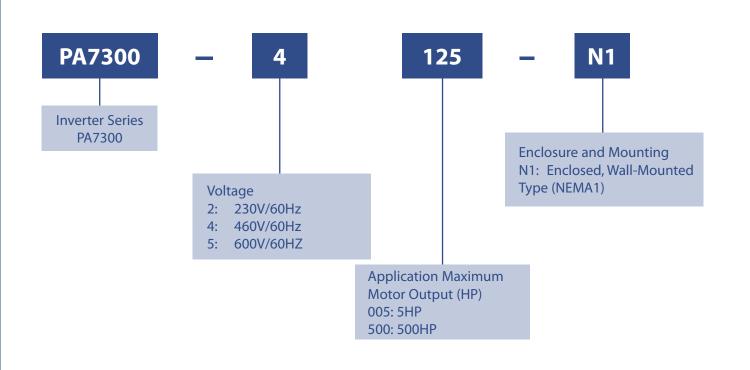


# **TECO Westinghouse**

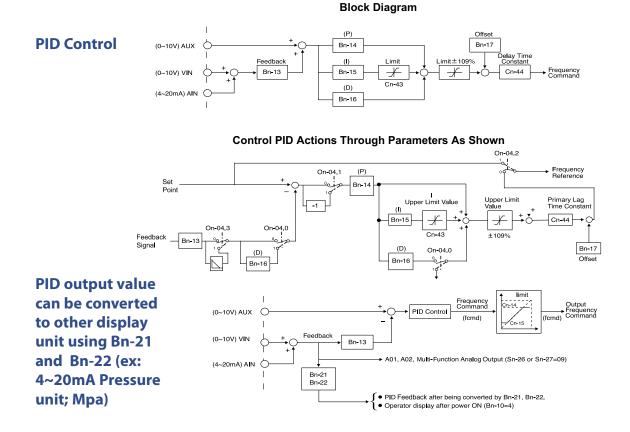


PID and Auto Energy Saving Functions.		
Input Phase Loss and Output Phase Loss Protection.		
LCD Keypad can be used to copy parameter settings	from one Inverter to another.	
Output Common Mode Choke Built-in on 230V 30HF	9 - 125HP and 460V 40HP - 300HF	<sup>o</sup> ratings.
Accessible parameters include PF, KW, KWHr, and Mo	tor Elapsed Run Hour.	
Multi-Function Input/Output Interface.		
RS-485 Communication Cards (option) –	Modbus/Metasys (pa-c) Profibus (pa-p)	Lonworks (PA-L)
1 - 8 PID Relay Card.		
PID Sleep/Wake Functions.		
3 Analog Inputs (0-10V x 2, 4-20mA)		
2 Analog Outputs (0-10V x 2, 4 - 20mA option)		
Motor Thermistor Input.		
Cooling Fan On/Off Control.		
Range:	208/230V 3ø 5 - 125HP	380/460V 3ø 5 - 500HP
UL, cUL,CE	500/600V 3ø 5 - 100HP	

### **Model Designation**

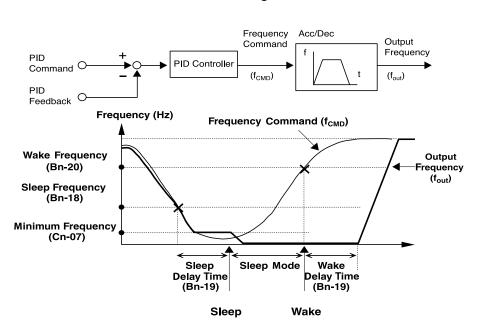


# **PID Function**



### **PID Sleep/Wake Functions**

Sleep demand mode makes it possible to stop the motor when it is running at a low speed with light load. If the system increases, the Inverter will restart the motor. Energy savings can be achieved with this function, since the motor operates only when the system needs it.



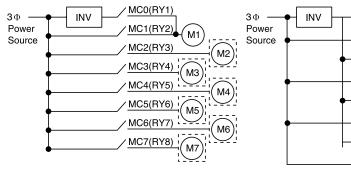
Block Diagram

### 1 - 8 PID Relay Card

The optional 1 - 8 PID Relay Card (PA-PID), with 8 relay contact outputs, can be used to control up to 7 pumps using the PID function in a constant pressure water supply system.

