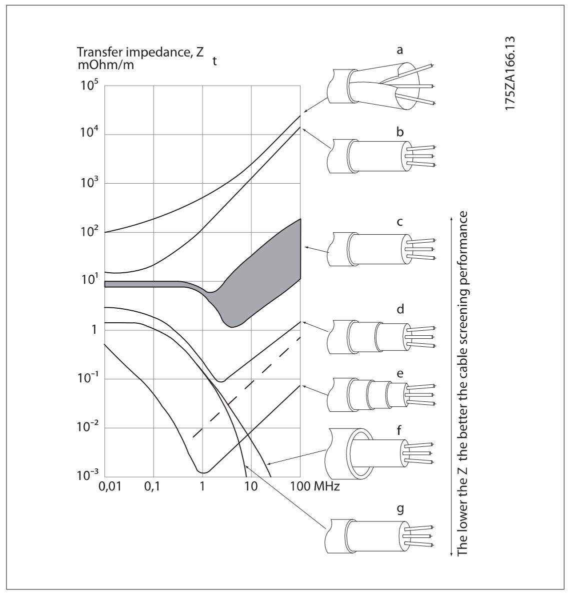
The ability of a cable to reduce the in- and outgoing radiation of electric noise depends on the transfer impedance (Z_T). The screen of a cable is normally designed to reduce the transfer of electric noise; however, a screen with a lower transfer impedance (Z_T) value is more effective than a screen with a higher transfer impedance (Z_T).

Transfer impedance (Z_T) is rarely stated by cable manufacturers but it is often possible to estimate transfer impedance (Z_T) by assessing the physical design of the cable.

Transfer impedance (Z_T) can be assessed on the basis of the following factors:

- The conductibility of the screen material.
- The contact resistance between the individual screen conductors.
- The screen coverage, i.e. the physical area of the cable covered by the screen - often stated as a percentage value.
- Screen type, i.e. braided or twisted pattern.

a. Aluminium-clad with copper wire.
b. Twisted copper wire or armoured steel wire cable.
c. Single-layer braided copper wire with varying percentage screen coverage.
This is the typical Danfoss reference cable.
d. Double-layer braided copper wire.
e. Twin layer of braided copper wire with a magnetic, screened/armoured intermediate layer.
f. Cable that runs in copper tube or steel tube.
g. Lead cable with 1.1 mm wall thickness.



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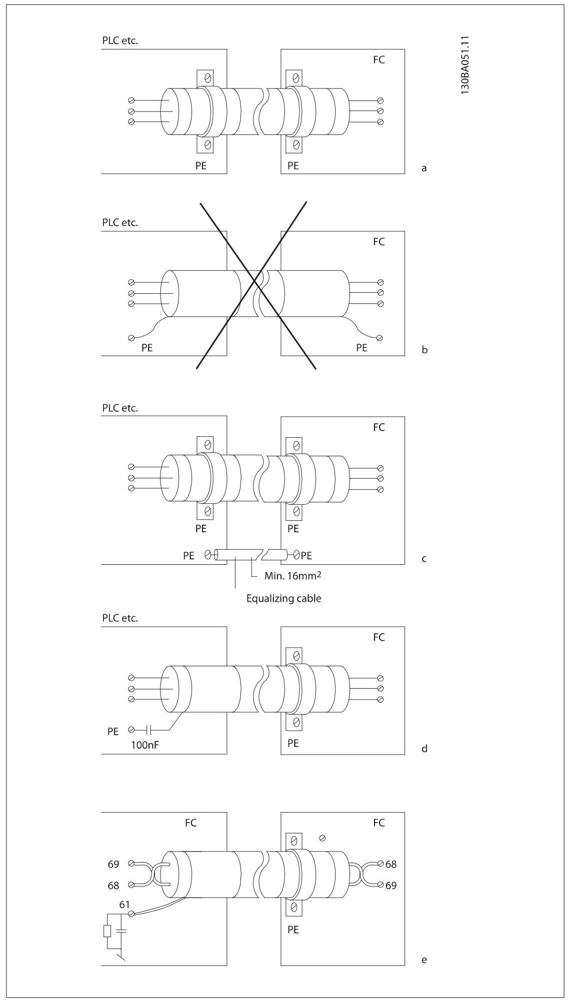
5.11.3 Earthing of Screened/Armoured Control Cables

Generally speaking, control cables must be braided screened/armoured and the screen must be connected by means of a cable clamp at both ends to the metal cabinet of the unit.

The drawing below indicates how correct earthing is carried out and what to do if in doubt.

a. **Correct earthing**
   Control cables and cables for serial communication must be fitted with cable clamps at both ends to ensure the best possible electrical contact.
b. **Wrong earthing**
   Do not use twisted cable ends (pigtails). They increase the screen impedance at high frequencies.
c. **Protection with respect to earth potential between PLC and**
   If the earth potential between the frequency converter and the PLC (etc.) is different, electric noise may occur that will disturb the entire system. Solve this problem by fitting an equalising cable, next to the control cable. Minimum cable cross-section: 16 mm ^{2}.
d. **For 50/60 Hz earth loops**
   If very long control cables are used, 50/60 Hz earth loops may occur. Solve this problem by connecting one end of the screen to earth via a 100nF capacitor (keeping leads short).
e. **Cables for serial communication**
   Eliminate low-frequency noise currents between two frequency converters by connecting one end of the screen to terminal 61. This terminal is connected to earth via an internal RC link. Use twisted-pair cables to reduce the differential mode interference between the conductors.



5.12.1 Residual Current Device

You can use RCD relays, multiple protective earthing or earthing as extra protection, provided that local safety regulations are complied with.
If an earth fault appears, a DC content may develop in the faulty current.
If RCD relays are used, you must observe local regulations. Relays must be suitable for protection of 3-phase equipment with a bridge rectifier and for a brief discharge on power-up see section *Earth Leakage Current* for further information.

6 Application Examples

6.1.1 Start/Stop

Terminal 18 = start/stop par. 5-10 [8] *Start*
Terminal 27 = No operation par. 5-12 [0] *No operation* (Default *coast inverse*

Par. 5-10 *Digital Input, Terminal 18* = *Start* (default)

Par. 5-12 *Digital Input, Terminal 27* = *coast inverse* (default)

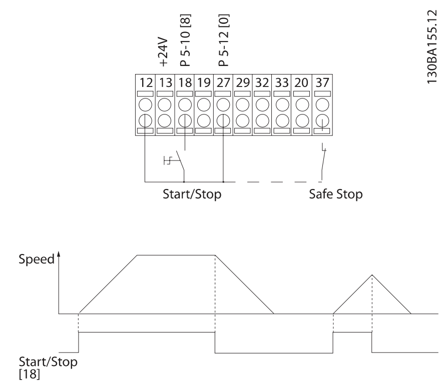


Illustration 6.1: Terminal 37: Available only with Safe Stop Function!

6.1.2 Pulse Start/Stop

Terminal 18 = start/stop par. 5-10 [9] *Latched start*
Terminal 27= Stop par. 5-12 [6] *Stop inverse*

Par. 5-10 *Digital Input, Terminal 18* = *Latched start*

Par. 5-12 *Digital Input, Terminal 27* = *Stop inverse*

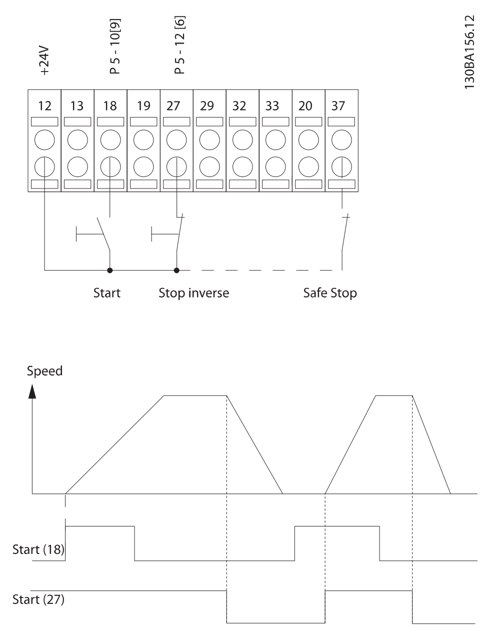


Illustration 6.2: Terminal 37: Available only with Safe Stop Function!

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6.1.3 Potentiometer Reference

Voltage reference via a potentiometer.

par. 3-15 *Reference 1 Source* [1] = *Analog Input 53*

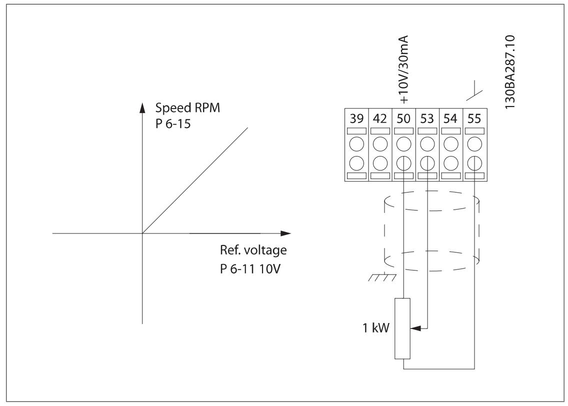
par. 6-10 *Terminal 53 Low Voltage* = 0 Volt

par. 6-11 *Terminal 53 High Voltage* = 10 Volt

par. 6-14 *Terminal 53 Low Ref./Feedb. Value* = 0 RPM

par. 6-15 *Terminal 53 High Ref./Feedb. Value* = 1.500 RPM

Switch S201 = OFF (U)



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6.1.4 Automatic Motor Adaptation (AMA)

AMA is an algorithm to measure the electrical motor parameters on a motor at standstill. This means thatAMA itself does not supply any torque.
AMA is useful when commissioning systems and optimising the adjustment of the frequency converter to the applied motor. This feature is particularly used where the default setting does not apply to the connected motor.
par. 1-29 *Automatic Motor Adaptation (AMA)* allows a choice of complete AMA with determination of all electrical motor parameters or reduced AMA with determination of the stator resistance Rs only.
The duration of a total AMA varies from a few minutes on small motors to more than 15 minutes on large motors.

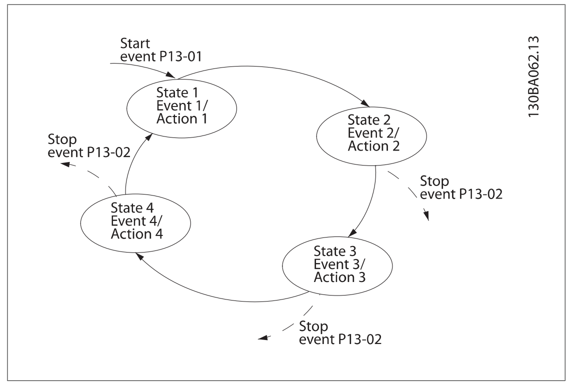
Limitations and preconditions:

- For the AMA to determine the motor parameters optimally, enter the correct motor nameplate data in par. 1-20 *Motor Power [kW]* to par. 1-28 *Motor Rotation Check*.
- For the best adjustment of the frequency converter, carry out AMA on a cold motor. Repeated AMA runs may lead to a heating of the motor, which results in an increase of the stator resistance, Rs. Normally, this is not critical.
- AMA can only be carried out if the rated motor current is minimum 35% of the rated output current of the frequency converter. AMA can be carried out on up to one oversize motor.
- It is possible to carry out a reduced AMA test with a Sine-wave filter installed. Avoid carrying out a complete AMA with a Sine-wave filter. If an overall setting is required, remove the Sine-wave filter while running a total AMA. After completion of the AMA, reinsert the Sine-wave filter.
- If motors are coupled in parallel, use only reduced AMA if any.
- Avoid running a complete AMA when using synchronous motors. If synchronous motors are applied, run a reduced AMA and manually set the extended motor data. The AMA function does not apply to permanent magnet motors.
- The frequency converter does not produce motor torque during an AMA. During an AMA, it is imperative that the application does not force the motor shaft to run, which is known to happen with e.g. wind milling in ventilation systems. This disturbs the AMA function.

The Smart Logic Control (SLC) is essentially a sequence of user defined actions (see par. 13-52 *SL Controller Action*) executed by the SLC when the associated user defined *event* (see par. 13-51 *SL Controller Event*) is evaluated as TRUE by the SLC.
Events and *actions* are each numbered and are linked in pairs called states. This means that when *event [1]* is fulfilled (attains the value TRUE), *action [1]* is executed. After this, the conditions of *event [2]* will be evaluated and if evaluated TRUE, *action [2]*will be executed and so on. Events and actions are placed in array parameters.

Only one *event* will be evaluated at any time. If an *event* is evaluated as FALSE, nothing happens (in the SLC) during the present scan interval and no other *events* will be evaluated. This means that when the SLC starts, it evaluates *event [1]* (and only *event [1]*) each scan interval. Only when *event [1]* is evaluated TRUE, the SLC executes *action [1]* and starts evaluating *event [2]*.

It is possible to program from 0 to 20 *events* and *actions*. When the last *event / action* has been executed, the sequence starts over again from *event [1] / action [1]*. The illustration shows an example with three *events / actions*:

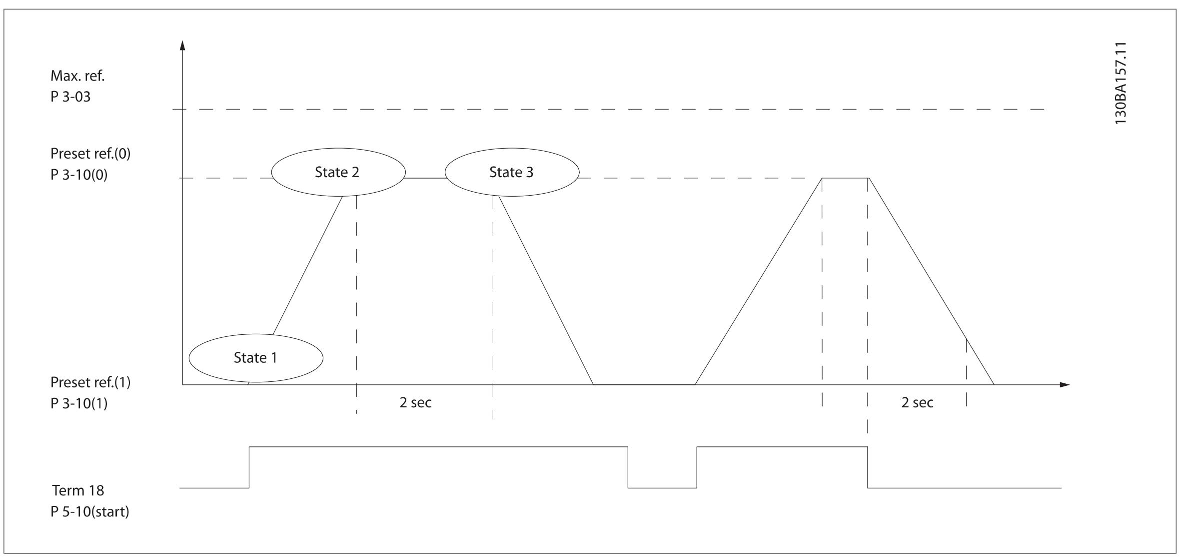


6.1.5 Smart Logic Control Programming

New useful facility in VLT Automation VT Drive is the Smart Logic Control (SLC).
In applications where a PLC is generating a simple sequence the SLC may take over elementary tasks from the main control.
SLC is designed to act from event send to or generated in the VLT Automation VT Drive. The frequency converter will then perform the pre-programmed action.

6.1.6 SLC Application Example

One sequence 1:
Start – ramp up – run at reference speed 2 sec – ramp down and hold shaft until stop.



Set the ramping times in par. 3-41 *Ramp 1 Ramp Up Time* and par. 3-42 *Ramp 1 Ramp Down Time* to the wanted times

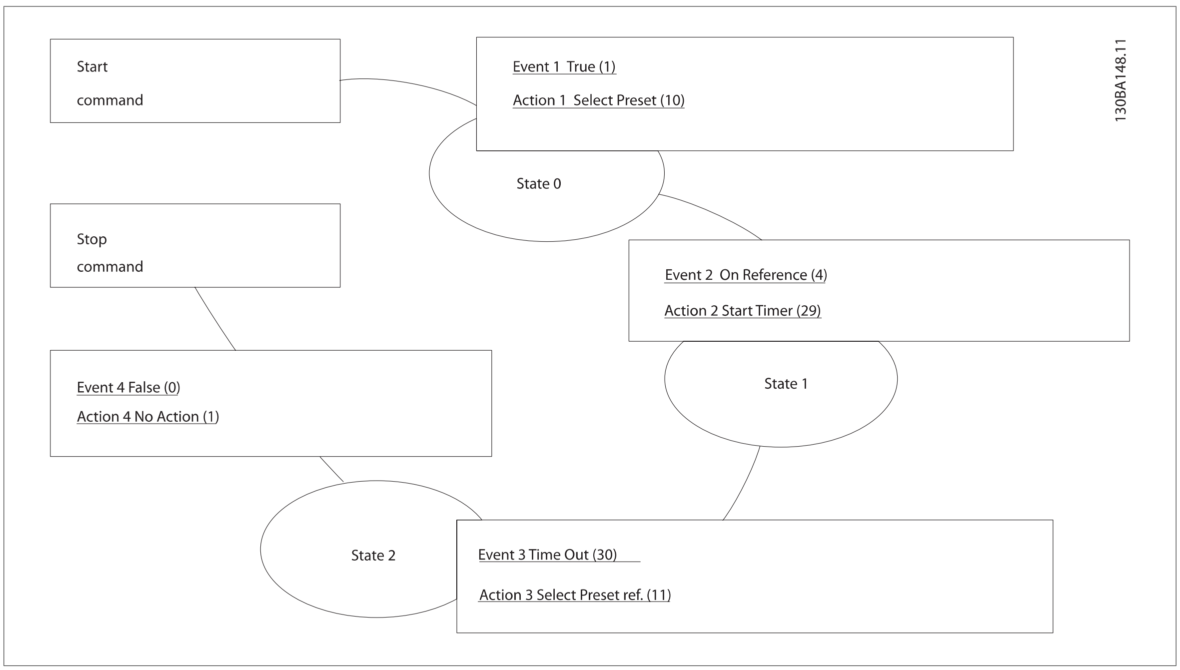
$$t_{ramp} = \frac{t_{acc} \times n_{norm}(par.\ 1 - 25)}{ref\,[RPM]}$$

Set term 27 to *No Operation* (par. 5-12 *Terminal 27 Digital Input*)

Set Preset reference 0 to first preset speed (par. 3-10 *Preset Reference* [0]) in percentage of Max reference speed (par. 3-03 *Maximum Reference*). Ex.: 60%
Set preset reference 1 to second preset speed (par. 3-10 *Preset Reference* [1] Ex.: 0 % (zero).
Set the timer 0 for constant running speed in par. 13-20 *SL Controller Timer* [0]. Ex.: 2 sec.

Set Event 1 in par. 13-51 *SL Controller Event* [1] to *True* [1]
Set Event 2 in par. 13-51 *SL Controller Event* [2] to *On Reference* [4]
Set Event 3 in par. 13-51 *SL Controller Event* [3] to *Time Out 0* [30]
Set Event 4 in par. 13-51 *SL Controller Event* [1] to *False* [0]

Set Action 1 in par. 13-52 *SL Controller Action* [1] to *Select preset 0* [10]
Set Action 2 in par. 13-52 *SL Controller Action* [2] to *Start Timer 0* [29]
Set Action 3 in par. 13-52 *SL Controller Action* [3] to *Select preset 1* [11]
Set Action 4 in par. 13-52 *SL Controller Action* [4] to *No Action* [1]



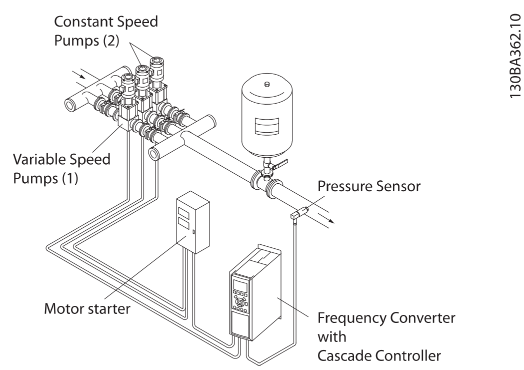
Set the Smart Logic Control in par. 13-00 *SL Controller Mode* to ON.

Start / stop command is applied on terminal 18. If stop signal is applied the frequency converter will ramp down and go into free mode.

6.1.7 BASIC Cascade Controller

The BASIC Cascade Controller is used for pump applications where a certain pressure ("head") or level needs to be maintained over a wide dynamic range. Running a large pump at variable speed over a wide range is not an ideal solution because of low pump efficiency at lower speed. In a practical way, the limit is 25% of the rated full load speed for the pump.

In the BASIC Cascade Controller the frequency converter controls a variable speed (lead) motor as the variable speed pump and can stage up to two additional constant speed pumps on and off. By varying the speed of the initial pump, variable speed control of the entire system is provided. This maintains constant pressure while eliminating pressure surges, resulting in reduced system stress and quieter operation in pumping systems.



Fixed Lead Pump

The motors must be of equal size. The BASIC Cascade Controller allows the frequency converter to control up to 3 equal size pumps using the drives two built-in relays. When the variable pump (lead) is connected directly to the drive, the other 2 pumps are controlled by the two built-in relays. When lead pump alternations is enabled, pumps are connected to the built-in relays and the drive is capable of operating 2 pumps.

Lead Pump Alternation

The motors must be of equal size. This function makes it possible to cycle the drive between the pumps in the system (maximum of 2 pumps). In this operation the run time between pumps is equalized reducing the required pump maintenance and increasing reliability and lifetime of the system. The alternation of the lead pump can take place at a command signal or at staging (adding another pump).

The command can be a manual alternation or an alternation event signal. If the alternation event is selected, the lead pump alternation takes place every time the event occurs. Selections include whenever an alternation timer expires, at a predefined time of day or when the lead pump goes into sleep mode. Staging is determined by the actual system load.

A separate parameter limits alternation only to take place if total capacity required is > 50%. Total pump capacity is determined as lead pump plus fixed speed pumps capacities.

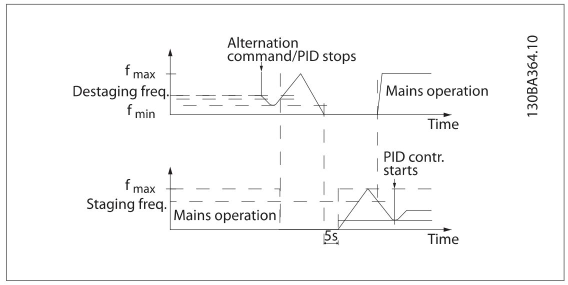
Bandwidth Management

In cascade control systems, to avoid frequent switching of fixed speed pumps, the desired system pressure is kept within a bandwidth rather than at a constant level. The Staging Bandwidth provides the required bandwidth for operation. When a large and quick change in system pressure occurs, the Override Bandwidth overrides the Staging Bandwidth to prevent immediate response to a short duration pressure change. An Override Bandwidth Timer can be programmed to prevent staging until the system pressure has stabilized and normal control established.

When the Cascade Controller is enabled and the drive issues a trip alarm, the system head is maintained by staging and destaging fixed speed pumps. To prevent frequent staging and destaging and minimize pressure fluxuations, a wider Fixed Speed Bandwidth is used instead of the Staging bandwidth.

6.1.8 Pump Staging with Lead Pump Alternation

With lead pump alternation enabled, a maximum of two pumps are controlled. At an alternation command, the PID stops, the lead pump ramps to minimum frequency (f_{min}) and after a delay, it ramps to maximum frequency (f_{max}). When the speed of the lead pump reaches the de-staging frequency, the fixed speed pump will be cut out (de-staged). The lead pump continues to ramp up and then ramps down to a stop and the two relays are cut out.