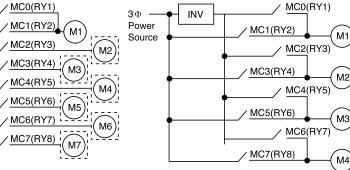
The relay constants are described below:

- Bn-23: Frequency Command **Upper-Bound Delay Time**
- Bn-24: Frequency Command Lower-Bound Delay Time
- Bn-25: MC ON/OFF Delay Time
- Bn-26: Pump ON/OFF Detection Level
- Sn-30: Pump Operation Mode Selection (See diagram below)
- Sn-31: PA-PID Card Relay2 Valid/Invalid
- Sn-32: PA-PID Card Relay3 Valid/Invalid
- Sn-33: PA-PID Card Relay4 Valid/Invalid
- Sn-34: PA-PID Card Relay5 Valid/Invalid
- Sn-35: PA-PID Card Relay6 Valid/Invalid
- Sn-36: PA-PID Card Relay7 Valid/Invalid
- Sn-37: PA-PID Card Relay8 Valid/Invalid

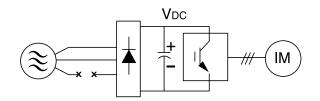




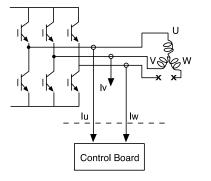
#### **Cycled Inverter Mode**



### **IPL-Input Phase Loss Protection**



### **OPL-Output Phase Loss Protection**



IPL function is disabled in the following cases:

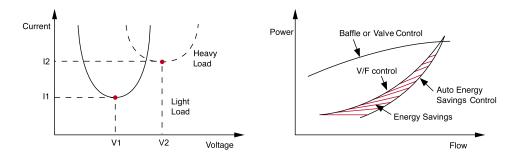
- While the inverter is stopped
- While decelerating
- While the output current <= 30% x the inverters rated current</li>
- When IPL Level  $\Delta$  V=100%
- When IPL protection function is disabled (Sn-13=xxx0)
- When "A/D Fault CPF05" is present

The OPL function is disabled in the following cases:

- While the inverter is stopped
- During DC injection braking of inverter •
- While the output current <= 30% x the inverters rated current</li>
- When OPL Protection Function is disabled (Sn-13=xx0x)
- When "A/D Fault CPF05" is present

The Inverter will automatically adjust voltage to minimize output current for different loads.

For fans, pumps, and HVAC applications, the auto energy saving mode will consume less power than for general V/F control.



## **Noise Filter**

When an input noise filter is installed as indicated, the Inverter will comply with the EN61800-3 (2000) noise interference suppression directive.

	Voltage(V) 460V														INPUT NOISE FILTER								
Inverter	HP	5	7.5	10	15	20	25	30	40	50	60	75	100	125	150	175	200	250	300	350	400	500	
	Rated Current (A)	8	12	16	24	32	38	44	59	75	86	111	151	189	231	267	304	340	380	516	585	732	S 2 5 - S/L2 V/T2
Input Noise Filter	Rated Current (A)	25	25	25	50	50	50	50	80	80	120	120	200	200	320	320	320	400	400	600	600	800	Input Noise Filter Connection

# **Digital Operator**



### LCD Keypad (standard)

- Uses Graphic LCD, Dual Language (Chinese and English)
- English LCD operator, can function as a parameter copy unit.

#### LED Keypad (option)

- Large size LED operator
- Same installation and dimension as the LCD operator.



# **Specifications**

#### 230V Class

INVERT	'ER (HP)	5	7.5	10	15	20	25	30	40	50	60	75	100	125
MAX. APPLIC Output I	ABLE MOTOR HP (KW)*•	5 (3.7)	7.5 (5)	10 (7.5)	15 (11)	20 (15)	25 (18.5)	30 (22)	40 (30)	50 (37)	60 (45)	75 (55)	100 (75)	125 (90)
	Inverter Capacity (KVA)	6.2	9.3	12.4	18.6	24.8	27.4	33	44	55	63	81	110	125
Quetrout	Rated Output Current (A)	16	24	32	48	64	72	88	117	144	167	212	288	327
Output Characteristics	Max. Output Voltage	3-Phase, 200/208/220/230V (Proportional to input voltage)												
	Rated Output Frequency	Up to 180Hz												
	Rated Input Voltage and Frequency	3-Phase, 200/208/220V, 50Hz 200/208/220/230V, 60Hz												
Power Supply	Allowable Voltage Fluctuation							+10	1%~-15%	6				
	Allowable Frequency Fluctuation								±5%					