After a time delay, the relay for the fixed speed pump cuts in (staged) and this pump becomes the new lead pump. The new lead pump ramps up to maximum speed and then down to minimum speed. When ramping down and reaching the staging frequency, the old lead pump is now cut in (staged) on the mains as the new fixed speed pump.

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If the lead pump has been running at minimum frequency (f_{min}) for a programmed amount of time, with a fixed speed pump running, the lead pump contributes little to the system. When programmed value of the timer expires, the lead pump is removed avoiding water heating problems.

6.1.9 System Status and Operation

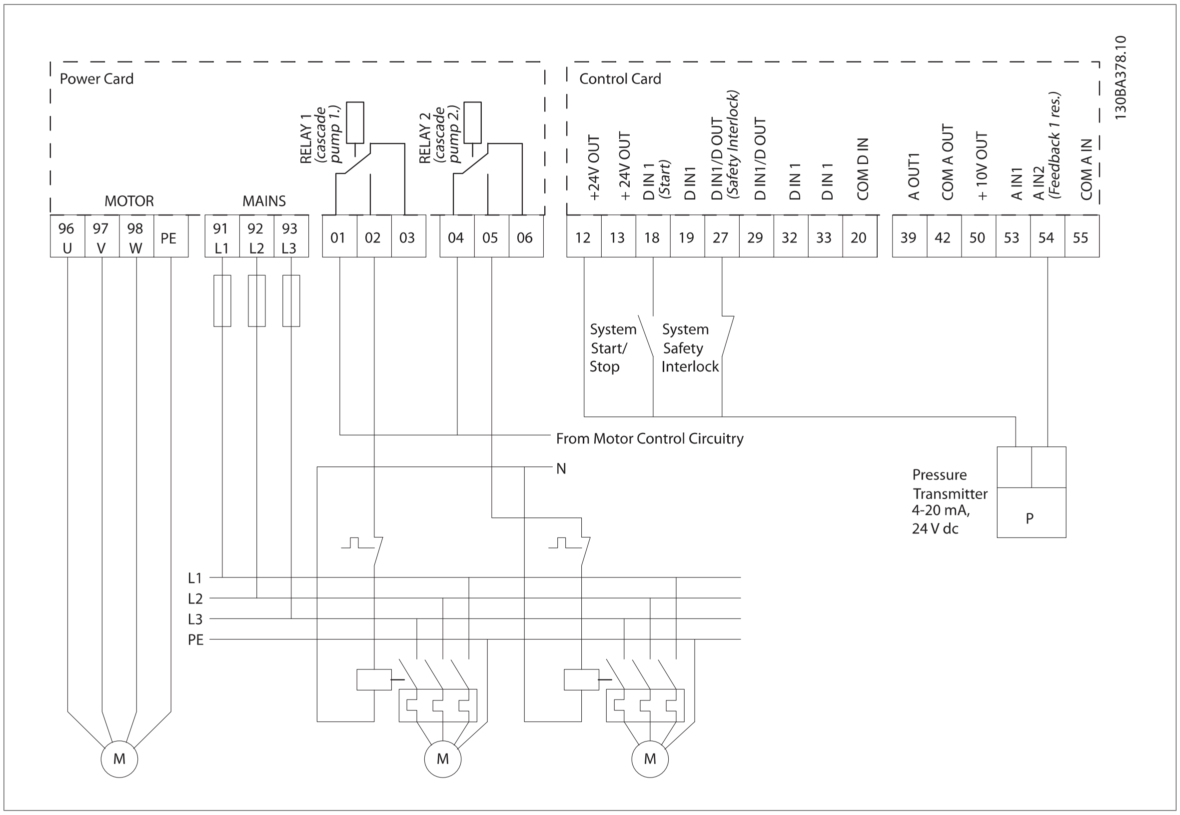
If the lead pump goes into Sleep Mode, the function is displayed on the Local Control Panel. It is possible to alternate the lead pump on a Sleep Mode condition.

When the cascade controller is enabled, the operation status for each pump and the cascade controller is displayed on the Local Control Panel. Information displayed includes:

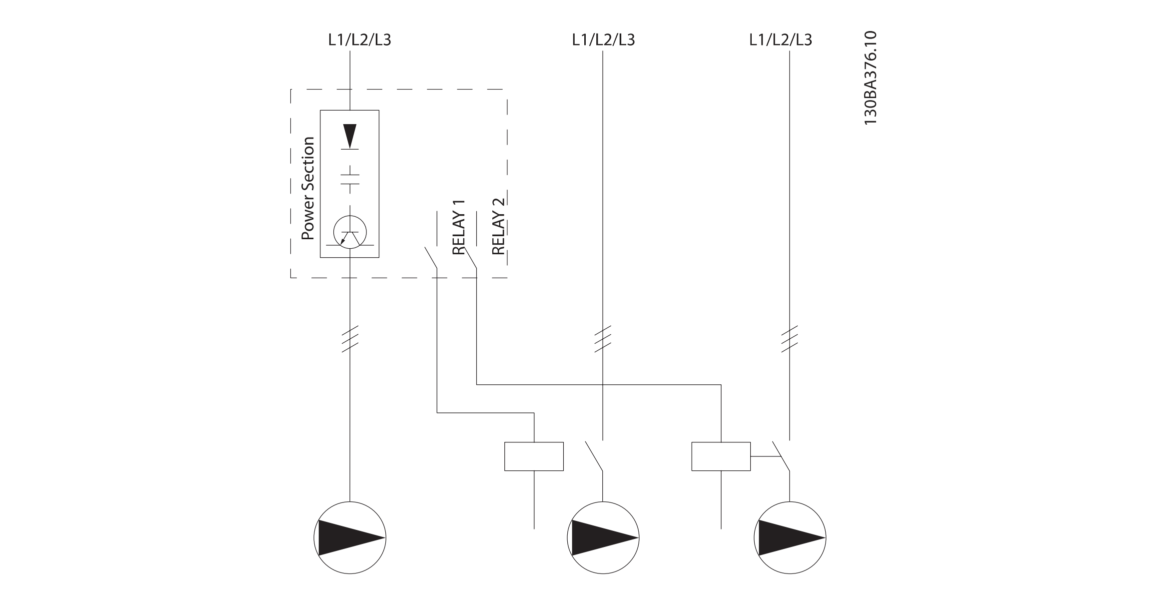
- Pumps Status, is a read out of the status for the relays assigned to each pump. The display shows pumps that are disabled, off, running on the frequency converter or running on the mains/motor starter.
- Cascade Status, is a read out of the status for the Cascade Controller. The display shows the Cascade Controller is disabled, all pumps are off, and emergency has stopped all pumps, all pumps are running, fixed speed pumps are being staged/destaged and lead pump alternation is occurring.
- Destage at No-Flow ensures that all fixed speed pumps are stopped individually until the no-flow status disappears.

6.1.10 Cascade Controller Wiring Diagram

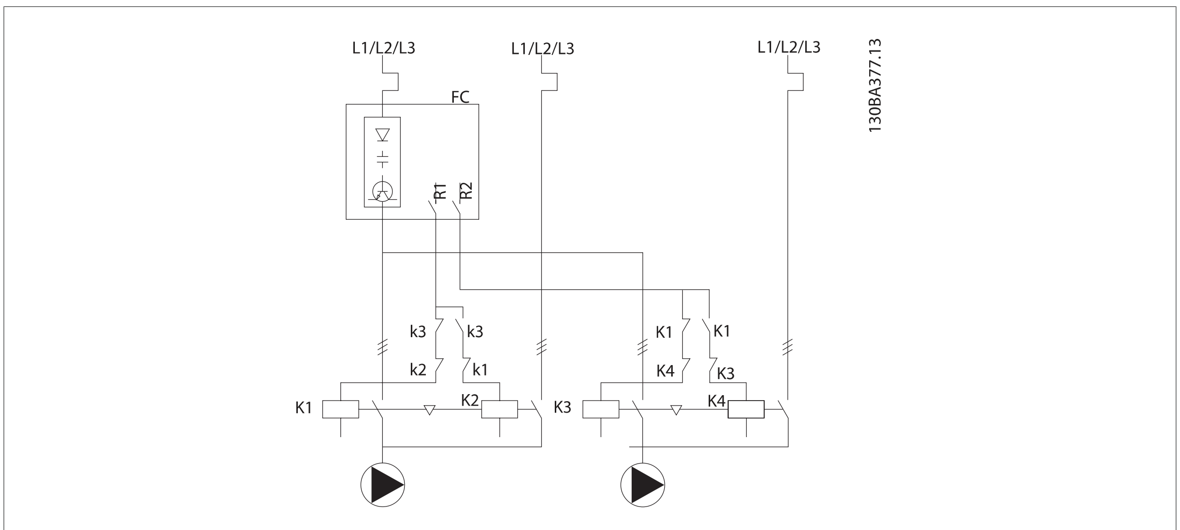
The wiring diagram shows an example with the built in BASIC cascade controller with one variable speed pump (lead) and two fixed speed pumps, a 4-20 mA transmitter and System Safety Interlock.



6.1.11 Fixed Variable Speed Pump Wiring Diagram



6.1.12 Lead Pump Alternation Wiring Diagram



Every pump must be connected to two contactors (K1/K2 and K3/K4) with a mechanical interlock. Thermal relays or other motor protection devices must be applied according to local regulation and/or individual demands.

- RELAY 1 (R1) and RELAY 2 (R2) are the built-in relays in the frequency converter.
- When all relays are de-energized, the first built in relay to be energized will cut in the contactor corresponding to the pump controlled by the relay. E.g. RELAY 1 cuts in contactor K1, which becomes the lead pump.
- K1 blocks for K2 via the mechanical interlock preventing mains to be connected to the output of the frequency converter (via K1).

- Auxiliary break contact on K1 prevents K3 to cut in.
- RELAY 2 controls contactor K4 for on/off control of the fixed speed pump.
- At alternation both relays de-energizes and now RELAY 2 will be energized as the first relay.

6.1.13 Start/Stop Conditions

Commands assigned to digital inputs. See *Digital Inputs*, par.5-1*.

	Variable speed pump (lead)	**Fixed speed pumps**
Start (SYSTEM START /STOP)	Ramps up (if stopped and there is a demand)	Staging (if stopped and there is a demand)
Lead Pump Start	Ramps up if SYSTEM START is active	Not affected
Coast (EMERGENCY STOP)	Coast to stop	Cut out (built in relays are de-energized)
Safety Interlock	Coast to stop	Cut out (built in relays are de-energized)

Function of buttons on Local Control Panel

	Variable speed pump (lead)	**Fixed speed pumps**
Hand On	Ramps up (if stopped by a normal stop command) or stays in operation if already running	Destaging (if running)
Off	Ramps down	Cut out
Auto On	Starts and stops according to commands via terminals or serial bus	Staging/Destaging

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7 RS-485 Installation and Set-up

7.1 RS-485 Installation and Set-up

7.1.1 Overview

RS-485 is a two-wire bus interface compatible with multi-drop network topology, i.e. nodes can be connected as a bus, or via drop cables from a common trunk line. A total of 32 nodes can be connected to one network segment.
Network segments are divided up by repeaters. Please note that each repeater functions as a node within the segment in which it is installed. Each node connected within a given network must have a unique node address, across all segments.
Terminate each segment at both ends, using either the termination switch (S801) of the frequency converters or a biased termination resistor network. Always use screened twisted pair (STP) cable for bus cabling, and always follow good common installation practice.
Low-impedance ground connection of the screen at every node is very important, including at high frequencies. This can be achieved by connecting a large surface of the screen to ground, for example by means of a cable clamp or a conductive cable gland. It may be necessary to apply potential-equalizing cables to maintain the same ground potential throughout the network, particularly in installations where there are long lengths of cable.
To prevent impedance mismatch, always use the same type of cable throughout the entire network. When connecting a motor to the frequency converter, always use screened motor cable.

Cable: Screened twisted pair (STP)
Impedance: 120 Ohm
Cable length: Max. 1200 m (including drop lines)
Max. 500 m station-to-station

7.1.2 Network Connection

Connect the frequency converter to the RS-485 network as follows (see also diagram):

1. Connect signal wires to terminal 68 (P+) and terminal 69 (N-) on the main control board of the frequency converter.
2. Connect the cable screen to the cable clamps.