### 460V Class

INVERT	ER (HP)	5	7.5	10	15	20	25	30	40	50	60	75	100	125	150	175	200	250	300	350	400	500
MAX. APPLIC Output F	5 (3.7)	<b>7.5</b> (5)	<b>10</b> (7.5)	<b>15</b> (11)	<b>20</b> (15)	<b>25</b> (18.5)	<b>30</b> (22)	<b>40</b> (30)	<b>50</b> (37)	<b>60</b> (45)		<b>100</b> (75)						<b>300</b> (220)				
	Inverter Capacity (KVA)	6.2	9.3	12.4	18.6	24.8	29	34	45	57	66	85	115	144	176	203	232	259	290	393	446	558
Output	Rated Output Current (A)	8	12	16	24	32	38	44	59	75	86	111	151	189	231	267	304	340	380	516	585	732
Characteristics	Max. Output Voltage	3-Phase, 380/400/415/440/460V (Proportional to input voltage)																				
	Rated Output Frequency	Up to 180Hz																				
	Rated Input Voltage and Frequency	3-Phase, 380/400/415/440/460V, 50/60Hz																				
Power Supply	Allowable Voltage Fluctuation									+	10%~	15%	Ó									
	Allowable Frequency Fluctuation										±59	%										

\*1 Based on a 4 pole motor

	Control Method	Sine Wave PWM									
	Frequency Control Range	0.1 to 180Hz									
S	Frequency Accuracy	Digital Command: $0.01\%$ $+14 \text{ to } 104\degree F$ -10 to $40\degree C$ Analog Command: $0.1\%$ $77 \pm 18\degree F$ $25 \pm 10\degree C$									
Control Characteristics	Frequency Setting Resolution	Digital Operator Reference: 0.01Hz Analog Reference: 0.06Hz/60Hz									
acte	Output Frequency Resolution	0.01Hz (1/30000)									
Chai	Overload Capacity	110% Rated Output Current for One Minute									
itrol	Frequency Setting Signal	0 to 10VDC (20K Ω), 4-20mA (250 Ω)									
Con	Accel/Decel Time	0.1 to 6000 sec (Independent Accel/Decel Time Settings)									
	Braking Torque	Approximately 20%									
	No. of V/F Patterns (Total of 5)	1: Custom Pattern, 4: For Fans and Pumps									
	Motor Overload Protection	Electric Thermal Overload Relay									
	Instantaneous Overcurrent	Motor Coasts to Stop at Approximately 200% of Rated Current									
	Overload	Motor Coasts to Stop after 1 minute at 110% Rated Output Current									
	Overvoltage (230V)	Motor Coasts to Stop if Inverter Output Voltage exceeds 410VDC									
	Overvoltage (460V)	Motor Coasts to Stop if the Inverter Output Voltage exceeds 820VDC									
ons	Undervoltage (230V)	Motor Coasts to Stop if Inverter Output Voltage drops to 190VDC or below									
Incti	Undervoltage (460V)	Motor Coasts to Stop if Inverter Output Voltage drops to 380VDC or below									
Protective Functions	Momentary Power Loss	Motor Coasts to Stop after Momentary Power Loss lasting over 15ms (time-setting made prior to shipment)									
rote	Motor Overheat Protection	Motor PTC Thermistor (Active: 1330 Ω, Return: 550 Ω)									
<b>d</b>	Input Phase Loss	Single Phase Protection									
	Output Phase Loss	Provided by Electronic Circuit									
	Fin Overheat	Thermostat									
	Stall Prevention	Stall Prevention at Acceleration/Deceleration and Constant Speed Operation									
	Ground Fault	Provided by Electronic Circuit									
	Power Charge Indication	Charge Lamp stays ON until Bus Voltage drops below 50V									
	Location	Indoor (protected from corrosive gases and dust)									
Environmental Conditions	Ambient Temperature	Wall-mounted type: $+14$ to $104^{\circ}$ F (-10 to $+40^{\circ}$ C) not frozen Open chassis type: $+14$ to $113^{\circ}$ F (-10 to $+45^{\circ}$ C) not frozen									
ironr	Storage Temperature	-4 to 140°F (-20 to +60°C)									
Envi	Humidity	95% RH (non-condensing)									
	Vibration	1G at 10 to 20Hz, up to 0.2G at 20 to 50Hz									
Communicati	ion Function	RS-485 Communication Card Options - MODBUS/METASYS, PROFIBUS, LONWORKS									
Noise Interfe	rence Suppression	EN61800-3 (2000) with specified noise filter									
Noise Immun	ity	EN61800-3 (2000)									

# Main Circuit Terminals

TERMINALS	TERMINAL FUNCTION
R / L1	
S / L2	Main Circuit Input Power Supply
T/L3	
U / T1	
V / T2	Inverter Output
W / T3	
$\oplus$	DC Douver Supply Input or Dealing Unit
$\ominus$	DC Power Supply Input or Braking Unit
B2	B2 ⊕ ⊖: External Braking Resistor (only for 230V 25HP, 460V 25HP and 30HP ratings)
E( PE, ╧ )	Grounding (3rd Type Grounding)

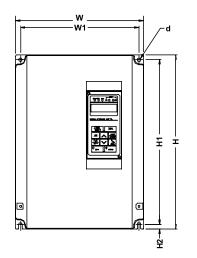
# **Control Circuit Terminals**

I/0	TERMINAL	FUNCTION													
	1	Forward operation – stop signal													
	2	Reverse operation - stop signal													
	3	External fault input													
	4	Fault reset													
Digital	5	Multi-function contact input. The following signals are available for selection: forward / re	everse select,												
Input	6	run mode select, multi-speed select, jog frequency select, accel/decel time select, externa	l												
Terminals	7	fault, external coast to stop, hold command, inverter overheat protection, DB command, a	aux.												
	8	input effective, speed search, energy-savings operation													
	24VG	SINK Common (OV)													
	24V	SOURCE Common (24V)													
	SC	Sequence Input Common (24V)													
	+15V	+15V power supply for external frequency command													
	VIN	Master speed voltage reference (0 to 10V)													
Analog	AIN	Master speed current reference (4 to 20mA)													
Input Terminals	AUX	Auxiliary analog command. One of the following signals are available for selection: Frequency command, frequency gain, frequency bias, overtorque detection level, voltage	bias, accel/decel rate, DB current												
Ierminais	MT	Motor temperature PTC thermistor. (Active: 1330Ω, Return: 550Ω)													
	GND	Analog signal common													
	E	Connection to shield signal lead (frame ground)	Connection to shield signal lead (frame ground)												
	R3A	Fault contact output A (closed at fault)													
	R3B	Fault contact output B (open at fault)													
	R3C	Fault contact output common													
Digital	R2A-R2C	Multi-function contact output. One of the following signals are available for output:													
Output Terminals	R1A-R1C	output during running, zero speed, synchronized speed, arbitrary speed, agreed frequency detection, overtorque, undervoltage, run mode, coast to stop, braking resistor o	overheat, alarm, fault												
	D01	Multi-function PHC (photo-coupler) output 1 (open collector, 48VDC, 50mA)	The same functions as terminals R1A-R1C and R2A-R2C												
	DCOM	Multi-function PHC output common													
Analog	A01	Analog multi-function output port: Frequency command, output	0 111/												
Output	A02	frequency, output current, output voltage, DC voltage, output power	0~11V max. 2mA or less												
Terminals	GND	Common lead for analog port													

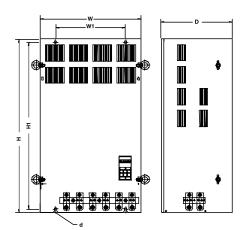
# Dimensions

VOLTAGE	INVERTER	OP	EN CHA	SSIS TY	'PE (IPO	0) inch	es	WEIGHT	ENCLOSED TYPE (NEMA 1) inches						WEIGHT		REFERENCE
(V)	CAPACITY (HP)	W	H	D	W1	H1	d	(LB)	W	H	D	W1	H1	d	(LB)	ACL/DCL	FIGURE
	5							13							13	External ACL	
	7.5	8.32	11.81	8.46	7.56	11.26	M6	13	8.32	11.81	8.46	7.56	11.26	M6	13	External ACL (option)	(a)
	10							13							13	(option)	
	15							27				9.65			27	External ACL	
	20	10.43	14.17	8.86	9.65	13.39	M6	27	10.43	14.17	8.86		13.39	M6	27	(option)	(a)
	25							27							27	(option)	
230V	30							80							84	DCL Built-in	
	40	11.16	20.67	12.09	8.66	19.88	M8	80	11.48	29.33	12.09	8.66	19.88	M8	84	(standard)	
	50							80							84	(Stanuaru)	(1.)
	60	13.54	24.80	12.78	9.84	24.02	M8	104	13.86	37.20	12.78	9.84	24.02	M8	111	DCL Built-in	(b)
	75							109							115		
	100	18.07	31.10	12.78	12.60	29.92	M10	181	18.19	43.50	12.78	12.60	29.92	M10	192	(standard)	
	125 5							181 13							192 13		
	7.5	8.32	11.81	8.46	7.56	11.26	M6	13	8.32	11.81	8.46	7.56	11.26	M6	13	External ACL	(a)
	10	0.52	11.01	0.40	7.50		IVIO	13			0.40	7.50		IVIO	13	(option)	(d)
	10							27							27		
	20					13.39		27							27	External ACL	
	25	10.43	14.17	8.86	9.65		M6	27	10.43	14.17	8.86	9.65	13.39	M6	27	(option)	(a)
	30							27							27	(option)	
	40							80							84	DCL Built-in	
	50	11.16	20.67	12.09	8.66	19.88	M8	80	11.48	29.33	12.09	8.66	19.88	M8	84	(standard)	
	60							104							111		
	75	13.54	24.80	12.78	9.84	24.02	M8	104	13.86	37.20	12.78	9.84	24.02	M8	111	DCL Built-in	
	100							104							111	(standard)	(b)
460V	125							177							188		
	150	18.07	31.10	12.78	12.60	29.92	M10	177	18.19	43.50	12.78	12.60	29.92	M10	188	DCL Built-in (standard)	
	175							179							190	(Stallualu)	
	200							283							298	DCL Built-in	
	250	23.58	39.37	15.02	18.11	37.80	M12	283	23.70	51.38	15.02	18.11	37.80	M12	298	(standard)	
	300							291							307	(Junuard)	
	350							353							366	External ACL	
	400	28.74	48.43	15.04	27.17	36.61	M12	375	28.74	52.36	15.04	27.17	36.61	M12	390	(option)	(c)
	500							419							435	(option)	