NB!
Screened, twisted-pair cables are recommended in order to reduce noise between conductors.

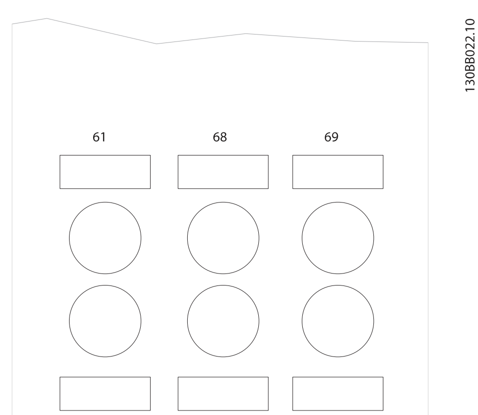

Illustration 7.1: Network Terminal Connection

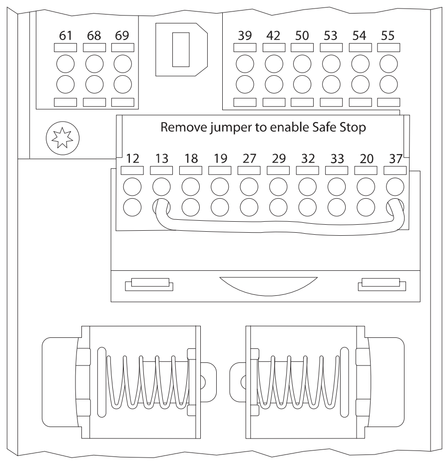

Illustration 7.2: Control card terminals

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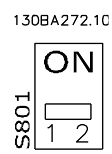
7.1.3 VLT Automation VT Drive Hardware Setup

Use the terminator dip switch on the main control board of the frequency converter to terminate the RS-485 bus.



Terminator Switch Factory Setting

NB!
The factory setting for the dip switch is OFF.

7.1.4 VLT Automation VT Drive Parameter Settings for Modbus Communication

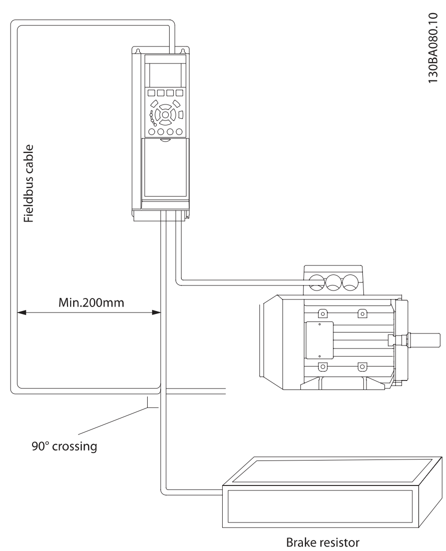
The following parameters apply to the RS-485 interface (FC-port):

Parameter Number	Parameter name	Function
8-30	Protocol	Select the application protocol to run on the RS-485 interface
8-31	Address	Set the node address. Note: The address range depends on the protocol selected in par. 8-30
8-32	Baud Rate	Set the baud rate. Note: The default baud rate depends on the protocol selected in par. 8-30
8-33	PC port parity/Stop bits	Set the parity and number of stop bits. Note: The default selection depends on the protocol selected in par. 8-30
8-35	Min. response delay	Specify a minimum delay time between receiving a request and transmitting a response. This can be used for overcoming modem turnaround delays.
8-36	Max. response delay	Specify a maximum delay time between transmitting a request and receiving a response.
8-37	Max. inter-char delay	Specify a maximum delay time between two received bytes to ensure timeout if transmission is interrupted.

7.1.5 EMC Precautions

The following EMC precautions are recommended in order to achieve interference-free operation of the RS-485 network.

NB!
Relevant national and local regulations, for example regarding protective earth connection, must be observed. The RS-485 communication cable must be kept away from motor and brake resistor cables to avoid coupling of high frequency noise from one cable to another. Normally a distance of 200 mm (8 inches) is sufficient, but keeping the greatest possible distance between the cables is generally recommended, especially where cables run in parallel over long distances. When crossing is unavoidable, the RS-485 cable must cross motor and brake resistor cables at an angle of 90 degrees.



7.2 FC Protocol Overview

The FC protocol, also referred to as FC bus or Standard bus, is the Danfoss standard fieldbus. It defines an access technique according to the master-slave principle for communications via a serial bus.
One master and a maximum of 126 slaves can be connected to the bus. The individual slaves are selected by the master via an address character in the telegram. A slave itself can never transmit without first being requested to do so, and direct message transfer between the individual slaves is not possible. Communications occur in the half-duplex mode.
The master function cannot be transferred to another node (single-master system).

The physical layer is RS-485, thus utilizing the RS-485 port built into the frequency converter. The FC protocol supports different telegram formats; a short format of 8 bytes for process data, and a long format of 16 bytes that also includes a parameter channel. A third telegram format is used for texts.

7.2.1 VLT Automation VT Drive with Modbus RTU

The FC protocol provides access to the Control Word and Bus Reference of the frequency converter.

The Control Word allows the Modbus master to control several important functions of the frequency converter:

- Start
- Stop of the frequency converter in various ways:
  Coast stop
  Quick stop
  DC Brake stop
  Normal (ramp) stop
- Reset after a fault trip
- Run at a variety of preset speeds
- Run in reverse
- Change of the active set-up
- Control of the two relays built into the frequency converter

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The Bus Reference is commonly used for speed control. It is also possible to access the parameters, read their values, and where possible, write values to them. This permits a range of control options, including controlling the setpoint of the frequency converter when its internal PID controller is used.

7.3 Network Configuration

7.3.1 VLT Automation VT Drive Frequency Converter Set-up

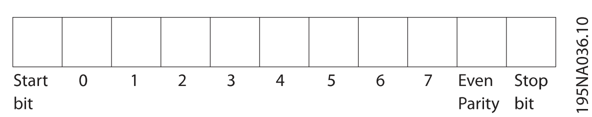
Set the following parameters to enable the FC protocol for the VLT Automation VT Drive.

Parameter Number	Parameter name	Setting
8-30	Protocol	FC
8-31	Address	1 - 126
8-32	Baud Rate	2400 - 115200
8-33	Parity/Stop bits	Even parity, 1 stop bit (default)

7.4 FC Protocol Message Framing Structure

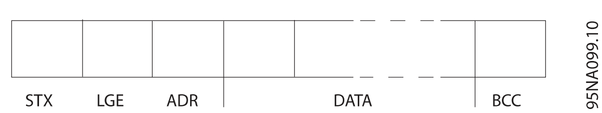
7.4.1 Content of a Character (byte)

Each character transferred begins with a start bit. Then 8 data bits are transferred, corresponding to a byte. Each character is secured via a parity bit, which is set at "1" when it reaches parity (i.e. when there is an equal number of 1's in the 8 data bits and the parity bit in total). A character is completed by a stop bit, thus consisting of 11 bits in all.



7.4.2 Telegram Structure

Each telegram begins with a start character (STX)=02 Hex, followed by a byte denoting the telegram length (LGE) and a byte denoting the frequency converter address (ADR). A number of data bytes (variable, depending on the type of telegram) follows. The telegram is completed by a data control byte (BCC).



7.4.3 Telegram Length (LGE)

The telegram length is the number of data bytes plus the address byte ADR and the data control byte BCC.

The length of telegrams with 4 data bytes is	LGE = 4 + 1 + 1 = 6 bytes
The length of telegrams with 12 data bytes is	LGE = 12 + 1 + 1 = 14 bytes
The length of telegrams containing texts is	10[1)]+n bytes

[1)] The 10 represents the fixed characters, while the "n'" is variable (depending on the length of the text).

7.4.4 Frequency Converter Address (ADR)

Two different address formats are used.
The address range of the frequency converter is either 1-31 or 1-126.

1. Address format 1-31:
Bit 7 = 0 (address format 1-31 active)
Bit 6 is not used
Bit 5 = 1: Broadcast, address bits (0-4) are not used
Bit 5 = 0: No Broadcast
Bit 0-4 = Frequency converter address 1-31

2. Address format 1-126:
Bit 7 = 1 (address format 1-126 active)
Bit 0-6 = Frequency converter address 1-126
Bit 0-6 = 0 Broadcast

The slave returns the address byte unchanged to the master in the response telegram.

7.4.5 Data Control Byte (BCC)

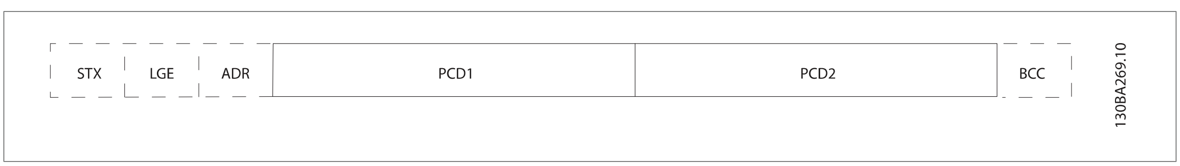
The checksum is calculated as an XOR-function. Before the first byte in the telegram is received, the Calculated Checksum is 0.

7.4.6 The Data Field

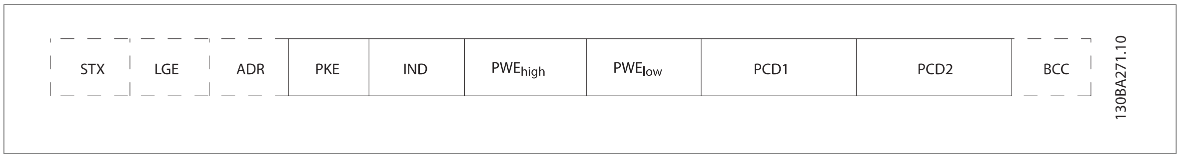
The structure of data blocks depends on the type of telegram. There are three telegram types, and the type applies for both control telegrams (master=>slave) and response telegrams (slave=>master).

The three types of telegram are:

Process block (PCD):
The PCD is made up of a data block of four bytes (2 words) and contains:
- Control word and reference value (from master to slave)
- Status word and present output frequency (from slave to master).

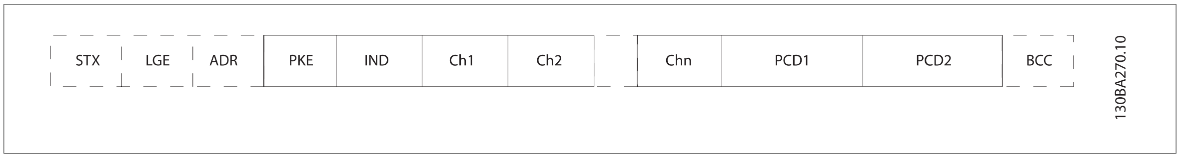


Parameter block:
The parameter block is used to transfer parameters between master and slave. The data block is made up of 12 bytes (6 words) and also contains the process block.


STX
LGE
ADR
PKE
IND
PWEhigh
PWElow
PCD1
PCD2
BCC
130BA271.10

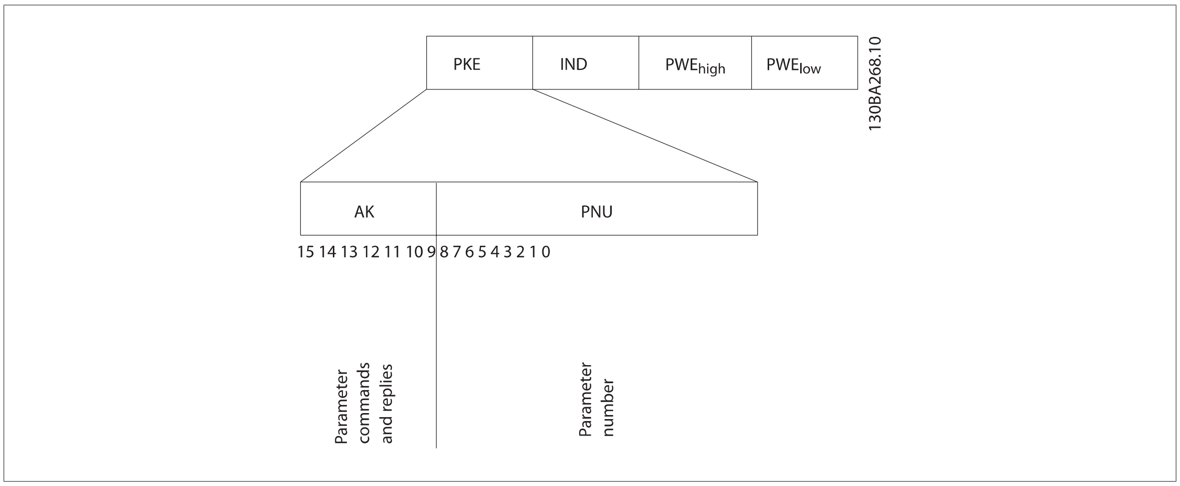
Text block:

The text block is used to read or write texts via the data block.



7.4.7 The PKE Field

The PKE field contains two sub-fields: Parameter command and response AK, and Parameter number PNU:



Bits no. 12-15 transfer parameter commands from master to slave and return processed slave responses to the master.

Parameter commands master ⇒ slave				
Bit no.				Parameter command
15	14	13	12	
0	0	0	0	No command
0	0	0	1	Read parameter value
0	0	1	0	Write parameter value in RAM (word)
0	0	1	1	Write parameter value in RAM (double word)
1	1	0	1	Write parameter value in RAM and EEprom (double word)
1	1	1	0	Write parameter value in RAM and EEprom (word)
1	1	1	1	Read/write text

Response slave ⇒master				
Bit no.				**Response**
15	14	13	12	
0	0	0	0	No response
0	0	0	1	Parameter value transferred (word)
0	0	1	0	Parameter value transferred (double word)
0	1	1	1	Command cannot be performed
1	1	1	1	text transferred

If the command cannot be performed, the slave sends this response:
0111 Command cannot be performed
- and issues the following fault report in the parameter value (PWE):

PWE low (Hex)	Fault Report
0	The parameter number used does not exit
1	There is no write access to the defined parameter
2	Data value exceeds the parameter's limits
3	The sub index used does not exit
4	The parameter is not the array type
5	The data type does not match the defined parameter
11	Data change in the defined parameter is not possible in the frequency converter's present mode. Certain parameters can only be changed when the motor is turned off
82	There is no bus access to the defined parameter
83	Data change is not possible because factory setup is selected

7.4.8 Parameter Number (PNU)

Bits no. 0-11 transfer parameter numbers. The function of the relevant parameter is defined in the parameter description in the chapter *How to Programme*.

7.4.9 Index (IND)

The index is used together with the parameter number to read/write-access parameters with an index, e.g. par. 15-30 *Alarm Log: Error Code*. The index consists of 2 bytes, a low byte and a high byte.

NB!
Only the low byte is used as an index.

7.4.10 Parameter Value (PWE)

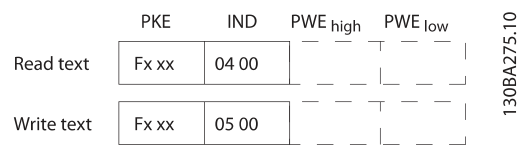
The parameter value block consists of 2 words (4 bytes), and the value depends on the defined command (AK). The master prompts for a parameter value when the PWE block contains no value. To change a parameter value (write), write the new value in the PWE block and send from the master to the slave.

When a slave responds to a parameter request (read command), the present parameter value in the PWE block is transferred and returned to the master. If a parameter contains not a numerical value but several data options, e.g. par. 0-01 *Language* where [0] corresponds to English, and [4] corresponds to Danish, select the data value by entering the value in the PWE block. See Example - Selecting a data value. Serial communication is only capable of reading parameters containing data type 9 (text string).

par. 15-40 *FC Type* to par. 15-53 *Power Card Serial Number* contain data type 9.
For example, read the unit size and mains voltage range in par. 15-40 *FC Type*. When a text string is transferred (read), the length of the telegram is variable, and the texts are of different lengths. The telegram length is defined in the second byte of the telegram, LGE. When using text transfer the index character indicates whether it is a read or a write command.

To read a text via the PWE block, set the parameter command (AK) to 'F' Hex. The index character high-byte must be "4".

Some parameters contain text that can be written to via the serial bus. To write a text via the PWE block, set the parameter command (AK) to 'F' Hex. The index characters high-byte must be "5".



7.4.11 Data Types Supported by VLT Automation VT Drive

Data types	**Description**
3	Integer 16
4	Integer 32
5	Unsigned 8
6	Unsigned 16
7	Unsigned 32
9	Text string
10	Byte string
13	Time difference
33	Reserved
35	Bit sequence

Unsigned means that there is no operational sign in the telegram.

7.4.12 Conversion

The various attributes of each parameter are displayed in the section Factory Settings. Parameter values are transferred as whole numbers only. Conversion factors are therefore used to transfer decimals.

par. 4-12 *Motor Speed Low Limit [Hz]* has a conversion factor of 0.1.
To preset the minimum frequency to 10 Hz, transfer the value 100. A conversion factor of 0.1 means that the value transferred is multiplied by 0.1. The value 100 is thus perceived as 10.0.

Conversion table

Conversion index	**Conversion factor**
74	0.1
2	100
1	10
0	1
-1	0.1
-2	0.01
-3	0.001
-4	0.0001
-5	0.00001

7.4.13 Process Words (PCD)

The block of process words is divided into two blocks of 16 bits, which always occur in the defined sequence.

	PCD 1	PCD 2
Control telegram (master⇒slave Control word)		Reference-value
Control telegram (slave ⇒master) Status word		Present outp. frequency

7

7.5 Examples

7.5.1 Writing a Parameter Value

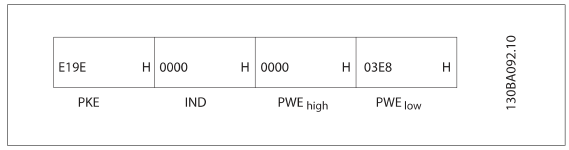
Change par. 4-14 *Motor Speed High Limit [Hz]* to 100 Hz.
Write the data in EEPROM.

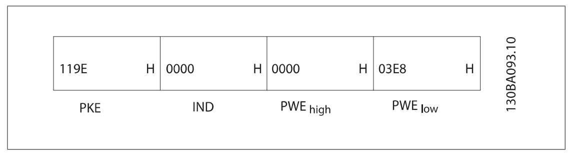
PKE = E19E Hex - Write single word in par. 4-14 *Motor Speed High Limit [Hz]*
IND = 0000 Hex
PWEHIGH = 0000 Hex
PWELOW = 03E8 Hex - Data value 1000, corresponding to 100 Hz, see Conversion.

Note: par. 4-14 *Motor Speed High Limit [Hz]* is a single word, and the parameter command for write in EEPROM is "E". Parameter number 4-14 is 19E in hexadecimal.

The response from the slave to the master will be:

The telegram will look like this:

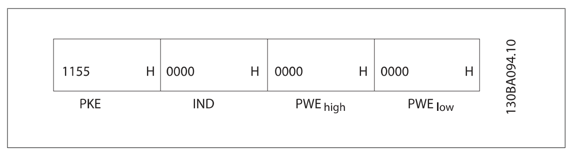




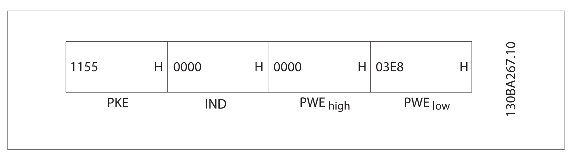
7.5.2 Reading a Parameter Value

Read the value in par. 3-41 *Ramp 1 Ramp Up Time*

PKE = 1155 Hex - Read parameter value in par. 3-41 *Ramp 1 Ramp Up Time*
IND = 0000 Hex
PWEHIGH = 0000 Hex
PWELOW = 0000 Hex



If the value in par. 3-41 *Ramp 1 Ramp Up Time* is 10 s, the response from the slave to the master will be:



NB!
3E8 Hex corresponds to 1000 decimal. The conversion index for par. 3-41 *Ramp 1 Ramp Up Time* is -2, i.e. 0.01.
Par. 3-41 is of the type *Unsigned 32*.

7.6 Modbus RTU Overview

7.6.1 Assumptions

This instruction manual assumes that the installed controller supports the interfaces in this document and that all the requirements stipulated in the controller, as well as the frequency converter, are strictly observed, along with all limitations therein.

7.6.2 What the User Should Already Know

The Modbus RTU (Remote Terminal Unit) is designed to communicate with any controller that supports the interfaces defined in this document. It is assumed that the user has full knowledge of the capabilities and limitations of the controller.

7.6.3 Modbus RTU Overview

Regardless of the type of physical communication networks, the Modbus RTU Overview describes the process a controller uses to request access to another device. This includes i.a. how it will respond to requests from another device, and how errors will be detected and reported. It also establishes a common format for the layout and contents of message fields.
During communications over a Modbus RTU network, the protocol determines how each controller will learn its device address, recognise a message addressed to it, determine the kind of action to be taken, and extract any data or other information contained in the message. If a reply is required, the controller will construct the reply message and send it.
Controllers communicate using a master-slave technique in which only one device (the master) can initiate transactions (called queries). The other devices (slaves) respond by supplying the requested data to the master, or by taking the action requested in the query.
The master can address individual slaves, or can initiate a broadcast message to all slaves. Slaves return a message (called a response) to queries that are addressed to them individually. No responses are returned to broadcast queries from the master. The Modbus RTU protocol establishes the format for the master's query by placing into it the device (or broadcast) address, a function code defining the requested action, any data to be sent, and an error-checking field. The slave's response message is also constructed using Modbus protocol. It contains fields confirming the action taken, any data to be returned, and an error-checking field. If an error occurs in receipt of the message, or if the slave is unable to perform the requested action, the slave will construct an error message and send it in response, or a time-out will occur.

7.7 Network Configuration

7.7.1 VLT Automation VT Drive with Modbus RTU

To enable Modbus RTU on the VLT Automation VT Drive, set the following parameters:

Parameter Number	Parameter name	Setting
8-30	Protocol	Modbus RTU
8-31	Address	1 - 247
8-32	Baud Rate	2400 - 115200
8-33	Parity/Stop bits	Even parity, 1 stop bit (default)

7.8 Modbus RTU Message Framing Structure

7.8.1 Frequency Converter with Modbus RTU

The controllers are set up to communicate on the Modbus network using RTU (Remote Terminal Unit) mode, with each byte in a message containing two 4-bit hexadecimal characters. The format for each byte is shown below.

Start bit	Data byte								Stop/ parity	Stop

Coding System	8-bit binary, hexadecimal 0-9, A-F. Two hexadecimal characters contained in each 8-bit field of the message
Bits Per Byte	1 start bit 8 data bits, least significant bit sent first 1 bit for even/odd parity; no bit for no parity 1 stop bit if parity is used; 2 bits if no parity
Error Check Field	Cyclical Redundancy Check (CRC)

7.8.2 Modbus RTU Message Structure

The transmitting device places a Modbus RTU message into a frame with a known beginning and ending point. This allows receiving devices to begin at the start of the message, read the address portion, determine which device is addressed (or all devices, if the message is broadcast), and to recognise when the message is completed. Partial messages are detected and errors set as a result. Characters for transmission must be in hexadecimal 00 to FF format in each field. The frequency converter continuously monitors the network bus, also during 'silent' intervals. When the first field (the address field) is received, each frequency converter or device decodes it to determine which device is being addressed. Modbus RTU messages addressed to zero are broadcast messages. No response is permitted for broadcast messages. A typical message frame is shown below.