### (a) 230V: 5HP - 25HP 460V: 5HP - 30HP

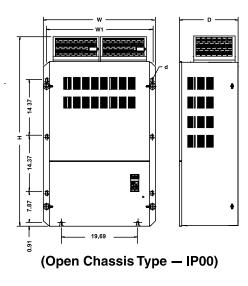


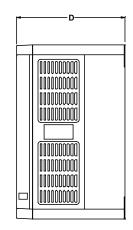
### (b) 230V: 30HP – 125HP 460V: 40HP – 300HP

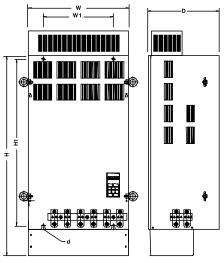


(Open Chassis Type – IP00)

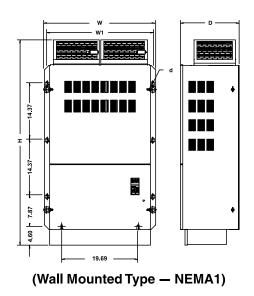
#### (c) 460V: 350HP - 500HP



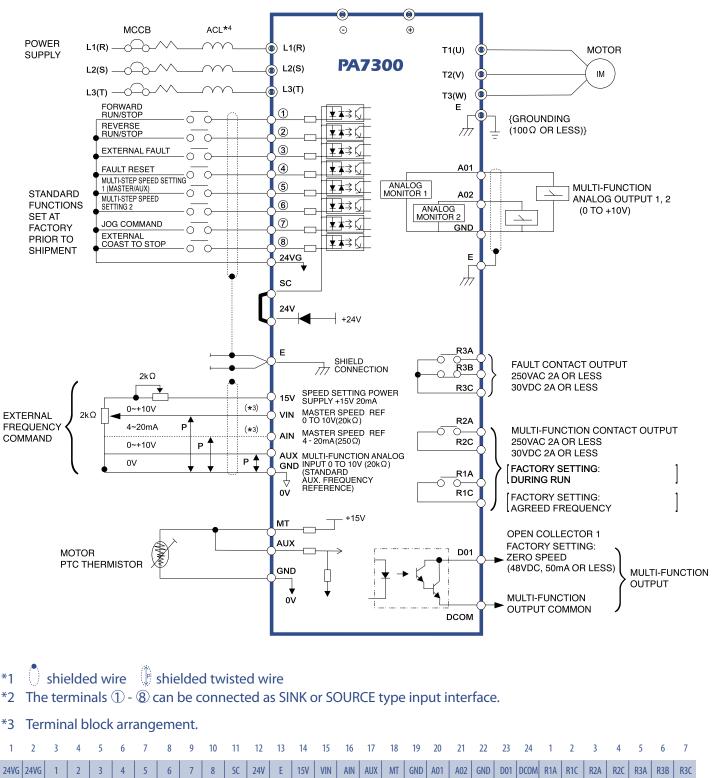




(Wall Mounted Type — NEMA1)



### **Connection Diagram**



DC Power Supply (Braking Input)

\*4 External ACL is used for 350HP - 500HP models (DCL built-in for 40HP - 300HP).

Shorted at factory

# TECO Westinghouse