Typical Modbus RTU Message Structure

Start	Address	Function	Data	CRC check	End
T1-T2-T3-T4	8 bits	8 bits	N x 8 bits	16 bits	T1-T2-T3-T4

7.8.3 Start / Stop Field

Messages start with a silent period of at least 3.5 character intervals. This is implemented as a multiple of character intervals at the selected network baud rate (shown as Start T1-T2-T3-T4). The first field to be transmitted is the device address. Following the last transmitted character, a similar period of at least 3.5 character intervals marks the end of the message. A new message can begin after this period. The entire message frame must be transmitted as a continuous stream. If a silent period of more than 1.5 character intervals occurs before completion of the frame, the receiving device flushes the incomplete message and assumes that the next byte will be the address field of a new message. Similarly, if a new message begins prior to 3.5 character intervals after a previous message, the receiving device will consider it a continuation of the previous message. This will cause a time-out (no response from the slave), since the value in the final CRC field will not be valid for the combined messages.

7.8.4 Address Field

The address field of a message frame contains 8 bits. Valid slave device addresses are in the range of 0 – 247 decimal. The individual slave devices are assigned addresses in the range of 1 – 247. (0 is reserved for broadcast mode, which all slaves recognize.) A master addresses a slave by placing the slave address in the address field of the message. When the slave sends its response, it places its own address in this address field to let the master know which slave is responding.

7.8.5 Function Field

The function field of a message frame contains 8 bits. Valid codes are in the range of 1-FF. Function fields are used to send messages between master and slave. When a message is sent from a master to a slave device, the function code field tells the slave what kind of action to perform. When the slave responds to the master, it uses the function code field to indicate either a normal (error-free) response, or that some kind of error occurred (called an exception response). For a normal response, the slave simply echoes the original function code. For an exception response, the slave returns a code that is equivalent to the original function code with its most significant bit set to logic 1. In addition, the slave places a unique code into the data field of the response message. This tells the master what kind of error occurred, or the reason for the exception. Please also refer to the sections *Function Codes Supported by Modbus RTU* and *Exception Codes.*

7.8.6 Data Field

The data field is constructed using sets of two hexadecimal digits, in the range of 00 to FF hexadecimal. These are made up of one RTU character. The data field of messages sent from a master to slave device contains additional information which the slave must use to take the action defined by the function code. This can include items such as coil or register addresses, the quantity of items to be handled, and the count of actual data bytes in the field.

7.8.7 CRC Check Field

Messages include an error-checking field, operating on the basis of a Cyclical Redundancy Check (CRC) method. The CRC field checks the contents of the entire message. It is applied regardless of any parity check method used for the individual characters of the message. The CRC value is calculated by the transmitting device, which appends the CRC as the last field in the message. The receiving device recalculates a CRC during receipt of the message and compares the calculated value to the actual value received in the CRC field. If the two values are unequal, a bus time-out results. The error-checking field contains a 16-bit binary value implemented as two 8-bit bytes. When this is done, the low-order byte of the field is appended first, followed by the high-order byte. The CRC high-order byte is the last byte sent in the message.

7.8.8 Coil Register Addressing

In Modbus, all data are organized in coils and holding registers. Coils hold a single bit, whereas holding registers hold a 2-byte word (i.e. 16 bits). All data addresses in Modbus messages are referenced to zero. The first occurrence of a data item is addressed as item number zero. For example: The coil known as ‘coil 1’ in a programmable controller is addressed as coil 0000 in the data address field of a Modbus message. Coil 127 decimal is addressed as coil 007EHEX (126 decimal).
Holding register 40001 is addressed as register 0000 in the data address field of the message. The function code field already specifies a ‘holding register’ operation. Therefore, the ‘4XXXX’ reference is implicit. Holding register 40108 is addressed as register 006BHEX (107 decimal).

Coil Number	Description		Signal Direction
1-16	Frequency converter control word (see table below)		Master to slave
17-32	Frequency converter speed or set-point reference Range 0x0 – 0xFFFF (-200% ... ~200%)		Master to slave
33-48	Frequency converter status word (see table below)		Slave to master
49-64	Open loop mode: Frequency converter output frequency Closed loop mode: Frequency converter feedback signal		Slave to master
65	Parameter write control (master to slave)		Master to slave
	0 =	Parameter changes are written to the RAM of the frequency converter	
	1 =	Parameter changes are written to the RAM and EEPROM of the frequency converter.	
66-65536	Reserved		

Coil	0	1
01	Preset reference LSB	
02	Preset reference MSB	
03	DC brake	No DC brake
04	Coast stop	No coast stop
05	Quick stop	No quick stop
06	Freeze freq.	No freeze freq.
07	Ramp stop	Start
08	No reset	Reset
09	No jog	Jog
10	Ramp 1	Ramp 2
11	Data not valid	Data valid
12	Relay 1 off	Relay 1 on
13	Relay 2 off	Relay 2 on
14	Set up LSB	
15	Set up MSB	
16	No reversing	Reversing

Frequency converter control word (FC profile)

Coil	0	1
33	Control not ready	Control ready
34	Frequency converter not ready	Frequency converter ready
35	Coasting stop	Safety closed
36	No alarm	Alarm
37	Not used	Not used
38	Not used	Not used
39	Not used	Not used
40	No warning	Warning
41	Not at reference	At reference
42	Hand mode	Auto mode
43	Out of freq. range	In frequency range
44	Stopped	Running
45	Not used	Not used
46	No voltage warning	Voltage warning
47	Not in current limit	Current limit
48	No thermal warning	Thermal warning

Frequency converter status word (FC profile)

Holding registers

Register Number	Description
00001-00006	Reserved
00007	Last error code from an FC data object interface
00008	Reserved
00009	Parameter index*
00010-00990	000 parameter group (parameters 001 through 099)
01000-01990	100 parameter group (parameters 100 through 199)
02000-02990	200 parameter group (parameters 200 through 299)
03000-03990	300 parameter group (parameters 300 through 399)
04000-04990	400 parameter group (parameters 400 through 499)
...	...
49000-49990	4900 parameter group (parameters 4900 through 4999)
50000	Input data: Frequency converter control word register (CTW).
50010	Input data: Bus reference register (REF).
...	...
50200	Output data: Frequency converter status word register (STW).
50210	Output data: Frequency converter main actual value register (MAV).

* Used to specify the index number to be used when accessing an indexed parameter.

7.8.9 How to Control VLT Automation VT Drive

This section describes codes which can be used in the function and data fields of a Modbus RTU message. For a complete description of all the message fields please refer to the section *Modbus RTU Message Framing Structure.*

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7.8.10 Function Codes Supported by Modbus RTU

Modbus RTU supports use of the following function codes in the function field of a message:

Function	Function Code
Read coils	1 hex
Read holding registers	3 hex
Write single coil	5 hex
Write single register	6 hex
Write multiple coils	F hex
Write multiple registers	10 hex
Get comm. event counter	B hex
Report slave ID	11 hex

Function	Function Code	Sub-function code	Sub-function
Diagnostics	8	1	Restart communication
		2	Return diagnostic register
		10	Clear counters and diagnostic register
		11	Return bus message count
		12	Return bus communication error count
		13	Return bus exception error count
		14	Return slave message count

7.8.11 Database Error Codes

In the event of an error, the following error codes may appear in the data field of a response message. For a full explanation of the structure of an exception (i.e. error) response, please refer to the section *Modbus RTU Message Framing Structure, Function Field.*

Error Code in data field (decimal)	Database Error Code description
00	The parameter number does not exit
01	There is no write access to the parameter
02	The data value exceeds the parameter limits
03	The sub-index in use does not exit
04	The parameter is not of the array type
05	The data type does not match the parameter called
06	Only reset
07	Not changeable
11	No write access
17	Data change in the parameter called is not possible in the present mode
18	Other error
64	Invalid data address
65	Invalid message length
66	Invalid data length or value
67	Invalid function code
130	There is no bus access to the parameter called
131	Data change is not possible because factory set-up is selected

7.9 How to Access Parameters

7.9.1 Parameter Handling

The PNU (Parameter Number) is translated from the register address contained in the Modbus read or write message. The parameter number is translated to Modbus as (10 x parameter number) DECIMAL.

7.9.2 Storage of Data

The Coil 65 decimal determines whether data written to the frequency converter are stored in EEPROM and RAM (coil 65 = 1) or only in RAM (coil 65 = 0).

7.9.3 IND

The array index is set in Holding Register 9 and used when accessing array parameters.

7.9.4 Text Blocks

Parameters stored as text strings are accessed in the same way as the other parameters. The maximum text block size is 20 characters. If a read request for a parameter is for more characters than the parameter stores, the response is truncated. If the read request for a parameter is for fewer characters than the parameter stores, the response is space filled.

7.9.5 Conversion Factor

The different attributes for each parameter can be seen in the section on factory settings. Since a parameter value can only be transferred as a whole number, a conversion factor must be used to transfer decimals. Please refer to the *Parameters section*.

7.9.6 Parameter Values

Standard Data Types
Standard data types are int16, int32, uint8, uint16 and uint32. They are stored as 4x registers (40001 – 4FFFF). The parameters are read using function 03HEX "Read Holding Registers." Parameters are written using the function 6HEX "Preset Single Register" for 1 register (16 bits), and the function 10HEX "Preset Multiple Registers" for 2 registers (32 bits). Readable sizes range from 1 register (16 bits) up to 10 registers (20 characters).

Non standard Data Types
Non standard data types are text strings and are stored as 4x registers (40001 – 4FFFF). The parameters are read using function 03HEX "Read Holding Registers" and written using function 10HEX "Preset Multiple Registers." Readable sizes range from 1 register (2 characters) up to 10 registers (20 characters).

7.10 Examples

The following examples illustrate various Modbus RTU commands. If an error occurs, please refer to the Exception Codes section.

7.10.1 Read Coil Status (01 HEX)

Description

This function reads the ON/OFF status of discrete outputs (coils) in the frequency converter. Broadcast is never supported for reads.

Query

The query message specifies the starting coil and quantity of coils to be read. Coil addresses start at zero, i.e. coil 33 is addressed as 32.

Example of a request to read coils 33-48 (Status Word) from slave device 01:

Field Name	Example (HEX)
Slave Address	01 (frequency converter address)
Function	01 (read coils)
Starting Address HI	00
Starting Address LO	20 (32 decimals) Coil 33
No. of Points HI	00
No. of Points LO	10 (16 decimals)
Error Check (CRC)	-

Response

The coil status in the response message is packed as one coil per bit of the data field. Status is indicated as: 1 = ON; 0 = OFF. The LSB of the first data byte contains the coil addressed in the query. The other coils follow toward the high order end of this byte, and from 'low order to high order' in subsequent bytes.
If the returned coil quantity is not a multiple of eight, the remaining bits in the final data byte will be padded with zeros (toward the high order end of the byte). The Byte Count field specifies the number of complete bytes of data.

Field Name	Example (HEX)
Slave Address	01 (frequency converter address)
Function	01 (read coils)
Byte Count	02 (2 bytes of data)
Data (Coils 40-33)	07
Data (Coils 48-41)	06 (STW=0607hex)
Error Check (CRC)	-

7.10.2 Force/Write Single Coil (05 HEX)

Description

This function forces a writes a coil to either ON or OFF. When broadcast the function forces the same coil references in all attached slaves.

Query

The query message specifies the coil 65 (parameter write control) to be forced. Coil addresses start at zero, i.e. coil 65 is addressed as 64. Force Data = 00 00HEX (OFF) or FF 00HEX (ON).

Field Name	Example (HEX)
Slave Address	01 (frequency converter address)
Function	05 (write single coil)
Coil Address HI	00
Coil Address LO	40 (64 decimal) Coil 65
Force Data HI	FF
Force Data LO	00 (FF 00 = ON)
Error Check (CRC)	-

Response

The normal response is an echo of the query, returned after the coil state has been forced.

Field Name	Example (HEX)
Slave Address	01
Function	05
Force Data HI	FF
Force Data LO	00
Quantity of Coils HI	00
Quantity of Coils LO	01
Error Check (CRC)	-

7.10.3 Force/Write Multiple Coils (0F HEX)

This function forces each coil in a sequence of coils to either ON or OFF. When broadcast the function forces the same coil references in all attached slaves. .

The query message specifies the coils 17 to 32 (speed set-point) to be forced.

Field Name	Example (HEX)
Slave Address	01 (frequency converter address)
Function	0F (write multiple coils)
Coil Address HI	00
Coil Address LO	10 (coil address 17)
Quantity of Coils HI	00
Quantity of Coils LO	10 (16 coils)
Byte Count	02
Force Data HI (Coils 8-1)	20
Force Data LO (Coils 10-9)	00 (ref. = 2000hex)
Error Check (CRC)	-

Response

The normal response returns the slave address, function code, starting address, and quantity of coiles forced.

Field Name	Example (HEX)
Slave Address	01 (frequency converter address)
Function	0F (write multiple coils)
Coil Address HI	00
Coil Address LO	10 (coil address 17)
Quantity of Coils HI	00
Quantity of Coils LO	10 (16 coils)
Error Check (CRC)	-

7.10.4 Read Holding Registers (03 HEX)

Description

This function reads the contents of holding registers in the slave.

Query

The query message specifies the starting register and quantity of registers to be read. Register addresses start at zero, i.e. registers 1-4 are addressed as 0-3.

Example: Read par. 3-03, *Maximum Reference*, register 03030.

Field Name	Example (HEX)
Slave Address	01
Function	03 (read holding registers)
Starting Address HI	0B (Register address 3029)
Starting Address LO	05 (Register address 3029)
No. of Points HI	00
No. of Points LO	02 - (Par. 3-03 is 32 bits long, i.e. 2 registers)
Error Check (CRC)	-

Response

The register data in the response message are packed as two bytes per register, with the binary contents right justified within each byte. For each register, the first byte contains the high order bits and the second contains the low order bits.

Field Name	Example (HEX)
Slave Address	01
Function	03
Byte Count	04
Data HI (Register 3030)	00
Data LO (Register 3030)	16
Data HI (Register 3031)	E3
Data LO (Register 3031)	60
Error Check (CRC)	-

7.10.5 Preset Single Register (06 HEX)

Description

This function presets a value into a single holding register.

Query

The query message specifies the register reference to be preset. Register addresses start at zero, i.e. register 1 is addressed as 0.

Example: Write to par. 1-00, register 1000.

Field Name	Example (HEX)
Slave Address	01
Function	06
Register Address HI	03 (Register address 999)
Register Address LO	E7 (Register address 999)
Preset Data HI	00
Preset Data LO	01
Error Check (CRC)	-

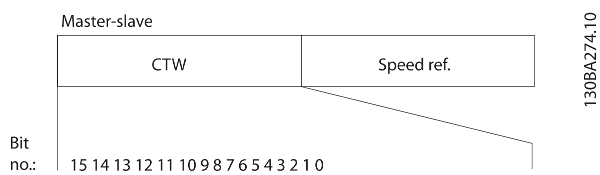
Response

Response The normal response is an echo of the query, returned after the register contents have been passed.

Field Name	Example (HEX)
Slave Address	01
Function	06
Register Address HI	03
Register Address LO	E7
Preset Data HI	00
Preset Data LO	01
Error Check (CRC)	-

7.11 Danfoss FC Control Profile

7.11.1 Control Word According to FC Profile(par. 8-10 *Control Profile* = FC profile)



Bit	Bit value = 0	Bit value = 1
00	Reference value	external selection lsb
01	Reference value	external selection msb
02	DC brake	Ramp
03	Coasting	No coasting
04	Quick stop	Ramp
05	Hold output frequency	use ramp
06	Ramp stop	Start
07	No function	Reset
08	No function	Jog
09	Ramp 1	Ramp 2
10	Data invalid	Data valid
11	No function	Relay 01 active
12	No function	Relay 02 active
13	Parameter set-up	selection lsb
14	Parameter set-up	selection msb
15	No function	Reverse

Explanation of the Control Bits

Bits 00/01

Bits 00 and 01 are used to choose between the four reference values, which are pre-programmed in par. 3-10 *Preset Reference* according to the following table:

Programmed ref. value	Par.	Bit 01	Bit 00
1	par. 3-10 *Preset Reference* [0]	0	0
2	par. 3-10 *Preset Reference* [1]	0	1
3	par. 3-10 *Preset Reference* [2]	1	0
4	par. 3-10 *Preset Reference* [3]	1	1

NB!

Make a selection in par. 8-56 *Preset Reference Select* to define how Bit 00/01 gates with the corresponding function on the digital inputs.

Bit 02, DC brake:

Bit 02 = ’0’ leads to DC braking and stop. Set braking current and duration in par. 2-01 *DC Brake Current* and par. 2-02 *DC Braking Time*. Bit 02 = ’1’ leads to ramping.

Bit 03, Coasting:

Bit 03 = ’0’: The frequency converter immediately "lets go" of the motor, (the output transistors are "shut off") and it coasts to a standstill. Bit 03 = ’1’: The frequency converter starts the motor if the other starting conditions are met.

NB!

Make a selection in par. 8-50 *Coasting Select* to define how Bit 03 gates with the corresponding function on a digital input.

Bit 04, Quick stop:

Bit 04 = ’0’: Makes the motor speed ramp down to stop (set in par. 3-81 *Quick Stop Ramp Time*.

Bit 05, Hold output frequency

Bit 05 = ’0’: The present output frequency (in Hz) freezes. Change the frozen output frequency only by means of the digital inputs (par. 5-10 *Terminal 18 Digital Input* to par. 5-15 *Terminal 33 Digital Input*) programmed to *Speed up* and *Slow down*.

NB!

If Freeze output is active, the frequency converter can only be stopped by the following:

- Bit 03 Coasting stop
- Bit 02 DC braking
- Digital input (par. 5-10 *Terminal 18 Digital Input* to par. 5-15 *Terminal 33 Digital Input*) programmed to *DC braking*, *Coasting stop*, or *Reset* and *coasting stop*.

Bit 06, Ramp stop/start:

Bit 06 = ’0’: Causes a stop and makes the motor speed ramp down to stop via the selected ramp down parameter. Bit 06 = ’1’: Permits the frequency converter to start the motor, if the other starting conditions are met.

NB!

Make a selection in par. 8-53 *Start Select* to define how Bit 06 Ramp stop/start gates with the corresponding function on a digital input.

Bit 07, Reset: Bit 07 = ’0’: No reset. Bit 07 = ’1’: Resets a trip. Reset is activated on the signal’s leading edge, i.e. when changing from logic ’0’ to logic ’1’.

Bit 08, Jog:

Bit 08 = ’1’: The output frequency is determined by par. 3-19 *Jog Speed [RPM]*.

Bit 09, Selection of ramp 1/2:

Bit 09 = "0": Ramp 1 is active (par. 3-41 *Ramp 1 Ramp Up Time* to par. 3-42 *Ramp 1 Ramp Down Time*). Bit 09 = "1": Ramp 2 (par. 3-51 *Ramp 2 Ramp Up Time* to par. 3-52 *Ramp 2 Ramp Down Time*) is active.

Bit 10, Data not valid/Data valid:

Tell the frequency converter whether to use or ignore the control word. Bit 10 = ’0’: The control word is ignored. Bit 10 = ’1’: The control word is used. This function is relevant because the telegram always contains the control word, regardless of the telegram type. Thus, you can turn off the control word if you do not want to use it when updating or reading parameters.

Bit 11, Relay 01:

Bit 11 = "0": Relay not activated. Bit 11 = "1": Relay 01 activated provided that *Control word bit 11* is chosen in par. 5-40 *Function Relay*.

Bit 12, Relay 04:

Bit 12 = "0": Relay 04 is not activated. Bit 12 = "1": Relay 04 is activated provided that *Control word bit 12* is chosen in par. 5-40 *Function Relay*.

Bit 13/14, Selection of set-up:

Use bits 13 and 14 to choose from the four menu set-ups according to the shown table: .

Set-up	Bit 14	Bit 13
1	0	0
2	0	1
3	1	0
4	1	1

The function is only possible when *Multi Set-Ups* is selected in par. 0-10 *Active Set-up*.

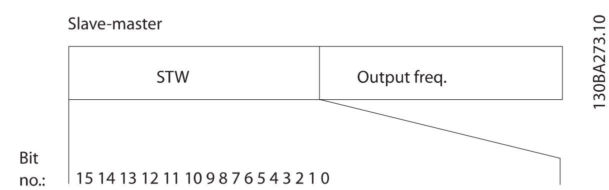
NB!

Make a selection in par. 8-55 *Set-up Select* to define how Bit 13/14 gates with the corresponding function on the digital inputs.

Bit 15 Reverse:

Bit 15 = ’0’: No reversing. Bit 15 = ’1’: Reversing. In the default setting, reversing is set to digital in par. 8-54 *Reversing Select*. Bit 15 causes reversing only when Ser. communication, Logic or or Logic and is selected.

7.11.2 Status Word According to FC Profile (STW) (par. 8-10 *Control Profile* = FC profile)



Bit	Bit = 0	Bit = 1
00	Control not ready	Control ready
01	Drive not ready	Drive ready
02	Coasting	Enable
03	No error	Trip
04	No error	Error (no trip)
05	Reserved	-
06	No error	Triplock
07	No warning	Warning
08	Speed ≠ reference	Speed = reference
09	Local operation	Bus control
10	Out of frequency limit	Frequency limit OK
11	No operation	In operation
12	Drive OK	Stopped, auto start
13	Voltage OK	Voltage exceeded
14	Torque OK	Torque exceeded
15	Timer OK	Timer exceeded

Explanation of the Status Bits

Bit 00, Control not ready/ready:

Bit 00 = ’0’: The frequency converter trips. Bit 00 = ’1’: The frequency converter controls are ready but the power component does not necessarily receive any power supply (in case of external 24 V supply to controls).

Bit 01, Drive ready:

Bit 01 = '1': The frequency converter is ready for operation but the coasting command is active via the digital inputs or via serial communication.

Bit 02, Coasting stop:
Bit 02 = '0': The frequency converter releases the motor. Bit 02 = '1': The frequency converter starts the motor with a start command.

Bit 03, No error/trip:
Bit 03 = '0' : The frequency converter is not in fault mode. Bit 03 = '1': The frequency converter trips. To re-establish operation, enter [Reset].

Bit 04, No error/error (no trip):
Bit 04 = '0': The frequency converter is not in fault mode. Bit 04 = "1": The frequency converter shows an error but does not trip.

Bit 05, Not used:
Bit 05 is not used in the status word.

Bit 06, No error / triplock:
Bit 06 = '0': The frequency converter is not in fault mode. Bit 06 = "1": The frequency converter is tripped and locked.

Bit 07, No warning/warning:
Bit 07 = '0': There are no warnings. Bit 07 = '1': A warning has occurred.

Bit 08, Speed≠ reference/speed = reference:
Bit 08 = '0': The motor is running but the present speed is different from the preset speed reference. It might e.g. be the case when the speed ramps up/down during start/stop. Bit 08 = '1': The motor speed matches the preset speed reference.

Bit 09, Local operation/bus control:
Bit 09 = '0': [STOP/RESET] is activate on the control unit or *Local control* in par. 3-13 *Reference Site* is selected. You cannot control the frequency converter via serial communication. Bit 09 = '1' It is possible to control the frequency converter via the fieldbus/ serial communication.

Bit 10, Out of frequency limit:
Bit 10 = '0': The output frequency has reached the value in par. 4-11 *Motor Speed Low Limit [RPM]* or par. 4-13 *Motor Speed High Limit [RPM]*. Bit 10 = "1": The output frequency is within the defined limits.

Bit 11, No operation/in operation:
Bit 11 = '0': The motor is not running. Bit 11 = '1': The frequency converter has a start signal or the output frequency is greater than 0 Hz.

Bit 12, Drive OK/stopped, autostart:
Bit 12 = '0': There is no temporary over temperature on the inverter. Bit 12 = '1': The inverter stops because of over temperature but the unit does not trip and will resume operation once the over temperature stops.

Bit 13, Voltage OK/limit exceeded:
Bit 13 = '0': There are no voltage warnings. Bit 13 = '1': The DC voltage in the frequency converter's intermediate circuit is too low or too high.

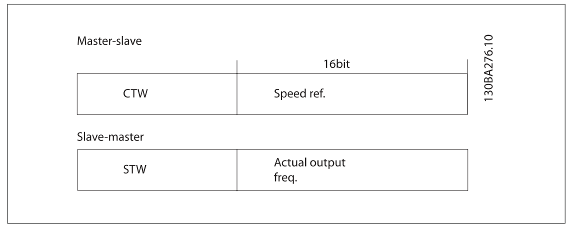
Bit 14, Torque OK/limit exceeded:
Bit 14 = '0': The motor current is lower than the torque limit selected in par. 4-18 *Current Limit*. Bit 14 = '1': The torque limit in par. 4-18 *Current Limit* is exceeded.

Bit 15, Timer OK/limit exceeded:
Bit 15 = '0': The timers for motor thermal protection and thermal protection are not exceeded 100%. Bit 15 = '1': One of the timers exceeds 100%.

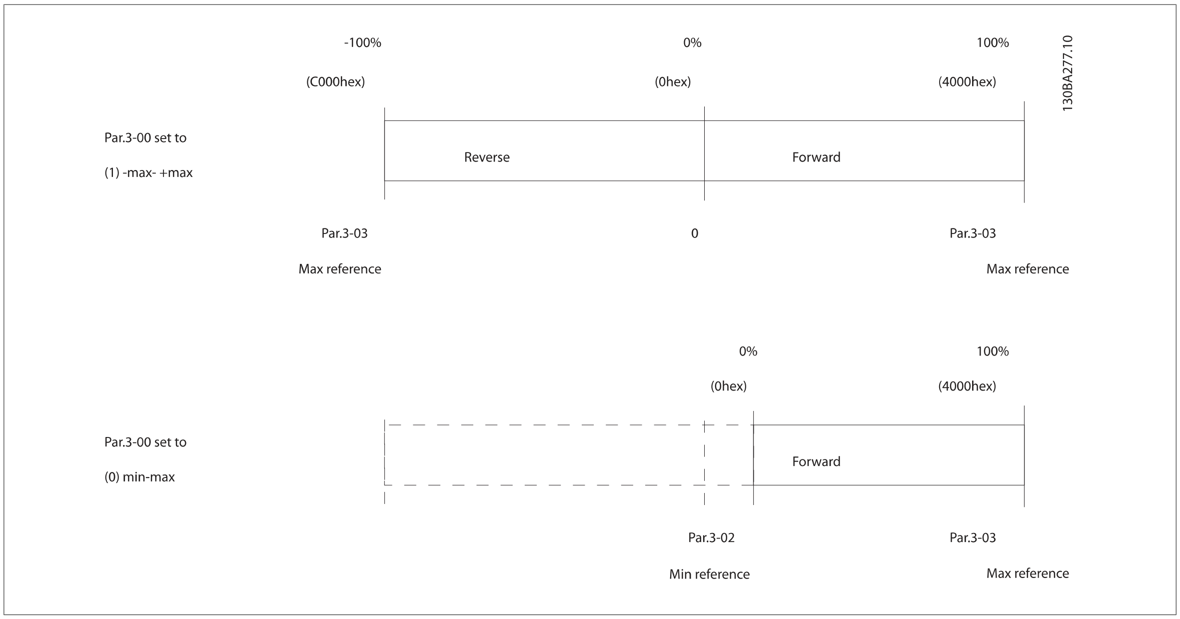
NB!
All bits in the STW are set to '0' if the connection between the Interbus option and the frequency converter is lost, or an internal communication problem has occurred.

7.11.3 Bus Speed Reference Value

Speed reference value is transmitted to the frequency converter in a relative value in %. The value is transmitted in the form of a 16-bit word; in integers (0-32767) the value 16384 (4000 Hex) corresponds to 100%. Negative figures are formatted by means of 2's complement. The Actual Output frequency (MAV) is scaled in the same way as the bus reference.



The reference and MAV are scaled as follows:



8

8 Troubleshooting

A warning or an alarm is signalled by the relevant LED on the front of the frequency converter and indicated by a code on the display.

A warning remains active until its cause is no longer present. Under certain circumstances operation of the motor may still be continued. Warning messages may be critical, but are not necessarily so.

In the event of an alarm, the frequency converter will have tripped. Alarms must be reset to restart operation once their cause has been rectified.

This may be done in four ways:

1. By using the [RESET] control button on the LCP control panel.
2. Via a digital input with the “Reset” function.
3. Via serial communication/optional fieldbus.
4. By resetting automatically using the [Auto Reset] function, which is a default setting for VLT Automation VT Drive Drive. see par. 14-20 *Reset Mode* in**VLT Automation VT Drive Programming Guide**

NB!
After a manual reset using the [RESET] button on the LCP, the [AUTO ON] or [HAND ON] button must be pressed to restart the motor.

If an alarm cannot be reset, the reason may be that its cause has not been rectified, or the alarm is trip-locked (see also table on following page).

Alarms that are trip-locked offer additional protection, means that the mains supply must be switched off before the alarm can be reset. After being switched back on, the frequency converter is no longer blocked and may be reset as described above once the cause has been rectified.

Alarms that are not trip-locked can also be reset using the automatic reset function in par. 14-20 *Reset Mode* (Warning: automatic wake-up is possible!)

If a warning and alarm is marked against a code in the table on the following page, this means that either a warning occurs before an alarm, or it can be specified whether it is a warning or an alarm that is to be displayed for a given fault.

This is possible, for instance, in par. 1-90 *Motor Thermal Protection*. After an alarm or trip, the motor carries on coasting, and the alarm and warning flash on the frequency converter. Once the problem has been rectified, only the alarm continues flashing.

8

No.	Description	Warning	Alarm/Trip	Alarm/Trip Lock	Parameter Reference
1	10 Volts low	X			
2	Live zero error	(X)	(X)		6-01
3	No motor	(X)			1-80
4	Mains phase loss	(X)	(X)	(X)	14-12
5	DC link voltage high	X			
6	DC link voltage low	X			
7	DC over voltage	X	X		
8	DC under voltage	X	X		
9	Inverter overloaded	X	X		
10	Motor ETR over temperature	(X)	(X)		1-90
11	Motor thermistor over temperature	(X)	(X)		1-90
12	Torque limit	X	X		
13	Over Current	X	X	X	
14	Earth fault	X	X	X	
15	Hardware mismatch		X	X	
16	Short Circuit		X	X	
17	Control word timeout	(X)	(X)		8-04
23	Internal Fan Fault	X			
24	External Fan Fault	X			14-53
25	Brake resistor short-circuited	X			
26	Brake resistor power limit	(X)	(X)		2-13
27	Brake chopper short-circuited	X	X		
28	Brake check	(X)	(X)		2-15
29	Drive over temperature	X	X	X	
30	Motor phase U missing	(X)	(X)	(X)	4-58
31	Motor phase V missing	(X)	(X)	(X)	4-58
32	Motor phase W missing	(X)	(X)	(X)	4-58
33	Inrush fault		X	X	
34	Fieldbus communication fault	X	X		
35	Out of frequency range	X	X		
36	Mains failure	X	X		
37	Phase Imbalance	X	X		
38	Internal fault		X	X	
39	Heatsink sensor		X	X	
40	Overload of Digital Output Terminal 27	(X)			5-00, 5-01
41	Overload of Digital Output Terminal 29	(X)			5-00, 5-02
42	Overload of Digital Output On X30/6	(X)			5-32
42	Overload of Digital Output On X30/7	(X)			5-33
46	Pwr. card supply		X	X	
47	24 V supply low	X	X	X	
48	1.8 V supply low		X	X	
49	Speed limit	X			
50	AMA calibration failed		X		
51	AMA check U_{nom} and I_{nom}		X		
52	AMA low I_{nom}		X		
53	AMA motor too big		X		
54	AMA motor too small		X		
55	AMA parameter out of range		X		
56	AMA interrupted by user		X		
57	AMA timeout		X		
58	AMA internal fault	X	X		
59	Current limit	X			

No.	Description	Warning	Alarm/Trip	Alarm/Trip Lock	Parameter Reference
60	External Interlock	X			
62	Output Frequency at Maximum Limit	X			
64	Voltage Limit	X			
65	Control Board Over-temperature	X	X	X	
66	Heat sink Temperature Low	X			
67	Option Configuration has Changed		X		
68	Safe Stop Activated		X1)		
69	Pwr. Card Temp		X	X	
70	Illegal FC configuration			X	
71	PTC 1 Safe Stop	X	X1)		
72	Dangerous Failure			X1)	
73	Safe Stop Auto Restart				
79	Illegal PS config		X	X	
80	Drive Initialised to Default Value		X		
91	Analog input 54 wrong settings			X	
92	NoFlow	X	X		22-2*
93	Dry Pump	X	X		22-2*
94	End of Curve	X	X		22-5*
95	Broken Belt	X	X		22-6*
96	Start Delayed	X			22-7*
97	Stop Delayed	X			22-7*
98	Clock Fault	X			0-7*
220	Overload Trip		X		
243	Brake IGBT	X	X		
244	Heatsink temp	X	X	X	
245	Heatsink sensor		X	X	
246	Pwr.card supply		X	X	
247	Pwr.card temp		X	X	
248	Illegal PS config		X	X	
250	New spare part			X	
251	New Type Code		X	X	

Table 8.1: Alarm/Warning code list

(X) Dependent on parameter

1) Can not be Auto reset via par. 14-20 *Reset Mode*

A trip is the action when an alarm has appeared. The trip will coast the motor and can be reset by pressing the reset button or make a reset by a digital input (Par. 5-1* [1]). The origin event that caused an alarm cannot damage the frequency converter or cause dangerous conditions. A trip lock is an action when an alarm occurs, which may cause damage to frequency converter or connected parts. A Trip Lock situation can only be reset by a power cycling.

LED indication	
Warning	yellow
Alarm	flashing red
Trip locked	yellow and red

8

Alarm Word and Extended Status Word

Bit	Hex	Dec	Alarm Word	Warning Word	Extended Status Word
0	00000001	1	Brake Check	Brake Check	Ramping
1	00000002	2	Pwr. Card Temp	Pwr. Card Temp	AMA Running
2	00000004	4	Earth Fault	Earth Fault	Start CW/CCW
3	00000008	8	Ctrl.Card Temp	Ctrl.Card Temp	Slow Down
4	00000010	16	Ctrl. Word TO	Ctrl. Word TO	Catch Up
5	00000020	32	Over Current	Over Current	Feedback High
6	00000040	64	Torque Limit	Torque Limit	Feedback Low
7	00000080	128	Motor Th Over	Motor Th Over	Output Current High
8	00000100	256	Motor ETR Over	Motor ETR Over	Output Current Low
9	00000200	512	Inverter Overld.	Inverter Overld.	Output Freq High
10	00000400	1024	DC under Volt	DC under Volt	Output Freq Low
11	00000800	2048	DC over Volt	DC over Volt	Brake Check OK
12	00001000	4096	Short Circuit	DC Voltage Low	Braking Max
13	00002000	8192	Inrush Fault	DC Voltage High	Braking
14	00004000	16384	Mains ph. Loss	Mains ph. Loss	Out of Speed Range
15	00008000	32768	AMA Not OK	No Motor	OVC Active
16	00010000	65536	Live Zero Error	Live Zero Error	
17	00020000	131072	Internal Fault	10V Low	
18	00040000	262144	Brake Overload	Brake Overload	
19	00080000	524288	U phase Loss	Brake Resistor	
20	00100000	1048576	V phase Loss	Brake IGBT	
21	00200000	2097152	W phase Loss	Speed Limit	
22	00400000	4194304	Fieldbus Fault	Fieldbus Fault	
23	00800000	8388608	24 V Supply Low	24V Supply Low	
24	01000000	16777216	Mains Failure	Mains Failure	
25	02000000	33554432	1.8V Supply Low	Current Limit	
26	04000000	67108864	Brake Resistor	Low Temp	
27	08000000	134217728	Brake IGBT	Voltage Limit	
28	10000000	268435456	Option Change	Unused	
29	20000000	536870912	Drive Initialised	Unused	
30	40000000	1073741824	Safe Stop	Unused	

Table 8.2: Description of Alarm Word, Warning Word and Extended Status Word

The alarm words, warning words and extended status words can be read out via serial bus or optional fieldbus for diagnosis. See also par. 16-90 *Alarm Word*, par. 16-92 *Warning Word* and par. 16-94 *Ext. Status Word*.

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